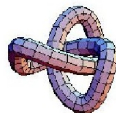


# Ill-posedness concepts and the distinguished role of smoothness in regularization for linear and nonlinear inverse problems

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Robert Plato (Siegen)

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Let  $X$  and  $Y$  be infinite dimensional Hilbert or Banach spaces.  
We consider **operator equations** modelling inverse problems,  
and distinguish **linear inverse problems**

$$Ax = y \quad (x \in X, y \in Y), \quad (*)$$

with a **bounded linear forward operator**  $A \in \mathcal{L}(X, Y)$ ,  
and **nonlinear inverse problems**

$$F(x) = y \quad (x \in \mathcal{D}(F) \subseteq X, y \in Y), \quad (**)$$

where  $F : \mathcal{D}(F) \subseteq X \longrightarrow Y$  is a **nonlinear forward operator**  
with **domain**  $\mathcal{D}(F)$ .

The **forward operators**  $A$  and  $F$  are typically ‘**smoothing**’,  
i.e., information about the solution  $x^\dagger$  of  $(*)$  and  $(**)$   
is erased at the transition to  $y$ : **ill-posedness phenomenon**.

Considering for simplicity the **deterministic noise model**

$$\|y - y^\delta\|_Y \leq \delta, \quad (\text{Noise})$$

**regularization** is to find **stable** approximations to  $x^\dagger$  from  $y^\delta$ ,  
where **objective and subjective a priori information** helps  
to suppress the negative consequences of ill-posedness.



## Local ill-posedness for nonlinear problems $(**)$

▷ B.H. AND O. SCHERZER: Factors influencing the ill-posedness of nonlinear problems. *Inverse Problems* **10** (1994), pp. 1277–1297.

### Definition

The equation  $(**)$  is called **locally well-posed** at the solution point  $x^\dagger \in \mathcal{D}(F)$  if there is a ball  $B_r(x^\dagger)$  around  $x^\dagger$  with radius  $r > 0$  such that for each sequence  $\{x_n\}_{n=1}^\infty \subset B_r(x^\dagger) \cap \mathcal{D}(F)$

$$\lim_{n \rightarrow \infty} \|F(x_n) - F(x^\dagger)\|_Y = 0 \implies \lim_{n \rightarrow \infty} \|x_n - x^\dagger\|_X = 0$$

holds true. Otherwise  $(**)$  is called **locally ill-posed** at  $x^\dagger$ .

For an application of this ill-posedness concept see:

▷ A. KIRSCH, A. RIEDER: Seismic tomography is locally ill-posed. *Inverse Problems* **30** (2014), 125001 (7pp).

## Nashed's ill-posedness concept for linear problems (\*) in Hilbert spaces

▷ M. Z. NASHED: A new approach to classification and regularization of ill-posed operator equations. In: H. W. Engl and C. W. Groetsch (Eds.), Inverse and Ill-posed Problems (Sankt Wolfgang, 1986), volume 4 of Notes Rep. Math. Sci. Engrg., pp. 53–75. Academic Press, Boston, MA, 1987.

### Definition

The linear operator equation (\*) is called **well-posed** if the range  $\mathcal{R}(A)$  of  $A$  is a closed subset of  $Y$ . Consequently it is called **ill-posed** if the range is not closed, i.e.  $\mathcal{R}(A) \neq \overline{\mathcal{R}(A)}^Y$ . In the ill-posed case, the equation (\*) is called **ill-posed of type I** if the range  $\mathcal{R}(A)$  contains an infinite dimensional closed subspace, and alternatively **ill-posed of type II** if  $A$  is compact.

**Degree of ill-posedness** is verified for type II (A compact) from **decay rate of singular values**  $\sigma_i(A) \rightarrow 0$  as  $i \rightarrow \infty$ .

### Definition

If there is a constant  $C > 0$  and an exponent  $\kappa > 0$  such that

$$\sigma_i(A) \geq C i^{-\kappa} \quad (i = 1, 2, \dots), \quad (\$)$$

we call the operator equation (\*) **moderately ill-posed** of degree at most  $\kappa$ , and in particular for  $\sigma_i(A) \asymp i^{-\kappa}$  of degree  $\kappa$ . If (\$) does not hold for arbitrarily large  $\kappa > 0$ , we call the operator equation (\*) **severely ill-posed**.

