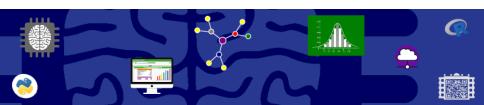
Introduction to Data Science

Winter Semester 2019/20

Oliver Ernst

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Lecture Slides



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- 2 Learning Theory
- 2.1 What is Statistical Learning?
- 2.2 Assessing Model Accuracy
- 3 Linear Regression
- 3.1 Simple Linear Regression
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- 3.3 Other Considerations in the Regression Model
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- 4.5 A Comparison of Classification Methods
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Contents

- Tree-Based Methods
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Chapter overview

- In previous chapter, considered *piecewise* approximation for univariate models (piecewise constant, splines, etc.).
- Here: piecewise constant *multivariate approximation*.
- Much greater variety of possible domain partitions.
- Recursive binary partitioning: efficient representation using binary trees.
- Can be used for regression and classification.
- Refinements: bagging, random forests, boosting.

Contents

- Tree-Based Methods
- 8.1 Decision Tree Fundamentals
- 8.2 Bagging, Random Forests and Boosting

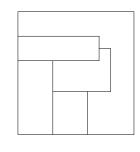
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Basic idea

Consider bivariate model

$$Y = f(X_1, X_2), X_i \in [0, 1].$$

- Divide feature space into axis-aligned rectangles.
- Within each rectangle, predict Y as the mean of the observations it contains.

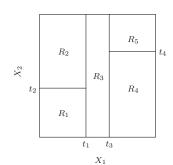


 X_1

Basic idea

- Simpler structure: construct rectangles by recursive binary partitioning.
- Predicting $Y = \hat{y}_{R_m}$ in region R_m yields piecewise constant model

$$Y = \hat{f}(X) = \sum_{m=1}^{5} \hat{y}_{R_m} \, \mathbf{1}_{\{X \in R_m\}}$$

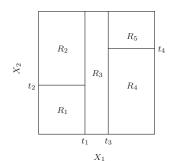


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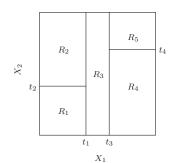
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 - First split at $X = t_1$.



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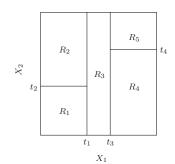
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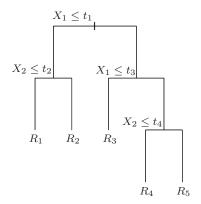
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 - Finally: region $X_1 > t_3$ is split at $X_2 = t_4$.

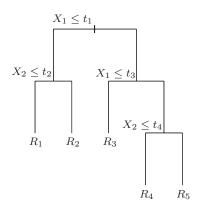


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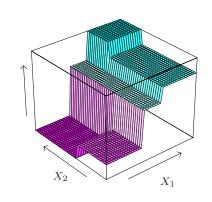


Recursive binary partition more conveniently represented by a binary tree; regions appear as **leaves**, internal nodes are the splits.

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Equivalent representation as piecewise constant function.

