

Thermo-mechanical coupling in fiber-reinforced continua: Mixed finite element formulations and energy-momentum time integration

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Motivation

- ▶ Dynamic simulations of fiber-reinforced materials in lightweight structures
- ▶ Keywords:
 - ▶ Anisotropic material behavior
 - ▶ Nearly-incompressible material behavior
 - ▶ Thermo-mechanical material behavior [Thermal expansion and heat conduction]
- ▶ Solution strategy:
 1. Mixed finite elements to reduce locking effects
 2. Extension to a thermo-mechanical coupling
 3. Higher-order energy-momentum conserving time integrator for stable and accurate dynamic simulations [eg(k)]

Continuum mechanics and material formulation

- Strain energy function (matrix part Ψ_M and n_F fiber parts Ψ_{F_i})

$$\Psi(C, \Theta) = \Psi_M(C, \Theta) + \sum_{i=1}^{n_F} \Psi_{F_i}(C, \Theta, M_i) \quad M_i = (a_i^0)^T \otimes a_i^0$$

C - Right Cauchy-Green tensor, Θ - Absolute temperature, a_i^0 - Fiber direction

- Components and specific dependencies ($J(C) = \sqrt{\det[C]}$)

$$\Psi_M(C, \Theta) = \Psi_M^{\text{iso}}(C, \text{cof}[C], J) + \Psi_M^{\text{vol}}(J) + \Psi_M^{\text{cap}}(\Theta) + \Psi_M^{\text{coup}}(\Theta, J)$$

$$\Psi_{F_i}(C, \Theta, M_i) = \Psi_{F_i}^{\text{ela}}(C, \text{cof}[C], J, M_i) + \Psi_{F_i}^{\text{cap}}(\Theta) + \Psi_{F_i}^{\text{coup}}(\Theta, C, M_i)$$

- Polyconvex material formulation for the hyperelastic parts

$$\Psi_M^{\text{iso}}(C, \text{cof}[C], J) = \Psi_M^{\text{iso}}(C) + \Psi_M^{\text{iso}}(\text{cof}[C]) + \Psi_M^{\text{iso}}(J)$$

$$\Psi_{F_i}^{\text{ela}}(C, \text{cof}[C], J, M_i) = \Psi_{F_i}^{\text{ela}}(C, M_i) + \Psi_{F_i}^{\text{ela}}(\text{cof}[C], M_i) + \Psi_{F_i}^{\text{ela}}(J)$$

- Thermo-mechanical coupling [Groß 18]

$$\Psi_M^{\text{coup}} = -2n_{\text{dim}}\beta_M(\Theta - \Theta_\infty)J \frac{\partial \Psi_M^{\text{vol}}(J)}{\partial J} \quad \Psi_{F_i}^{\text{coup}} = -2\beta_{F_i}(\Theta - \Theta_\infty)\sqrt{I_4^i} \frac{\partial \Psi_{F_i}^{\text{ela}}(I_4^i \dots)}{\partial I_4^i}$$

Θ_∞ - Ambient temperature, $I_4^i = \text{tr}[CM_i]$

Total internal energy Π^{int}

- ▶ Total internal energy for the mixed principle of virtual power [Groß 18]

$$\Pi^{\text{int}} = \Pi_{\text{HW}} + \int_{\mathcal{B}_0} \frac{1}{2} \mathbf{S} : (\mathbf{C} - \tilde{\mathbf{C}}) dV + \int_{\mathcal{B}_0} \tilde{\mathbf{S}} : \tilde{\mathbf{C}} dV + \int_{\mathcal{B}_0} \eta (\Theta - \tilde{\Theta}) dV$$

- ▶ Mixed elements based on Hu-Washizu functionals Π_{HW}
- ▶ Independent mixed field $\tilde{\mathbf{C}}$ and corresponding Lagrangian multiplier \mathbf{S}
- ▶ Superimposed stress tensor $\tilde{\mathbf{S}}$ to derive energy–momentum scheme [Groß 18]
- ▶ Assumed temperature field $\tilde{\Theta}$ and the entropy density field η
- ▶ Displacement element $\Pi_{\text{HW}} = \int_{\mathcal{B}_0} \Psi(\tilde{\mathbf{C}}, \Theta) dV$

Displacement-Pressure Element [Simo 85]

$$\Pi_{\text{HW}}^{\text{DP}} = \Pi_{\text{HW}}^{\text{DP}} + \int_{\mathcal{B}_0} p (J(\tilde{\mathbf{C}}) - \tilde{J}) dV + \int_{\mathcal{B}_0} \tilde{p} \tilde{J} dV$$

$$\Psi_{\text{M}}(\dots) = \Psi_{\text{M}}^{\text{iso}}(\tilde{\mathbf{C}}, \text{cof}[\tilde{\mathbf{C}}], \tilde{J}) + \Psi_{\text{M}}^{\text{vol}}(\tilde{J}) + \Psi_{\text{M}}^{\text{cap}}(\Theta) + \Psi_{\text{M}}^{\text{coup}}(\Theta, \tilde{J})$$

$$\Psi_{\text{F}_i}(\dots) = \Psi_{\text{F}_i}^{\text{ela}}(\tilde{\mathbf{C}}, \text{cof}[\tilde{\mathbf{C}}], \tilde{J}, \mathbf{M}_i) + \Psi_{\text{F}_i}^{\text{cap}}(\Theta) + \Psi_{\text{F}_i}^{\text{coup}}(\Theta, \tilde{\mathbf{C}}, \mathbf{M}_i)$$