Typical for severe ill-posedness is **exponential ill-posedness**.

For decreasing sequences  $s_i \geq 0$  and  $t_i \geq 0$  we say that  $s_i \asymp t_i$  ( $i \in \mathbb{N}$ ) if there are constants  $0 < \underline{c} \leq \bar{c} < \infty$  such that  $\underline{c} s_i \leq t_i \leq \bar{c} s_i$  ( $i \in \mathbb{N}$ ).

**Ill-posedness of type I:** Hausdorff moment problem (\*)  
with non-compact forward operator  $A : L^2(0, 1) \rightarrow \ell^2$  defined as

$$[Ax]_j := \int_0^1 t^{j-1} x(t) dt \quad (j = 1, 2, \dots).$$

**Ill-posedness of type II:**  $r$ -times fractional differentiation (\*)  
with compact Volterra operator  $A : L^2(0, 1) \rightarrow L^2(0, 1)$  as

$$[Ax](s) := \int_0^s \frac{(s-t)^{r-1}}{\Gamma(r)} x(t) dt \quad (0 \leq s \leq 1).$$

For all  $r > 0$ , fractional differentiation is ill-posed of degree  $r$ .

## Proposition

The linear operator equation  $(*)$  is either **locally well-posed everywhere** on  $X$  (which is the case if the equation is well-posed in the sense of Nashed and if moreover the null-space of  $A$  is trivial), or the linear operator equation  $(*)$  is **locally ill-posed everywhere** on  $X$ .

**Proof:** Evidently, by definition we see that  $(*)$  is locally ill-posed everywhere if  $\mathcal{N}(A) \neq \{0\}$ . In the case  $\mathcal{N}(A) = \{0\}$ , local well-posedness at  $x^\dagger$  is valid if and only if the implication

$$\|A(x_n - x^\dagger)\|_Y \rightarrow 0 \implies \|x_n - x^\dagger\|_X \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

holds whenever  $\|x_n - x^\dagger\|_X \leq r$ . This implication, however, is valid if and only if the inverse operator  $A^{-1} : \mathcal{R}(A) \rightarrow X$  is bounded, which just characterizes the situation of a closed range  $\mathcal{R}(A) = \overline{\mathcal{R}(A)}^Y$ .

## Further selected references on ill-posedness concepts:

- ▷ H. W. ENGL, M. HANKE AND A. NEUBAUER: *Regularization of Inverse Problems*. Kluwer, Dordrecht, 1996.
- ▷ O. SCHERZER, M. GRASMAIR, H. GROSSAUER, M. HALTMEIER, F. LENZEN: *Variational Methods in Imaging*. Springer, New York, 2009.
- ▷ T. SCHUSTER, B. KALTENBACHER, B. HOFMANN, K. S. KAZIMIERSKI: *Regularization Methods in Banach Spaces*. Walter de Gruyter, Berlin/Boston, 2012.
- ▷ B.H. AND R. PLATO: On ill-posedness concepts, stable solvability and saturation. *J. Inverse Ill-Posed Probl.* **18** (2018), pp. 287–297.
- ▷ P. MATHÉ, B.H. AND M. T. NAIR: Regularization of linear ill-posed problems involving multiplication operators. *Appl. Anal.* **101** (2022), pp. 714–732.

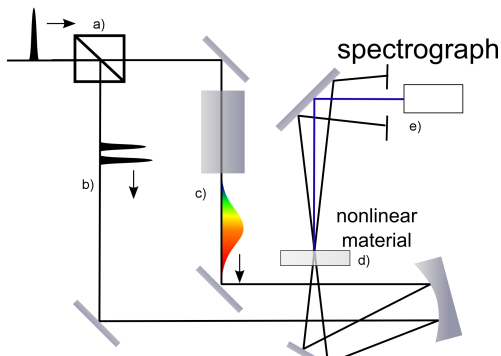
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# Two examples of nonlinear problems

## Example 1: A problem in short-term laser optics

SPIDER = Spectral Phase Interferometry for Direct Electric Field Reconstruction

Special version **Self-Diffraction (SD) SPIDER** was developed by **Max Born Institute for Nonlinear Optics, Berlin**