Hitters example

Hitters data set: predict baseball player's Salary based on

Years: # years played in major leagues
Hits: # hits made in previous year

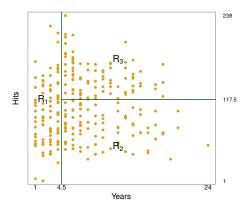
Hitters example

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Years: # years played in major leagues
Hits: # hits made in previous year
```

- First remove observations missing Salary values.
- Log-transform Salary values [k\$] to make distribution more bell-shaped.

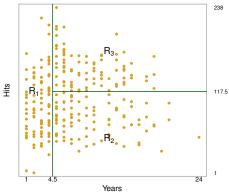
Hitters example



First split yields
 R₁ = {X : Years < 4.5}.

Observations of Years and Hits with partitioning arising from two splits.

Hitters example



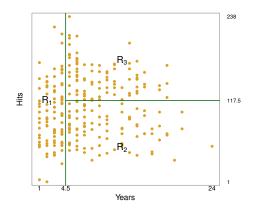
Observations of Years and Hits with

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- First split yields
 R₁ = {X : Years < 4.5}.
- Second split at Hits = 117.5 yields $R_2 = \{X : Years \ge 4.5, Hits < 117.5\}$ and

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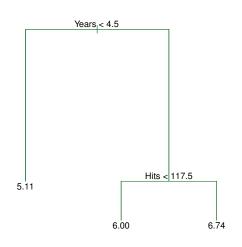
Predicted Salary in these regions:

$$R_1: \$1000 \times e^{5.107} = \$165, 174,$$

$$R_2: $1000 \times e^{5.999} = $402,838,$$

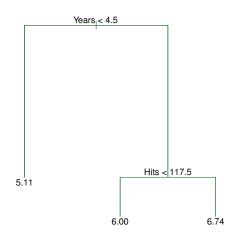
$$R_3: $1000 \times e^{6.740} = $845, 346.$$

Hitters example



• Left branch contains R_1 , right branch R_2 and R_3 .

Hitters example

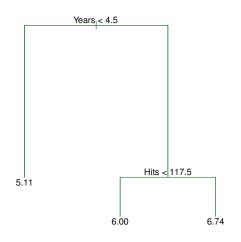


 Left branch contains R₁, right branch R₂ and R₃.

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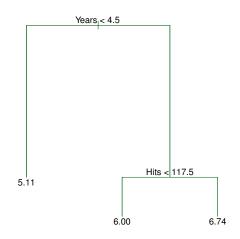
 Tree has two internal nodes, three terminal nodes (leaves).

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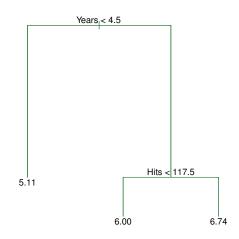
- Left branch contains R_1 , right branch R_2 and R_3 .
- Tree has two internal nodes, three terminal nodes (leaves).
- Number in each leaf gives mean value of log(Salary) for corresponding region.

Hitters example



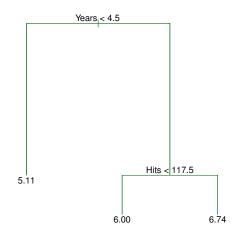
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- Advantages of tree: easily interpretable, nice graphical representation.

Hitters example



Regression tree resulting from these splits.

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- Interpretation: Years is most important factor in determining Salary (less experienced players earn less); Hits important Salary-relevant feature only among experienced players.
- Advantages of tree: easily interpretable, nice graphical representation.
- Known as CART: classification and regression tree.

Tree construction

• **Goal:** Partition feature space into high-dimensional rectangles $\{R_m\}_{m=1}^M$ in such a way that

RSS =
$$\sum_{m=1}^{M} \sum_{j \in R_m} (y_i - \hat{y}_{R_m})^2$$
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is minimized. (\hat{y}_{R_m} : mean of the response observations contained in R_m .)

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- Top-down refers to starting with the entire feature space and recursively splitting regions (recursive binary splitting).
- Greedy approach refers to determining the locally best split without looking ahead and possibly choosing a split leading to a better tree in some future step.

Tree construction

• To construct first split, consider splitting along variable X_j at splitting point $X_j = s$ and define half-spaces

$$R_1(j,s) := \{X : X_j \le s\}, \qquad R_2(j,s) := \{X : X_j > s\}.$$
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- For fixed j, s, the two minimizing values of \hat{y}_{R_1} and \hat{y}_{R_2} are clearly the sample means of the response observations in R_1 and R_2 , respectively.
- For each j, the optimal splitting point s can be found very quickly; with best split (j, s), partition data into the resulting two subregions and continue splitting recursively.

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 reduction of RSS for each split.
 However, split with small RSS reduction may enable larger reduction in
 - subsequent splits.
- Better strategy: grow very large tree T_0 , then **prune** it back to obtain a **subtree**.
- Can compare different subtrees using cross-validation, but comparing all
 possible subtrees is infeasible.

Cost complexity pruning