CoFEM Element [Schr 11]

$$\Pi_{\text{HW}}^{\text{CoFEM}} = \Pi_{\text{HW}}^{\text{DP}} + \int_{\mathcal{B}_0} \mathbf{B} : (\text{cof}[\tilde{\mathbf{C}}] - \tilde{\mathbf{H}}) dV + \int_{\mathcal{B}_0} \tilde{\mathbf{B}} : \tilde{\mathbf{H}} dV$$

$$\Psi_{\text{M}}(\dots) = \Psi_{\text{M}}^{\text{iso}}(\tilde{\mathbf{C}}, \tilde{\mathbf{H}}, \tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{vol}}(\tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{cap}}(\Theta) + \Psi_{\text{M}}^{\text{coup}}(\Theta, \tilde{\mathbf{J}})$$

$$\Psi_{\text{F}_i}(\dots) = \Psi_{\text{F}_i}^{\text{ela}}(\tilde{\mathbf{C}}, \tilde{\mathbf{H}}, \tilde{\mathbf{J}}, \mathbf{M}_i) + \Psi_{\text{F}_i}^{\text{cap}}(\Theta) + \Psi_{\text{F}_i}^{\text{coup}}(\Theta, \tilde{\mathbf{C}}, \mathbf{M}_i)$$

SKA Element [Schr 16]

$$\Pi_{\text{HW}}^{\text{CoSKA}} = \Pi_{\text{HW}}^{\text{CoFEM}} + \int_{\mathcal{B}_0} \frac{1}{2} \mathbf{S}_A : (\tilde{\mathbf{C}} - \tilde{\mathbf{C}}_A) dV + \int_{\mathcal{B}_0} \tilde{\mathbf{S}}_A : \tilde{\mathbf{C}}_A dV$$

$$\Psi_{\text{M}}(\dots) = \Psi_{\text{M}}^{\text{iso}}(\tilde{\mathbf{C}}, \tilde{\mathbf{H}}, \tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{vol}}(\tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{cap}}(\Theta) + \Psi_{\text{M}}^{\text{coup}}(\Theta, \tilde{\mathbf{J}})$$

$$\Psi_{\text{F}_i}(\dots) = \Psi_{\text{F}_i}^{\text{ela}}(\tilde{\mathbf{C}}_A, \text{cof}[\tilde{\mathbf{C}}_A], \sqrt{\det[\tilde{\mathbf{C}}_A]}, \mathbf{M}_i) + \Psi_{\text{F}_i}^{\text{cap}}(\Theta) + \Psi_{\text{F}_i}^{\text{coup}}(\Theta, \tilde{\mathbf{C}}_A, \mathbf{M}_i)$$

CoCoA Element

$$\Pi_{\text{HW}}^{\text{CoCoA}} = \Pi_{\text{HW}}^{\text{CoSKA}} + \int_{\mathcal{B}_0} \mathbf{B}_A : (\text{cof}[\tilde{\mathbf{C}}] - \tilde{\mathbf{H}}_A) dV + \int_{\mathcal{B}_0} \tilde{\mathbf{B}}_A : \tilde{\mathbf{H}}_A dV + \int_{\mathcal{B}_0} p_A (J(\tilde{\mathbf{C}}) - \tilde{\mathbf{J}}_A) dV$$

$$\Psi_{\text{M}}(\dots) = \Psi_{\text{M}}^{\text{iso}}(\tilde{\mathbf{C}}, \tilde{\mathbf{H}}, \tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{vol}}(\tilde{\mathbf{J}}) + \Psi_{\text{M}}^{\text{cap}}(\Theta) + \Psi_{\text{M}}^{\text{coup}}(\Theta, \tilde{\mathbf{J}}) + \int_{\mathcal{B}_0} \tilde{p}_A \tilde{\mathbf{J}}_A dV$$

$$\Psi_{\text{F}_i}(\dots) = \Psi_{\text{F}_i}^{\text{ela}}(\tilde{\mathbf{C}}_A, \tilde{\mathbf{H}}_A, \tilde{\mathbf{J}}_A, \mathbf{M}_i) + \Psi_{\text{F}_i}^{\text{cap}}(\Theta) + \Psi_{\text{F}_i}^{\text{coup}}(\Theta, \tilde{\mathbf{C}}_A, \mathbf{M}_i)$$

Superimposed fields for CoCoA Element

- Superimposed stress tensor $\tilde{\mathbf{S}}$ with $\tilde{\Psi} = \Psi_M^{\text{iso}}(\tilde{\mathbf{C}}) + \Psi_M^{\text{cap}}(\Theta) + \sum_{i=1}^{n_F} [\Psi_{F_i}^{\text{cap}}(\Theta)]$

$$\tilde{\mathbf{S}} = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{C}}} : \dot{\tilde{\mathbf{C}}} - \int \frac{\partial \tilde{\Psi}}{\partial \Theta} \dot{\Theta}}{\dot{\tilde{\mathbf{C}}} : \dot{\tilde{\mathbf{C}}}} \dot{\tilde{\mathbf{C}}}$$

- Superimposed pressure \tilde{p} with $\tilde{\Psi} = \Psi_M^{\text{iso}}(\tilde{\mathbf{J}}) + \Psi_M^{\text{vol}}(\tilde{\mathbf{J}}) + \Psi_M^{\text{coup}}(\Theta, \tilde{\mathbf{J}})$

$$\tilde{p} = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{J}}} \dot{\tilde{\mathbf{J}}} - \int \frac{\partial \tilde{\Psi}}{\partial \Theta} \dot{\Theta}}{\dot{\tilde{\mathbf{J}}} \dot{\tilde{\mathbf{J}}}} \dot{\tilde{\mathbf{J}}}$$

- Superimposed stress tensor $\tilde{\mathbf{S}}_A$ with $\tilde{\Psi} = \sum_{i=1}^{n_F} [\Psi_{F_i}^{\text{ela}}(\tilde{\mathbf{C}}_A, M_i) + \Psi_{F_i}^{\text{coup}}(\Theta, \tilde{\mathbf{C}}_A, M_i)]$

$$\tilde{\mathbf{S}}_A = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{C}}_A} : \dot{\tilde{\mathbf{C}}}_A - \int \frac{\partial \tilde{\Psi}}{\partial \Theta} \dot{\Theta}}{\dot{\tilde{\mathbf{C}}}_A : \dot{\tilde{\mathbf{C}}}_A} \dot{\tilde{\mathbf{C}}}_A$$