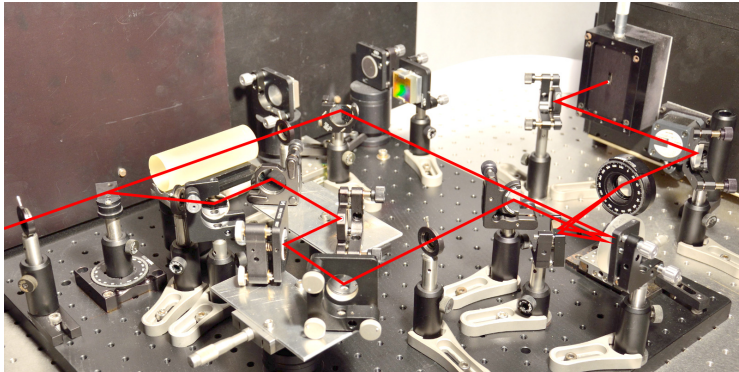


Figure: Measurement setup in self-diffraction spectral interferometry.

The physical model leads to an **autoconvolution problem**

$$\int_{\max(s-1,0)}^{\min(s,1)} k(s,t)x(s-t)x(t)dt = y(s) \quad (0 \leq s \leq 2) \quad (**)$$

with the corresponding **nonlinear forward operator**

$$F : X = L^2_{\mathbb{C}}(0,1) \rightarrow Y = L^2_{\mathbb{C}}(0,2).$$

We have to determine a **complex-valued** function  $x$  (characteristics of a short-term - femtosecond - laser pulse) from complex-valued measurement data of  $y$ , where the complex-valued continuous kernel  $k$  is available.

▷ J. FLEMMING: *Variational Source Conditions, Quadratic Inverse Problems, Sparsity Promoting Regularization. New Results in Modern Theory of Inverse Problems and an Application in Laser Optics*. Frontiers in Mathematics. Birkhäuser, Cham, 2018.

Let us consider for simplicity the case of a trivial kernel  $k \equiv 1$  as

$$[F(x)](s) := \int_{\max(s-1,0)}^{\min(s,1)} x(s-t)x(t)dt = y(s) \quad (0 \leq s \leq 2) \quad (**).$$

### Proposition

This equation (\*\*) is **locally ill-posed** everywhere on  $L^2_{\mathbb{C}}(0, 1)$ .

**Proof idea:** We consider on  $X = L^2_{\mathbb{C}}(0, 1)$  the sequence  $x_n = x^\dagger + \Delta_n$  for  $\Delta_n(t) = r e^{i n^2 t^2}$  with  $\|\Delta_n\|_X = r$ ,  $\Delta_n \rightharpoonup 0$  and  $\|F(\Delta_n)\|_Y \rightarrow 0$  as  $n \rightarrow \infty$ . The nonlinear operator  $F$  is **non-compact**, but its Fréchet derivative  $F'(x^\dagger)$  is **compact** for all  $x^\dagger \in L^2_{\mathbb{C}}(0, 1)$ . Hence,  $\|F'(x^\dagger)\Delta_n\|_Y \rightarrow 0$  as  $n \rightarrow \infty$  and thus  $\|F(x_n) - F(x^\dagger)\|_Y = \|F(\Delta_n) + F'(x^\dagger)\Delta_n\|_Y \rightarrow 0$  as  $n \rightarrow \infty$ .

This shows the local ill-posedness everywhere.

We derive from of **Titchmarsh's convolution theorem**:

### Proposition

If for given  $y \in Y = L^2_{\mathbb{C}}(0, 2)$  the function  $x^\dagger \in X = L^2_{\mathbb{C}}(0, 1)$  solves (\*\*), then  $x^\dagger$  and  $-x^\dagger$  are the only solutions of this operator equation.

Some more references:

- ▷ D. GERTH, B.H., S. BIRKHOLZ, S. KOKE AND G. STEINMEYER: Regularization of an autoconvolution problem in ultrashort laser pulse characterization. *Inverse Probl. Sci. Eng.* **22** (2014), pp. 245–266.
- ▷ S. W. ANZENGRUBER, S. BÜRGER, B.H. AND G. STEINMEYER: Variational regularization of complex deautoconvolution and phase retrieval in ultrashort laser pulse characterization. *Inverse Problems* **32** (2016), 035002 (27pp).