• Cost complexity pruning (a.k.a. weakest link pruning): consider sequence of trees indexed by tuning parameter $\alpha \ge 0$.

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Cost complexity pruning

- Cost complexity pruning (a.k.a. weakest link pruning): consider sequence of trees indexed by tuning parameter $\alpha \ge 0$.
- To each $\alpha \geq 0$ there corresponds a subtree $T \subset T_0$ which minimizes

$$\sum_{m=1}^{|T|} \sum_{i:x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|, \tag{8.3}$$

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- $\alpha=0$ corresponds to T_0 . For $\alpha>0$ (8.3) minimized by smaller tree T_{α} (can show this is unique).
- To find T_{α} use **weakest link pruning**: successively collapse internal node producing smallest per-node increase in $\sum_{m,i} (y_i \hat{y}_{R_m})^2$, continue until single-node tree reached. Can show: this tree sequence must contain T_{α} .
- Select α using validation set or cross-validation.

Regression tree algorithm

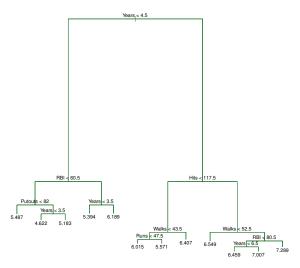
Algorithm 4: Regression tree.

- Use recursive binary splitting to grow tree T_0 on the training data, stopping when each leaf contains fewer than some minimum number of observations.
- **2** Apply cost complexity pruning to T_0 to obtain sequence of best subtrees, as a function of α .
- 3 Use K-fold cross-validation to choose α : divide training observations into K folds. For each $k=1,\ldots,K$:
 - \bigcirc Repeat steps 1 and 2 on all but k-th fold of training data.
 - m Evaluate test MSE on left out k-th fold, as function of α .

Average MSE for each value of α , choode α minimizing average MSE.

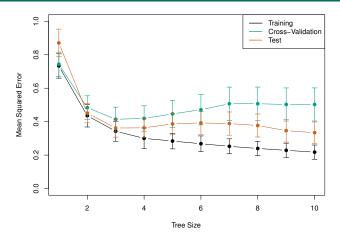
4 Return subtree from Step 2 corresponding to minimizing α .

Hitters example revisited



- Hitters data set using nine features.
- Randomly divide data set into 132 training and 131 test observations.
- Grow tree on training data.
- Vary α to obtain subtrees T_{α} with different numbers of leaves.
- Perform 6—fold CV to estimate MSE of T_{α} as function of α .
- Unpruned tree shown on left.

Hitters example revisited



Training, CV and test MSEs for regression tree of Hitters data set as a function of α with bands indicating ± 1 standard error. CV MSE somewhat pessimistic, but reasonable estimate of test MSE.

Classification Trees

• Tree-based piecewise constant prediction model for qualitative response.

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- In place of mean value, predict in R_m the most commonly occurring response observation there (majority vote).
- Grow classification tree using recursive binary splitting.
- In place of RSS, can use **classification error rate** *E* to determine optimal splits. This is simply the fraction of training observations not belonging to the most commonly occurring class, i.e.

$$E=1-\max_{k}\hat{p}_{m,k}$$
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 $\hat{p}_{m,k}$: proportion of training observations in R_m from k-th class.

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• Classification error rate *E* not sensitive enough for tree-growing. Two other popular measures preferable:

Gini index and entropy

• The **Gini index** is defined by

$$G = \sum_{k=1}^{K} \hat{p}_{m,k} (1 - \hat{p}_{m,k})$$
 (8.4)

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and represents a measure of total variance across the K classes. Small if all $\hat{p}_{m,k}$ close to zero or one; indication of node *purity*, i.e., small value indicates node contains predominantly observations from a single class.

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Entropy (or deviance) is defined by

$$D = -\sum_{k=1}^{K} \hat{p}_{m,k} \log \hat{p}_{m,k}. \tag{8.5}$$

Note $\hat{p}_{m,k} \log \hat{p}_{m,k} \leq 0$ since $\hat{p}_{m,k} \in [0, 1]$.

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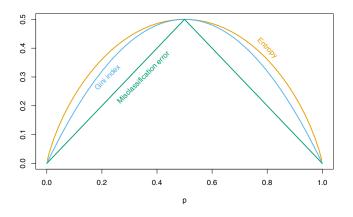
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• Any of *E*, *G* or *D* can be used to build the tree, but pruning should be done using *E* to maximize prediction accuracy of final pruned tree.

Gini index and entropy

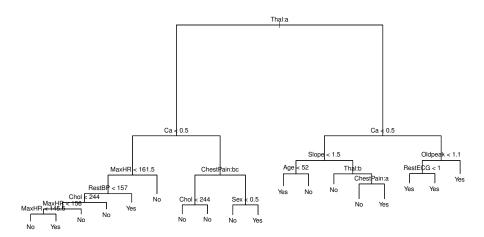