- Superimposed conjugated stress t. $\tilde{\mathbf{B}}$ with $\tilde{\Psi} = \Psi_M^{\text{iso}}(\tilde{\mathbf{H}})$ and $\tilde{\mathbf{B}}_A$ with $\tilde{\Psi} = \sum_{i=1}^{n_F} \Psi_{F_i}^{\text{ela}}(\tilde{\mathbf{H}}_A, M_i)$

$$\tilde{\mathbf{B}} = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{H}}} : \dot{\tilde{\mathbf{H}}}}{\dot{\tilde{\mathbf{H}}} : \dot{\tilde{\mathbf{H}}}} \dot{\tilde{\mathbf{H}}} \quad \tilde{\mathbf{B}}_A = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{H}}_A} : \dot{\tilde{\mathbf{H}}}_A}{\dot{\tilde{\mathbf{H}}}_A : \dot{\tilde{\mathbf{H}}}_A} \dot{\tilde{\mathbf{H}}}_A$$

- Superimposed pressure \tilde{p}_A with $\tilde{\Psi} = \sum_{i=1}^{n_F} [\Psi_{F_i}^{\text{ela}}(\tilde{\mathbf{J}}_A)]$

$$\tilde{S} = \frac{\tilde{\Psi}(1) - \tilde{\Psi}(0) - \int \frac{\partial \tilde{\Psi}}{\partial \tilde{\mathbf{J}}_A} \dot{\tilde{\mathbf{J}}}_A}{\dot{\tilde{\mathbf{J}}}_A \dot{\tilde{\mathbf{J}}}_A} \dot{\tilde{\mathbf{J}}}_A$$

Mixed principle of virtual power of CoCoA Element

- ▶ Total energy balance law in functional form $\dot{\mathcal{H}} = \dot{T} + \dot{\Pi}^{\text{ext}} + \dot{\Pi}^{\text{int}}$

$$\dot{\mathcal{H}}(\dot{\mathbf{q}}, \boldsymbol{\lambda}, \dot{\mathbf{v}}, \dot{\mathbf{p}}, \tilde{\boldsymbol{\Theta}}, \dot{\boldsymbol{\Theta}}, \dot{\boldsymbol{\eta}}, \dot{\tilde{\mathbf{C}}}, \dot{\tilde{\mathbf{C}}}_A, \dot{\tilde{\mathbf{H}}}, \dot{\tilde{\mathbf{H}}}_A, \dot{\tilde{\mathbf{J}}}, \dot{\tilde{\mathbf{J}}}_A, \mathbf{S}, \mathbf{S}_A, \mathbf{B}, \mathbf{B}_A, p, p_A) = 0$$

- ▶ Kinetic power functional

$$\dot{T}(\dot{\mathbf{q}}, \dot{\mathbf{v}}, \dot{\mathbf{p}}) = \int_{\mathcal{B}_0} (\rho_0 \mathbf{v} - \mathbf{p}) \cdot \dot{\mathbf{v}} dV + \int_{\mathcal{B}_0} \dot{\mathbf{p}} \cdot (\dot{\mathbf{q}} - \mathbf{v}) dV + \int_{\mathcal{B}_0} \mathbf{p} \cdot \ddot{\mathbf{q}} dV$$

- ▶ External power functional

$$\dot{\Pi}^{\text{ext}}(\dot{\mathbf{q}}, \boldsymbol{\lambda}, \tilde{\boldsymbol{\Theta}}) = - \int_{\partial \mathcal{B}_0} \mathbf{t} \cdot \dot{\mathbf{q}} dA - \int_{\partial \mathcal{B}_0} \boldsymbol{\lambda} \cdot (\dot{\mathbf{q}} - \dot{\mathbf{q}}^{\text{ref}}) dA + \int_{\mathcal{B}_0} \nabla \left(\frac{\tilde{\boldsymbol{\Theta}}}{\boldsymbol{\Theta}} \right) \cdot \mathbf{Q} dV.$$

- ▶ Piola heat flux vector ($\mathbf{J} = J(\tilde{\mathbf{C}})$)

$$\mathbf{Q} = - \left[\sum_{i=1}^{n_F} J \frac{k_{F_i} - k_M}{\tilde{\mathbf{C}}_A : \mathbf{M}_i} \mathbf{M}_i + k_J \tilde{\mathbf{C}}^{-1} \right] \nabla \boldsymbol{\Theta}$$

- ▶ Variation with respect to the variables in the arguments of the total energy balance

$$\int_T [\delta_* \dot{T} + \delta_* \dot{\Pi}^{\text{ext}} + \delta_* \dot{\Pi}^{\text{int}}] dt = 0$$