## Example 2: A problem in inverse option pricing

**Calibrating local volatility surfaces from market data** is an ill-posed nonlinear inverse problem in finance.

Consider the price process  $P(t)$  for an asset

$$\frac{dP(t)}{P(t)} = \mu dt + \sigma(t) dW(t) \quad (t \geq 0, P(0) > 0).$$

A **benchmark problem** for studying phenomena is the calibration of time-dependent volatilities  $\sigma(t)$ ,  $0 \leq t \leq T$ , from maturity-dependent option prices  $u(t)$ ,  $0 \leq t \leq T$ , of European call options with a fixed strike  $K > 0$ .

For parameters  $P > 0$ ,  $K > 0$ ,  $r \geq 0$ ,  $t \geq 0$  and  $s \geq 0$  we introduce the **Black-Scholes function** as

$$U_{BS}(P, K, r, t, s) := \begin{cases} P\Phi(d_1) - Ke^{-rt}\Phi(d_2) & (s > 0) \\ \max(P - Ke^{-rt}, 0) & (s = 0) \end{cases}$$

with

$$d_1 := \frac{\ln\left(\frac{P}{K}\right) + rt + \frac{s}{2}}{\sqrt{s}}, \quad d_2 := d_1 - \sqrt{s}$$

and the cumulative density function

$$\Phi(\xi) := \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\xi} e^{-\frac{\eta^2}{2}} d\eta.$$

of the standard normal distribution.

For

$$a(t) := \sigma^2(t) \quad \text{and} \quad S(t) = \int_0^t a(\tau) d\tau$$

the associated forward operator in  $(**)$  is here  $F : a \mapsto u$  with

$$[F(a)](t) := U_{BS}(P, K, r, t, S(t)) \quad (0 \leq t \leq T).$$

Hence, we have a composition  $F = N \circ J$  with the nonlinear **Nemytskii operator**  $[N(S)](t) := k(t, S(t))$  ( $0 \leq t \leq T$ ) for

$$k(t, v) = U_{BS}(P, K, r, t, v) \quad ((t, v) \in [0, T] \times [0, \infty)),$$

and with the linear **integral operator**

$$[Ja](t) := \int_0^t a(\tau) d\tau \quad (0 \leq t \leq T).$$

This calibration problem can be written as  $F(a) = u$  (\*\*).

It is split into an **ill-posed linear inner equation**

$$J a = S \quad (a \in D(F) \subset X, S \in Z) \quad (in)$$

and a **nonlinear outer equation**

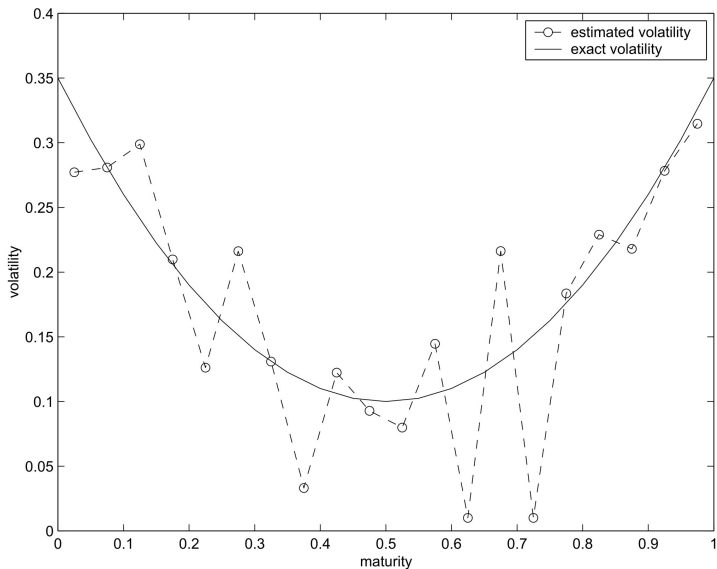
$$N(S) = u \quad (S \in Z, u \in Y), \quad (out)$$

where  $X, Y, Z$  are Banach spaces of real functions over  $[0, T]$ .