Node purity measures for two-class classification as a function of proportion p in class 2. Entropy has been scaled to pass through (0.5, 0.5). For two classes, if p denotes the proportion in class 2, the three measures are $1 - \max(p, 1 - p)$, 2p(1 - p) and $-p \log p - (1 - p) \log(1 - p)$.

Heart example

- Heart data set: binary response HD for 303 patients who presented with chest pain.
- Response Yes indicates presence of heart disease (based on angiographic test), No indicates absence of heart disease.
- 13 predictors including Age, Sex, Chol (cholesterol measurement), and further heart and lung function measurements.
- Cross-validation results in tree with six leaves.

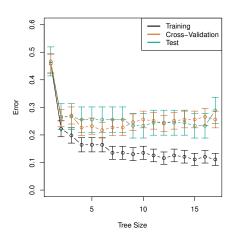
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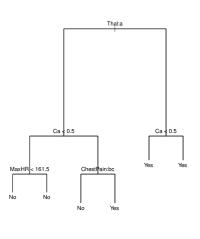


Heart data set: unpruned tree.

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Heart example





Heart data set. Left: training, CV and test MSE for different sizes of pruned tree.

Right: pruned tree corresponding to minimal CV MSE.

Heart example, qualitative predictors

- Heart data set contains a number of qualitative predictor variables such as Sex, Thal (Thallium stress test) and ChestPain.
- Splitting along one of these variables: assign some of the qualitative values to one branch, remaining values to other branch.
- In previous image: some internal nodes split quantitative variables.
- Top internal node splits Thal. Text Thal:a indicates left branch consists of observations with first value of Thal (normal), right consists of remaining values (fixed or reversible defects).
- Text ChestPain:bc on third split on left indicates left branch contains observations with second and third values of ChestPain variable (whose possible values are typical angina, atypical angina, non-anginal pain and asymptomatic).

Heart example, leaves with identical values

- Some leaves in Heart classification tree have the same prediction values.
- Example: split RestECG < 1 near bottom right of unpruned tree, both subregions predict response value Yes. Why perform split in the first place?

Heart example, leaves with identical values

- Some leaves in **Heart** classification tree have the same predicion values.
- Example: split RestECG < 1 near bottom right of unpruned tree, both subregions predict response value Yes. Why perform split in the first place?
- Split made to increase node purity.
- All 9 observations in right branch have leaf response value Yes. In left branch, 7/11 have response value Yes.
- Importance of node purity: given test observation belonging to region on right branch, then response certaionly Yes. For test observation on left branch, pobably Yes, but with much less certainty.
- ullet Even though RestECG < 1 does not reduce classification error, it improves the Gini index and entropy, which are more sensitive to node purity.

Trees vs. linear models

Prediction model of linear regression vs. regression tree

$$f(X) = \beta_0 + \beta_1 X_1 + \dots + \beta_p X_p, \qquad f(X) = \sum_{m=1}^{M} \hat{\mathbf{y}}_{R_m} \mathbf{1}_{\{X \in R_m\}}$$

with regression coefficients $\{\beta_j\}_{j=0}^p$ and partition of feature space into rectangular regions R_m .

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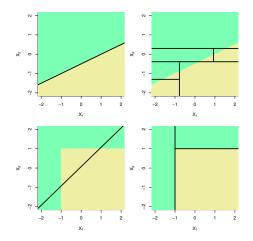
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- If feature-response relation close to linear, linear regression model likely superior.
 - Otherwise, tree-based models may outperform linear regression.
- Relative performances can be assessed by estimating test MSE via CV or validation set approach.
- Other considerations may also be relevant in comparison, such as interpretability or visualization.

Trees vs. linear models: example



Top row: 2D classification example with linear decision boundary (shaded regions), linear regression model superior. Bottom row: nonlinear)(piecewise constant) decision boundary captured perfectly by tree-based method,

Advantages and shortcomings of trees

- + Easy to explain (more so than linear regression).
- + Some argue decision trees more closely mimick human decision-making than linear regression/classification techniques (also widely used outside of statistical learning).
- + Trees, particularly small ones, easily displayed graphically, easily interpreted by non-experts.