Weak formulation of CoCoA Element

$$\begin{aligned}
 & \int_T \int_{\mathcal{B}_0} [\text{Div}[\mathbf{F}\mathbf{S}] - \dot{\mathbf{p}}] \cdot \delta \dot{\mathbf{q}} dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\frac{1}{\rho_0} \mathbf{p} - \dot{\mathbf{q}} \right] \cdot \delta \dot{\mathbf{v}} dV dt = 0 \quad \int_T \int_{\partial \mathcal{B}_0} [-\mathbf{t} - \boldsymbol{\lambda}] \cdot \delta \dot{\mathbf{q}} dA dt = 0 \\
 & \int_T \int_{\partial \mathcal{B}_0} \left[\dot{\hat{\mathbf{q}}} - \dot{\mathbf{q}}^{\text{ref}}(t) \right] \cdot \delta \boldsymbol{\lambda} dA dt = 0 \quad \int_T \int_{\mathcal{B}_0} [\Theta - \tilde{\Theta}] \delta \dot{\eta} dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\eta + \frac{\partial \Psi}{\partial \Theta} \right] \delta \dot{\Theta} dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} \left[\frac{\text{Div}[\mathbf{Q}]}{\Theta} + \dot{\eta} \right] \delta \tilde{\Theta} dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \frac{1}{2} [\dot{\mathbf{C}} - \dot{\mathbf{C}}] : \delta \mathbf{S} dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} \left[\frac{1}{2} \mathbf{S} - \left(\frac{\partial \Psi}{\partial \tilde{\mathbf{C}}} + \tilde{\mathbf{S}} + \mathbf{B} : \mathbb{P} + \frac{p}{2J} \text{cof}[\mathbf{C}] + \frac{1}{2} \mathbf{S}_A + \mathbf{B}_A : \mathbb{P} + \frac{p_A}{2J} \text{cof}[\mathbf{C}] \right) \right] : \delta \tilde{\mathbf{C}} dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} \frac{1}{2} [\dot{\mathbf{C}}_A - \dot{\mathbf{C}}] : \delta \mathbf{S}_A dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\frac{1}{2} \mathbf{S}_A - \left[\frac{\partial \Psi}{\partial \tilde{\mathbf{C}}_A} + \tilde{\mathbf{S}}_A \right] \right] : \delta \dot{\mathbf{C}}_A dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} [\dot{j} - j] \delta p dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[p - \left[\frac{\partial \Psi}{\partial \bar{j}} + \bar{p} \right] \right] \delta \dot{j} dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} [\dot{\mathbf{H}} - \text{cof}[\mathbf{C}]] : \delta \mathbf{B} dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\mathbf{B} - \left[\frac{\partial \Psi}{\partial \bar{\mathbf{H}}} + \bar{\mathbf{B}} \right] \right] : \delta \dot{\mathbf{H}} dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} [\dot{j}_A - j] \delta p_A dV dt = 0 = 0 \quad \int_T \int_{\mathcal{B}_0} \left[p_A - \left[\frac{\partial \Psi}{\partial \bar{j}_A} + \bar{p}_A \right] \right] \delta \dot{j}_A dV dt = 0 \\
 & \int_T \int_{\mathcal{B}_0} [\dot{\mathbf{H}}_A - \text{cof}[\mathbf{C}]] : \delta \mathbf{B}_A dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\mathbf{B}_A - \left[\frac{\partial \Psi}{\partial \bar{\mathbf{H}}_A} + \bar{\mathbf{B}}_A \right] \right] : \delta \dot{\mathbf{H}}_A dV dt = 0
 \end{aligned}$$

Approximation

k = Polynomial degree in time

- ▶ Discretization in space and time
- ▶ Lagrangian shape functions in space (N) [Wrig 08] [Bart 18]
 - ▶ Independent approximation of the different mixed fields
 - ▶ Lagrangian multiplier approximated equally as the corresponding mixed fields
- ▶ Lagrangian shape functions in time (M, M', \tilde{M}) [Bets 01] [Groß 18]

$$M_i(\alpha) = \prod_{\substack{j=1 \\ j \neq i}}^{k+1} \frac{\alpha - \alpha_j}{\alpha_i - \alpha_j}, \quad 1 \leq i \leq k+1 \quad \tilde{M}_i(\alpha) = \prod_{\substack{j=1 \\ j \neq i}}^k \frac{\alpha - \alpha_j}{\alpha_i - \alpha_j}, \quad 1 \leq i \leq k$$

- ▶ Time rate variables and mixed fields ($q, \lambda, v, p, \tilde{\Theta}, \Theta, \eta, \tilde{C}, \tilde{C}_A, \tilde{H}, \tilde{H}_A, \tilde{J}, \tilde{J}_A$)

$$(\bullet)^{e,h} = \sum_{I=1}^{k+1} \sum_{A=1}^{n_{no}} M_I(\alpha) N^A(\xi) (\bullet)_I^{eA} \quad \left((\dot{\bullet})^{e,h} = \frac{1}{h_n} \sum_{I=1}^{k+1} \sum_{A=1}^{n_{no}} M'_I(\alpha) N^A(\xi) (\bullet)_I^{eA} \right)$$

- ▶ Lagrangian multiplier and variation fields ($S, S_A, B, B_A, p, p_A, \delta_*$)

$$(\bullet)^{e,h} = \sum_{I=1}^k \sum_{A=1}^{n_{ou}} \tilde{M}_I N^A(\bullet) (\bullet)_I^{eA}$$

Implementation

- Solve mixed fields and corresponding Lagrangian multiplier at element level
 - Discontinuous at the boundaries of spatial elements
 - Sequential solution

$$\int_T \int_{\mathcal{B}_0} [\dot{\bar{J}} - \dot{J}] \delta p dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[p - \left[\frac{\partial \Psi}{\partial \bar{J}} + \bar{p} \right] \right] \delta \dot{\bar{J}} dV dt = 0$$

$$\bar{J}_{\text{new}}^e = [\mathbf{A}']^{-1} \left(\int_0^1 \mathbf{b} \boxtimes \dot{J}^e d\alpha - \mathbf{b}' \dot{\bar{J}}_1^e \right) \quad p_{\text{new}}^e = [\tilde{\mathbf{A}}]^{-1} \left(\int_0^1 \mathbf{b} \boxtimes \left[\frac{\partial \Psi}{\partial \bar{J}} + \bar{p} \right] d\alpha \right)$$

- Eliminate \mathbf{p} and η

$$\int_T \int_{\mathcal{B}_0} [\text{Div}[\mathbf{F}\mathbf{S}] - \dot{\mathbf{p}}] \cdot \delta \dot{\mathbf{q}} dV dt = 0 \quad \int_T \int_{\mathcal{B}_0} \left[\frac{1}{\rho_0} \mathbf{p} - \dot{\mathbf{q}} \right] \cdot \delta \dot{\mathbf{v}} dV dt = 0$$

- Condensate at element level to pure displacement temperature form
 - Schur complements \Rightarrow Inverted matrices are constant!

$$\begin{bmatrix} \mathbf{K}_{qq}^e & \mathbf{K}_{q\theta}^e & \mathbf{K}_{q\lambda}^e \\ \mathbf{K}_{\theta q}^e & \mathbf{K}_{\theta\theta}^e & \mathbf{0} \\ \mathbf{K}_{\lambda q}^e & \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \Delta \mathbf{q} \\ \Delta \Theta \\ \Delta \lambda \end{bmatrix} = \begin{bmatrix} \mathbf{r}_q^e \\ \mathbf{r}_\theta^e \\ \mathbf{r}_\lambda^e \end{bmatrix}$$