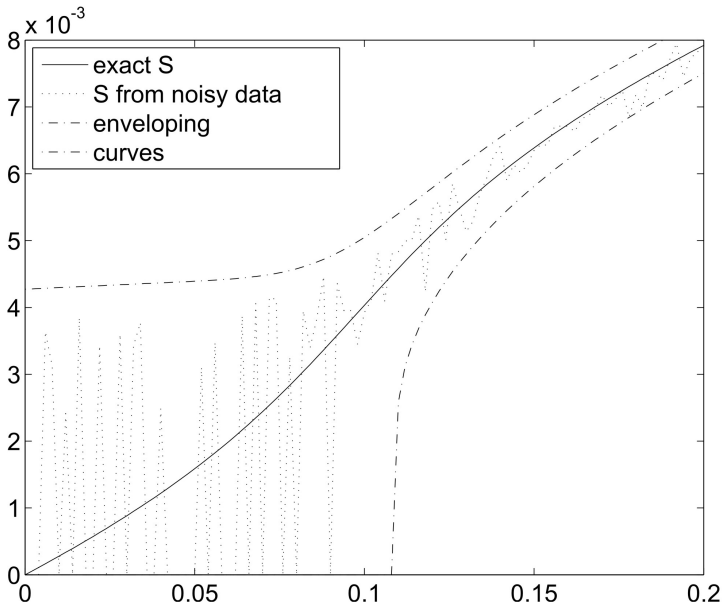
The composition problem (\*\*) is **locally ill-posed** everywhere.  
However, the character of the outer problem is not so clear.



## Least-squares solution of (\*\*) after discretization with 20 grid points

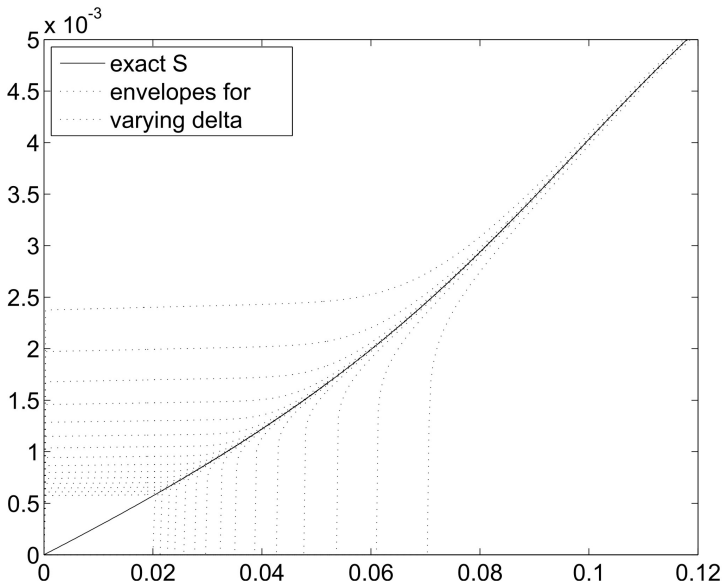


## Oscillations near $t = 0$ in solving the outer equation



Reduction of oscillation areas for  $\delta \rightarrow 0$ :

**Ill-conditioning** but not ill-posedness of the outer equation in  $C[0, T]$ .



## Some references:

- ▷ F. BLACK AND M. SCHOLES: The pricing of options and corporate liabilities. *J. Political Econom.* **81** (1973), pp. 637–654.
- ▷ I. BOUCHOUVEV AND V. ISAKOV: The inverse problem of option pricing. *Inverse Problems* **13** (1997), pp. L11–L17.
- ▷ T. HEIN AND B.H.: On the nature of ill-posedness of an inverse problem arising in option pricing. *Inverse Problems* **19** (2003), pp. 1319–1338.
- ▷ R. KRÄMER AND P. MATHÉ: Modulus of continuity of Nemytskii operators with application to the problem of option pricing. *J. Inverse Ill-Posed Probl.* **16** (2008), pp. 435–461.
- ▷ A. DE CEZARO, O. SCHERZER AND J. P. ZUBELLI: Convex regularization of local volatility models from option prices: convergence analysis and rates. *Nonlinear Anal.* **75** (2012), pp. 2398–2415.
- ▷ Y. F. SAPORITO, X. YANG, XU AND J. P. ZUBELLI: The calibration of stochastic local-volatility models: an inverse problem perspective. *Comput. Math. Appl.* **77** (2019), pp. 3054–3067.