- + Can handle qualitative predictors without introducing dummy variables.
- Prediction accuracy generally not as good as classical regression and classification techniques.
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Some of these disadvantages addressed by bagging, random forests, boosting.

Contents

- Tree-Based Methods
- 8.1 Decision Tree Fundamentals
- 8.2 Bagging, Random Forests and Boosting

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Bagging

Recall the bootstrap approach introduced in Chapter 5 for randomly generating subsamples of a set of observations for estimating statistical quantities without collecting additional data.

Bagging

- Recall the bootstrap approach introduced in Chapter 5 for randomly generating subsamples of a set of observations for estimating statistical quantities without collecting additional data.
- Here we revisit the bootstrap to show how it can be used as a variancereduction technique for any statistical learning method.
- This is particularly relevant for decision trees, which tend to possess high variance.
- Bagging: bootstrap aggregation.
- Variance can be reduced by averaging observations: for $\{X_k\}_{k=1}^N$ i.i.d. RV with variance σ^2 , variance of $\overline{X} = (X_1 + \cdots + X_N)/N$ is σ^2/N .
- Idea: Collect N training sets, construct prediction model \hat{f}_k for each, and average these to aggregate model

$$\hat{f}_{\text{avg}}(x) = \frac{1}{N} \sum_{k=1}^{N} \hat{f}_k(x).$$

Bagging

• Collecting *N* data sets generally infeasible.

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- Bootstrap: randomly select (with replacement) N_b sets of samples from (single) original data set. For each resampled data set, construct prediction model \hat{f}_k^* , $k = 1, ..., N_b$.

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Bagging

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For each resampled data set, construct prediction model \hat{f}_k^* , $k=1,\ldots,N_b$. Form bootstrap aggregate model

$$\hat{f}_{bag}(x) = \frac{1}{N_b} \sum_{k=1}^{N_b} \hat{f}_k^*(x).$$

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- For (regression) decision trees: grow (unpruned) tree for each resampled data set and average them.
- For classification trees: replace average with **majority vote**, i.e., for each new predictor observation, have aggregate model predict that class occurring most commonly across all decision trees \hat{f}_k^* .

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- For *i*-th observation: predict response using all trees for which it was OOB. Take average (regression) or majority vote (classification) to obtain aggregated prediction for all *n* observations, compare with response observation, i.e., MSE (regression) or classification error (classification), to obtain error estimate.

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- Can show: for N_b sufficiently large, OOB error estimate virtually equivalent to LOOCV error estimate.
 - This is a great benefit when performing bagging on large data sets, where CV would be computationally burdensome.

Measuring variable importance

Drawback of bagging: no single decision tree for interpretation.
 Increased predicion accuracy at the expense of interpretability.

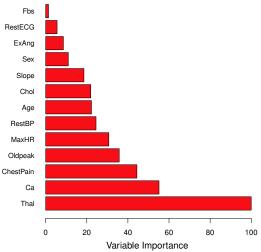
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- For regression trees, overall summary of importance of each predictor can be obtained by recording total amount RSS decreases when split performed along this variable, then averaging over all trees.
- For classification trees: record total Gini index reduction due to splits along each predictor per tree, then average over all trees.
- Large value indicates important predictor variable.

Measuring variable importance: Heart data set



Heart data set. Variable importance (relative to maximum) in terms of mean decrease in Gini index.

Random forests

- Improve over bagging by "decorrelating" trees.
- Build decision trees on bootstrapped samples as in bagging.
- When choosing next predictor variable to split, restrict selection to m < p randomly chosen variables instead of full set of p predictors.
 New set of m splitting candidates chosen at each splitting step.