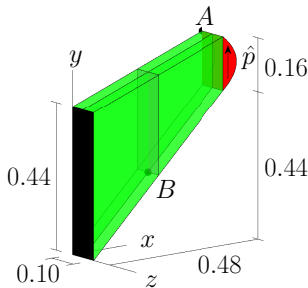
► Strain energy functions ([Schr 11] [Groß 18]):

$$\Psi_M^{iso} = \frac{\epsilon_1}{2} (\text{tr}[\mathbf{C}])^2 + \frac{\epsilon_2}{2} (\text{tr}[\text{cof}[\mathbf{C}]])^2 - \epsilon_3 \ln(J) \quad \Psi_M^{vol} = \frac{\epsilon_4}{2} (J^{\epsilon_5} + J^{-\epsilon_5} - 2)$$

$$\Psi_M^{cap} = c_M^0 (1 - \Theta_\infty c_M^1) (\Theta - \Theta_\infty - \Theta \ln \frac{\Theta}{\Theta_\infty}) - \frac{1}{2} c_M^0 c_M^1 (\Theta - \Theta_\infty)^2$$

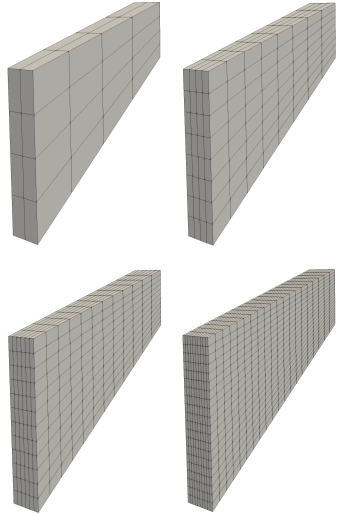
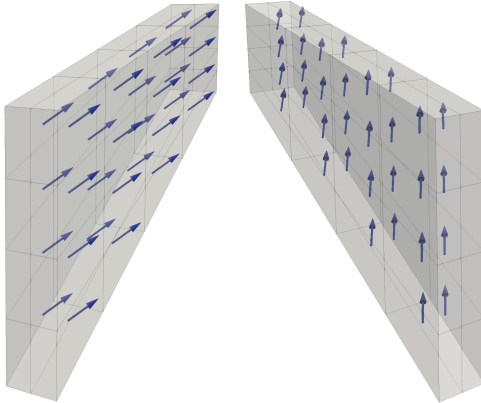
$$\Psi_{F_1}^{ela} = \epsilon_6 \left(\frac{1}{\epsilon_7 + 1} (\text{tr}[\mathbf{C} \mathbf{M}_1])^{\epsilon_7 + 1} + \frac{1}{\epsilon_8 + 1} (\text{tr}[\text{cof}[\mathbf{C}] \mathbf{M}_1])^{\epsilon_8 + 1} + \frac{1}{\epsilon_9} \det[\mathbf{C}]^{-\epsilon_9} \right)$$

$$\Psi_{F_1}^{cap} = c_{F_1}^0 (1 - \Theta_\infty c_{F_1}^1) (\Theta - \Theta_\infty - \Theta \ln \frac{\Theta}{\Theta_\infty}) - \frac{1}{2} c_{F_1}^0 c_{F_1}^1 (\Theta - \Theta_\infty)^2$$

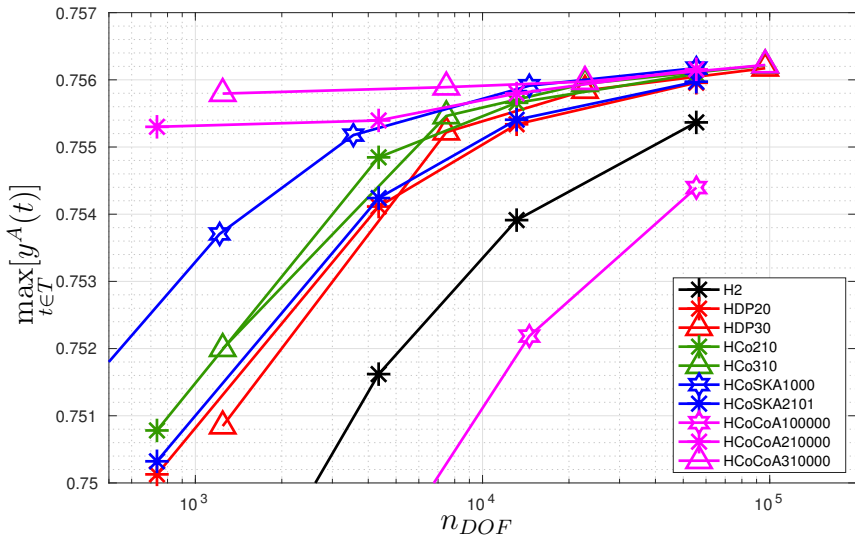


$\epsilon_1 = 0.1e6$	$k_M = 0.1$	$\rho_0 = 1000$
$\epsilon_2 = 0.1e6$	$\beta_M = 1e - 6$	$\hat{p} = 1.5e6$
$\epsilon_3 = 1.8e6$	$c_M^0 = 1000$	$T = 1.0$
$\epsilon_4 = 100e6$	$c_M^1 = 0.001$	$h_n = 0.001$
$\epsilon_5 = 4$	$k_{F_1} = 0.1$	$TOL = 1e - 2$
$\epsilon_6 = 10e6$	$\beta_{F_1} = 1e - 6$	
$\epsilon_7 = 4$	$c_{F_1}^0 = 1000$	
$\epsilon_8 = 4$	$c_{F_1}^1 = 0.001$	
$\epsilon_9 = 1$	$\Theta_\infty = 300$	