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# Degree of ill-posedness for compositions with non-compact linear operators

We consider for Hilbert spaces  $X, Y, Z$  the ill-posed equation

$$Ax = y, \quad x \in X, \quad y \in Y, \quad (*)$$

with **compact composite linear forward** operator

$$A : X \xrightarrow{D} Z \xrightarrow{B} Y,$$

where  $A = B \circ D : X \rightarrow Y$  is a composition of the **compact** linear operator  $D$  with infinite dimensional range  $\mathcal{R}(D)$  and the bounded **non-compact** operator  $B$  with non-closed range  $\mathcal{R}(B) \neq \overline{\mathcal{R}(B)}^Y$ .

In the nomenclature of NASHED 1987, the inner problem

$$Dx = z,$$

is ill-posed of **type II** due to the compactness of  $D$ ,  
whereas the outer problem

$$Bz = y$$

is ill-posed of **type I**, since  $B$  is non-compact.

General open question:

What impact does the non-compact operator  $B$  with non-closed range have on the degree of ill-posedness of  $(*)$ ?

Nashed states that

“... an equation involving a bounded non-compact operator with non-closed range is **less ill-posed** than an equation with a compact operator with infinite-dimensional range.”

▷ M. Z. NASHED: A new approach to classification and regularization of ill-posed operator equations, In: Inverse and Ill-posed Problems Sankt Wolfgang, 1986 (Eds.: H. W. Engl and C. W. Groetsch), Academic Press, Boston, 1987, pp. 53–75.

Specific open question:

Can the non-compact operator  $B$  with non-closed range in  $A = B \circ D$  ‘destroy’ the degree of ill-posedness from  $D$ ?



In  $X = Y = Z = L^2(0, 1)$  we have, for the

**integration operator**  $[Jx](s) := \int_0^s x(t)dt$  and classes of

**multiplication operators**  $[Mx](t) := m(t)x(t)$  with multiplier functions  $m \in L^\infty(0, 1)$  possessing essential zeros, that

$$\sigma_i(M \circ J) \asymp \sigma_i(J) \asymp i^{-1} \quad (i \in \mathbb{N}).$$

The non-compact  $B = M$  **does not ‘destroy’** the singular value decay rate of  $D = J$  by the composition  $A = M \circ J$ .

## For that fact we refer to:

- ▷ M. FREITAG AND B.H.: Analytical and numerical studies on the influence of multiplication operators for the ill-posedness of inverse problems. *J. Inv. Ill-Posed Problems* **13** (2005), pp. 123-148.
- ▷ B.H. AND L. VON WOLFERSDORF: Some results and a conjecture on the degree of ill-posedness for integration operators with weights. *Inverse Problems* **21** (2005), pp. 427-433.
- ▷ B.H. AND L. VON WOLFERSDORF: A new result on the singular value asymptotics of integration operators with weights. *Journal of Integral Equations and Applications* **21** (2009), pp. 281-295.

For the compact operator  $A = B \circ D : X \rightarrow Y$  and  $D : X \rightarrow Z$  with non-closed ranges  $\mathcal{R}(A)$  and  $\mathcal{R}(D)$  we have upper bounds for the singular values of  $A$  as

$$\sigma_i(A) \leq \|B\|_{\mathcal{L}(Z,Y)} \sigma_i(D).$$

Lower bounds based on a conditional stability estimate are given as follows:

### Theorem 1 (cf. Thm. 2.1 of [HM22])

Suppose that there exists an index function  $\Psi : (0, \infty) \rightarrow (0, \infty)$  such that for  $0 < \delta \leq \|A\|_{\mathcal{L}(X,Y)}$  the conditional stability estimate

$$\sup\{\|Dx\|_Z : \|Ax\|_Y \leq \delta, \|x\|_X \leq 1\} \leq \Psi(\delta)$$

holds. Then we have

$$\Psi^{-1}(\sigma_i(D)) \leq \sigma_i(A) \quad (i = 1, 2, \dots).$$

▷ B.H. AND P. MATHÉ: The degree of ill-posedness of composite linear ill-posed problems with focus on the impact of the non-compact Hausdorff moment operator. *ETNA* **57** (2022), pp. 1–16.

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# The mystery of the Hausdorff moment operator in a composition with the compact integration operator

We recall the Hausdorff moment operator  $B^{(H)} : L^2(0, 1) \rightarrow \ell^2$

$$[B^{(H)}z]_j := \int_0^1 t^{j-1} z(t) dt \quad (j = 1, 2, \dots).$$

to apply it later in a composition  $A = B^{(H)} \circ J$  with the compact integration operator

$J : L^2(0, 1) \rightarrow L^2(0, 1)$  with  $[Jx](s) := \int_0^s x(t) dt$  ( $0 \leq s \leq 1$ ).