- Common choice: $m \approx \sqrt{p}$. Smaller m called for in case of many correlated predictors.

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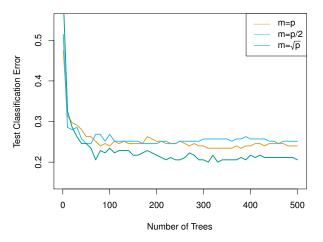
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 - This limits the variance reduction from averaging.
- On average, (p-m)/p splits will not even consider a given strong predictor.
- This mechanism results in a decorrelation of the trees, making their average less variable, hence more reliable.

Random forests: gene expression example

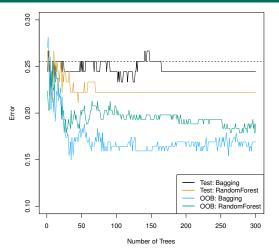
- High-dimensional biological data set: expression measurements for 4,718 genes on tissue samples from 349 patients.
- Human genome contains \approx 20,000 genes.
- Individual genes have varying levels of expression (activity) in different body cells, tissue or biological conditions.
- Here: each patient sample assigned to one of 15 classes (normal or one of 14 cancer types).
- Goal: predict cancer type using random forests based on 500 genes with largest variance in training set.
- Random division into training and test set.
- Random forests applied for 3 different values of m.

Random forests: gene expression example



Random forests for 15-class gene expression with p=500: test error against # trees. Single tree has classification error rate of 45.7%. Null rate (always assign to dominant class) is 75.4%. As for bagging, no danger of overfitting as # trees increases.

Bagging vs. random forests: Heart data set



Test error against number N_b of bootstrapped data sets. Random forests used $m=\sqrt{p}$. Dashed line: error of single classification tree. Solid green/blue: OOB errors considerably lower.

Boosting

- Boosting: general approach for improving predictions of statistical learning methods, here in context of decision trees.
- Basic approach as in bagging, but trees grown sequentially using information from previously generated trees.
- No bootstrap sampling; instead, each tree fit to a modified version of original data set.

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- No bootstrap sampling; instead, each tree fit to a modified version of original data set.
- Prodedure: begin with tree fit to original data.
- Fit next tree to **residuals** of first model in place of observation responses. Then add this tree to the first, as a **model correction**.
- Each tree can be small (few leaves) determined by parameter *d* in the algorithm.
 - By fitting small trees to residuals, \hat{f} is slowly improved in areas where it previously didn't perform well.
- Boosting for classification trees slightly more complicated.

Tuning parameters in boosting

 \blacksquare # trees N_b . Overfitting is possible with boosting, although it sets in slowly. Selection using CV.

Tuning parameters in boosting

- \bullet # trees N_b . Overfitting is possible with boosting, although it sets in slowly. Selection using CV.
- **2** Shrinkage parameter $\lambda > 0$ (small) determining learning rate. Typical values 10^{-2} or 10^{-3} . Very small λ can require very large N_b for good prediction.
- # splits d per tree, controls complexity of boosted ensemble. Can also use d = 1 ("stump") with single split, leads to an additive model. Since d splits can involve at most d variables, it controls the interaction order of the boosted model.

Algorithm 5: Boosting for regression trees.

- ① Set $\hat{f}(x) \equiv 0$ and $r_i = y_i$, i = 1, ..., n (entire training set).
- **2** for k = 1 to N_n do

Fit a tree \hat{f}_k with d splits (d+1) leaves to training data (X, r) Update \hat{f}_k by adding damped version of new tree:

$$\hat{f}(x) \leftarrow \hat{f}(x) + \lambda \hat{f}_k(x)$$

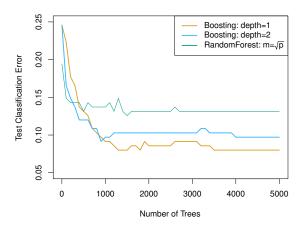
Update residuals

$$r_i \leftarrow r_i - \lambda \hat{f}_k(x_i), \quad i = 1, \dots, n.$$

3 Output boosted model

$$\hat{f}(x) = \sum_{k=1}^{N_b} \lambda \hat{f}_k(x).$$

Gene expression example revisited



Boosting and random forests for gene expression example: test error against # trees using $\lambda=0.01$ for boosted models. Depth-1 trees slightly outperform depth-2 trees, both outperform random forest, but difference is within standard error. Single tree has error rate 24%.