Anisotropic direction $(\mathbf{a}_1^0)^T = [1 \ 1 \ 1]$



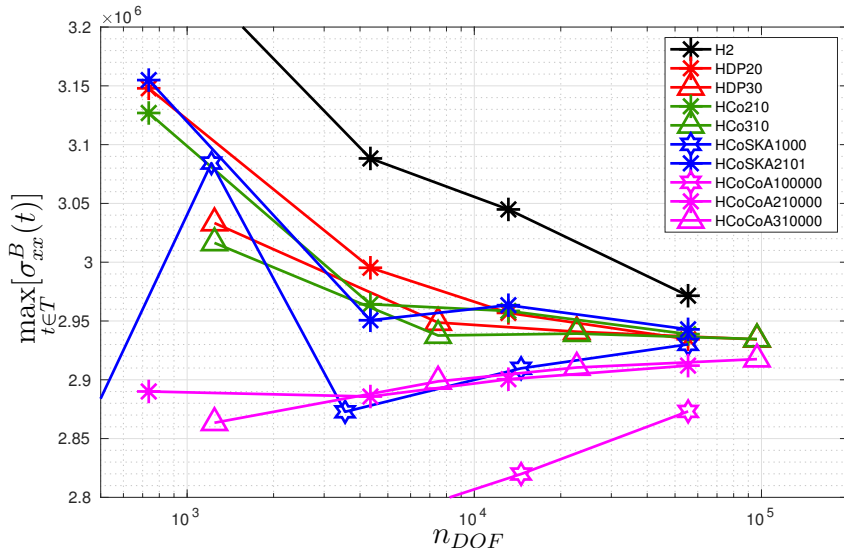
Numerical example - Cook cantilever beam Convergence of the y -coordinate at Point A [eg(1)]



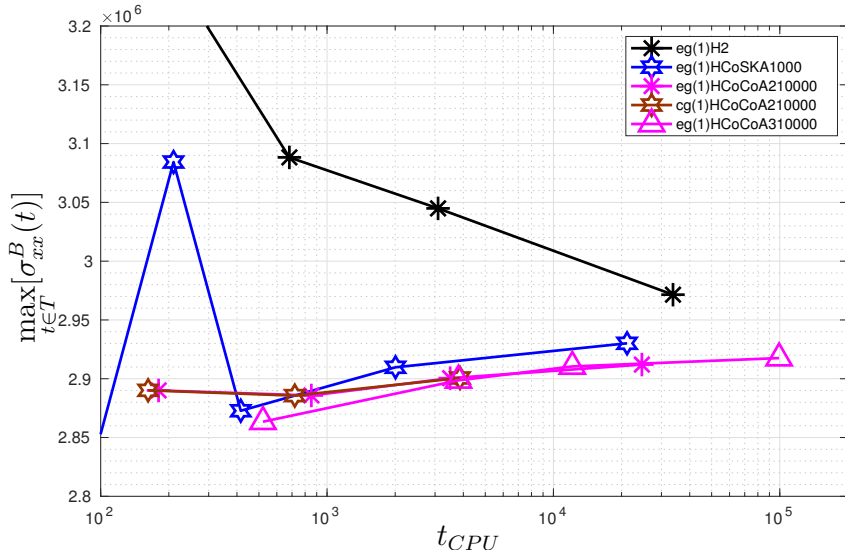
Digits (pol. degree of): $H[q]$ $HDP[q, \tilde{J}]$ $HCo[q, \tilde{H}, \tilde{J}]$ $HCoCoA[q, \tilde{H}, \tilde{J}, \tilde{C}_A, \tilde{H}_A, \tilde{J}_A]$

Numerical example - Cook cantilever beam

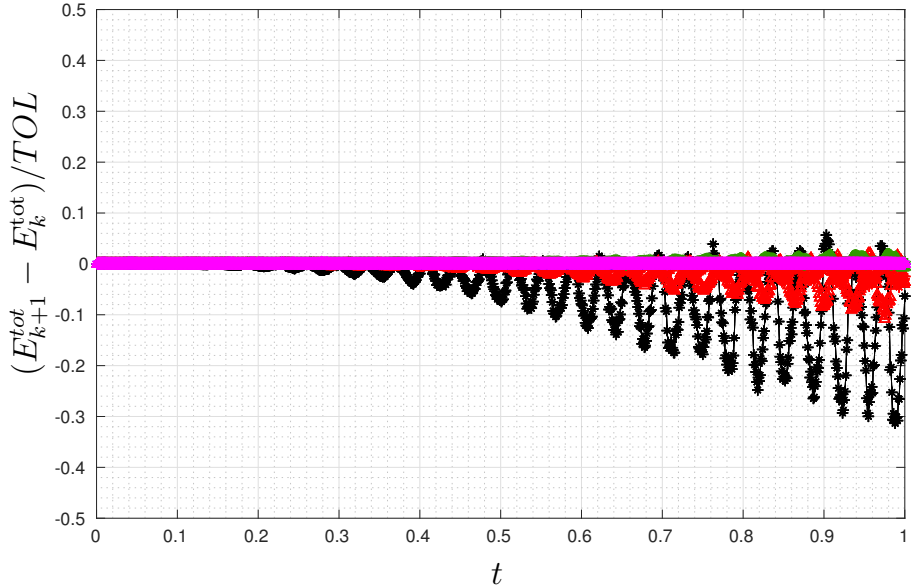
Convergence of σ_{xx} at Point B [eg(1)]

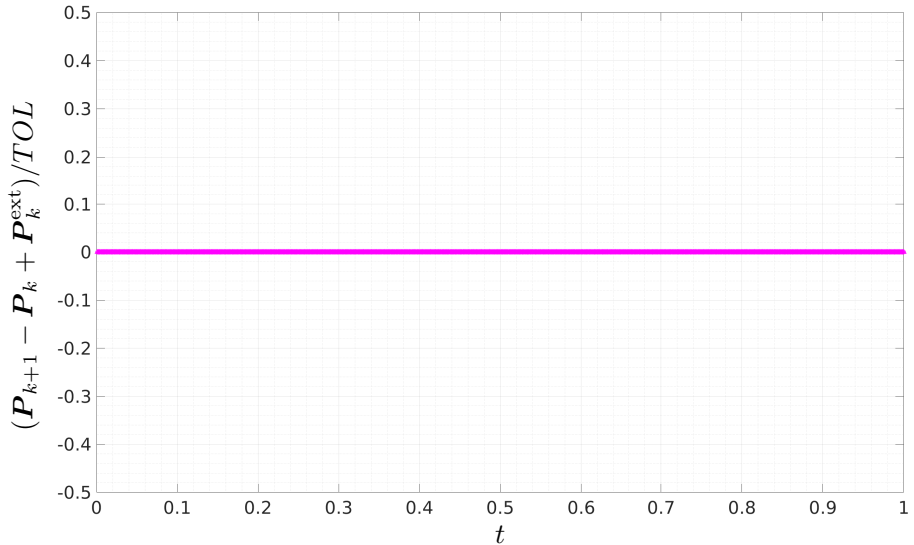


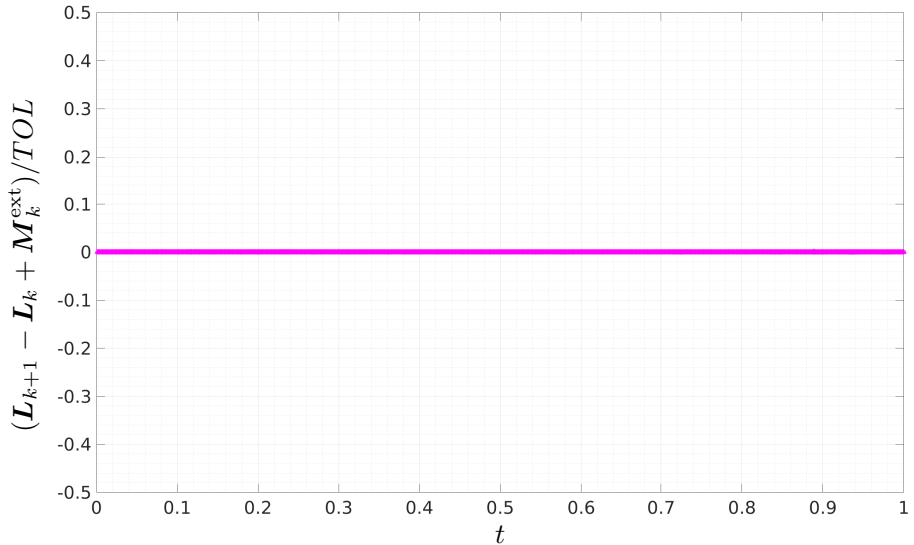
Digits (pol. degree of): $H[q]$ $HDP[q, \tilde{J}]$ $HCo[q, \tilde{H}, \tilde{J}]$ $HCoCoA[q, \tilde{H}, \tilde{J}, \tilde{C}_A, \tilde{H}_A, \tilde{J}_A]$



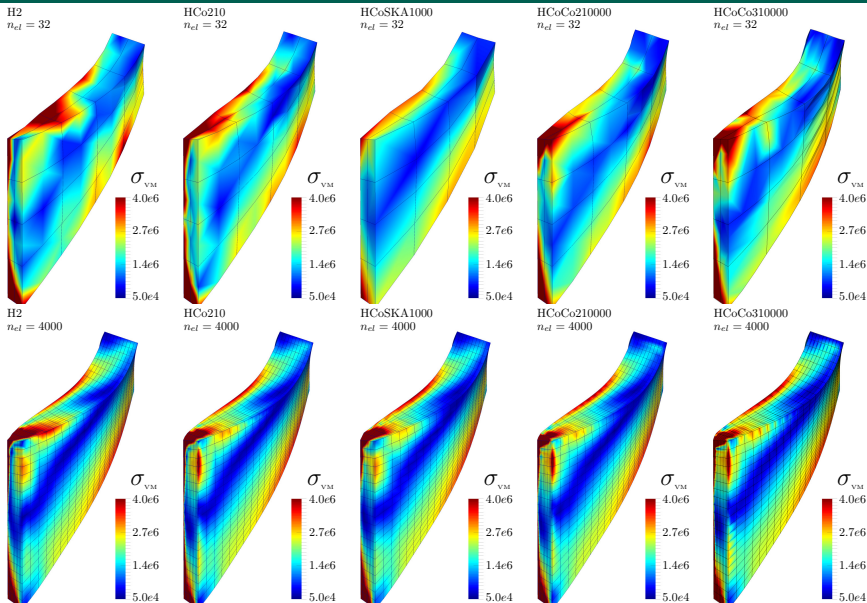
Digits (pol. degree of): $H[q]$ $HDP[q, \tilde{J}]$ $HCo[q, \tilde{H}, \tilde{J}]$ $HCoCoA[q, \tilde{H}, \tilde{J}, \tilde{C}_A, \tilde{H}_A, \tilde{J}_A]$



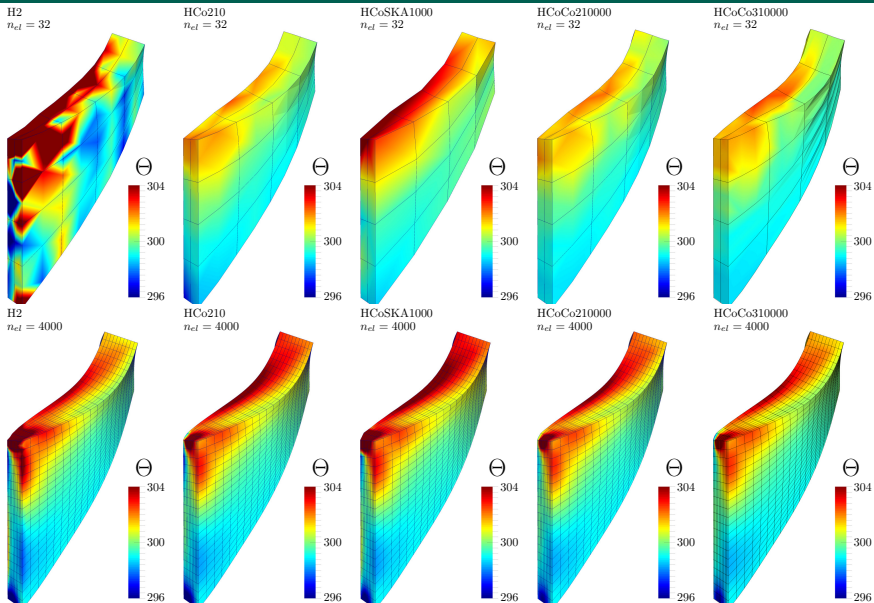




Numerical example - Cook cantilever beam Deformed configuration and v. Mises equivalent stress [eg(1)]



Numerical example - Cook cantilever beam Deformed configuration and temperature distribution [eg(1)]

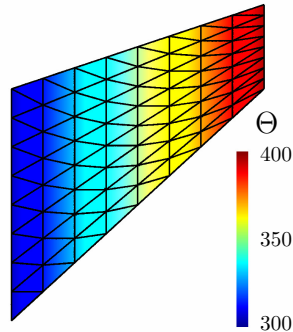
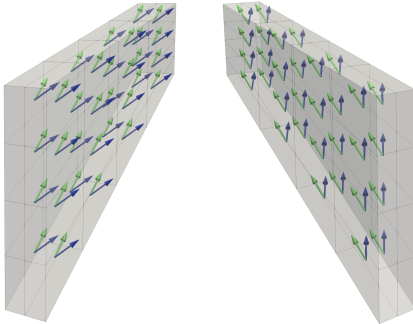


Anisotropic direction $(\mathbf{a}_1^0)^T = [1 \ 1 \ 1]$
Anisotropic direction $(\mathbf{a}_2^0)^T = [1 \ 1 \ 0]$

TCoCo310100

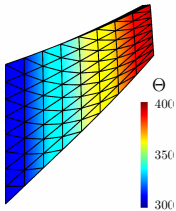
$t = 0.0$

$n_F = 1$

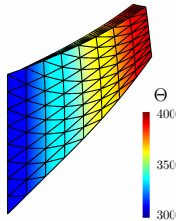


Numerical example - Cook cantilever beam Deformed configuration and temperature distribution TCoCo310100 [eg(2)]

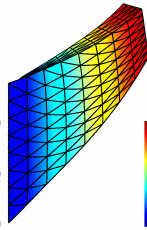
TCoCo310100
 $t = 0.2$
 $n_F = 1$



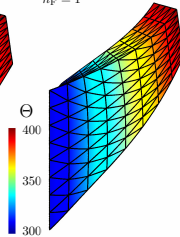
TCoCo310100
 $t = 0.4$
 $n_F = 1$



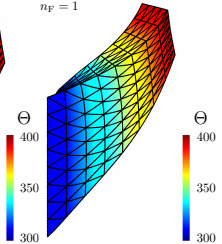
TCoCo310100
 $t = 0.6$
 $n_F = 1$



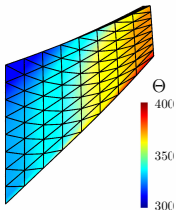
TCoCo310100
 $t = 0.8$
 $n_F = 1$



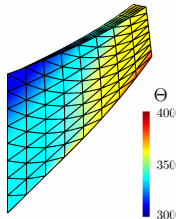
TCoCo310100
 $t = 1.0$
 $n_F = 1$



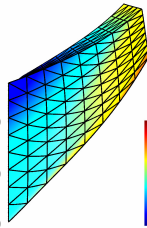
TCoCo310100
 $t = 0.2$
 $n_F = 2$



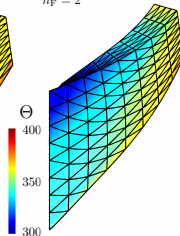
TCoCo310100
 $t = 0.4$
 $n_F = 2$



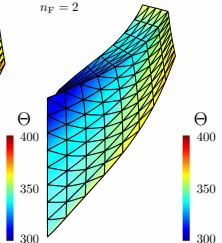
TCoCo310100
 $t = 0.6$
 $n_F = 2$

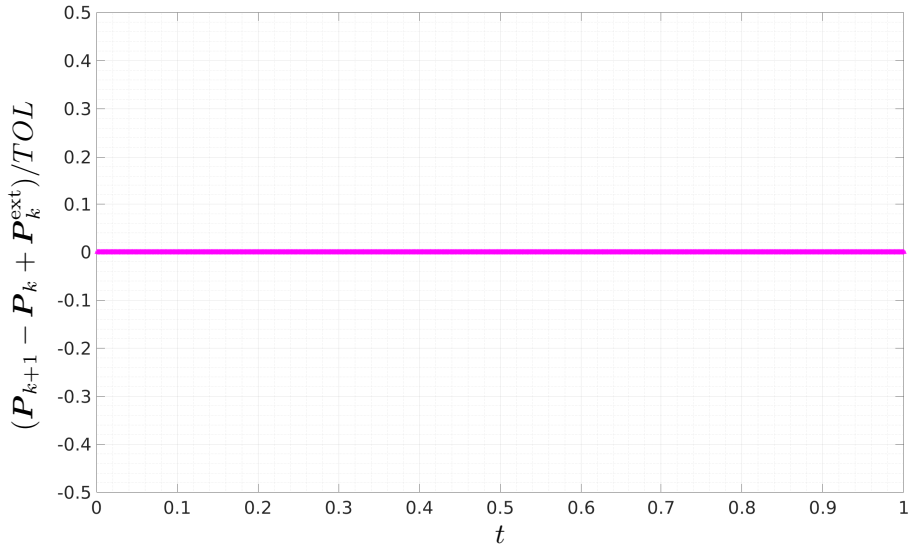


TCoCo310100
 $t = 0.8$
 $n_F = 2$



TCoCo310100
 $t = 1.0$
 $n_F = 2$





Conclusion

- ▶ Motivation:
 - ▶ Dynamic simulations of fiber-reinforced materials in light-weight structures
- ▶ Strategy:
 - ▶ Mixed finite elements to reduce locking effect
 - ▶ Extension to a thermo-mechanical coupling
 - ▶ Higher-order energy-momentum conserving time integrators for stable and accurate simulations
- ▶ Important results:
 - ▶ Excellent performance of the mixed elements is still preserved in a thermo-mechanical context.
 - ▶ Higher-order energy-momentum time integrators conserves energy
 - ▶ Possibility to determine the mechanical and thermal properties of our model separately by using different fibers
- ▶ Outlook:
 - ▶ Extend these formulations to a thermo-viscoelastic material behavior

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