For the subsequent proposition and assertions on  $B^{(H)}$  see:

▷ D. GERTH, B.H., C. HOFMANN AND S. KINDERMANN: The Hausdorff moment problem in the light of ill-posedness of type I. *EJMCA* **9** (2021), pp. 57–87.

## Proposition (cf. Props. 3-5 of [GHHK21])

For the operator  $B^{(H)} : L^2(0, 1) \rightarrow \ell^2$  we have the properties:  $B^{(H)}$  is a bounded, injective and **non-compact** linear operator with  $\|B^{(H)}\|_{\mathcal{L}(L^2(0,1), \ell^2)} = \sqrt{\pi}$  and **non-closed range**  $\mathcal{R}(B^{(H)})$ .

The adjoint operator  $(B^{(H)})^* : \ell^2 \rightarrow L^2(0, 1)$  attains the form

$$[(B^{(H)})^* y](t) = \sum_{j=1}^{\infty} y_j t^{j-1} \quad (0 \leq t \leq 1).$$

We have  $B^{(H)} = \mathbb{L} Q$  with an isometry  $Q : L^2(0, 1) \rightarrow \ell^2$  and a lower triangular operator  $\mathbb{L} : \ell^2 \rightarrow \ell^2$  being the lower Cholesky factor of the infinite Hilbert matrix  $\mathbb{H} = \left( \frac{1}{i+j-1} \right)_{i,j=1}^{\infty} : \ell^2 \rightarrow \ell^2$ .

This means that  $\mathbb{L} \mathbb{L}^* = \mathbb{H} = B^{(H)}(B^{(H)})^*$ .

Isometry  $[Qx]_j = \langle x, L_j \rangle_{L^2(0,1)}$  for ONS of Legendre polynomials  $\{L_j\}_{j=1}^{\infty}$  with  $\text{span}(L_1, \dots, L_j) = \text{span}(1, t, \dots, t^{j-1})$  (Gram-Schmidt).

Now we consider  $(*)$  with the compact composition

$$A = B^{(H)} \circ J : L^2(0, 1) \rightarrow \ell^2$$

as forward operator.

### Proposition (cf. Thm. 3.1 of [HM22])

There is a positive constant  $C_0$  such that

$$\sup \{ \|Jx\|_{L^2(0,1)} : \|B^{(H)}(Jx)\|_{\ell^2} \leq \delta, \|x\|_{L^2(0,1)} \leq 1 \} \leq \frac{C_0}{\ln(1/\delta)}.$$

This proposition yields with Theorem 1 by setting

$X = Z = L^2(0, 1)$ ,  $Y = \ell^2$  and  $\Psi(\delta) = \frac{C_0}{\ln(1/\delta)}$  the following

### Corollary 1

There exists a positive constant  $\underline{C}$  such that

$$\exp(-\underline{C} i) \leq \sigma_i(B^{(H)} \circ J) \quad (i = 1, 2, \dots).$$

However, further detailed studies allow us to prove that  $B^{(H)}$  **has the power to ‘destroy’ the ill-posedness degree of  $J$ .**

**Theorem 2 (cf. Thm. 5.1 of [HM22])**

For the composite operator  $A = B^{(H)} \circ J$  there exists a positive constant  $C$  such that

$$\sigma_i(B^{(H)} \circ J) \leq \frac{C}{i^{3/2}} \quad (i \in \mathbb{N}).$$

Hence, there is also a positive constant  $K$  such that that

$$\sigma_i(B^{(H)} \circ J) / \sigma_i(J) \leq \frac{K}{i^{1/2}} \quad (i \in \mathbb{N}).$$

The non-compact Hausdorff moment operator  $B^{(H)}$  is able to **increase** in a composition **the degree of ill-posedness 1** of  $J$  at least by  $1/2$ . Thus,  $\sigma_i(B^{(H)} \circ J) \asymp \sigma_i(J)$  is **violated**.



As a consequence of Corollary 1 and Theorem 2 we have:

### Corollary 2

For the compact composite operator  $A = B^{(H)} \circ J$  there exist positive constants  $\underline{C}$  and  $\overline{C}$  such that

$$\exp(-\underline{C} i) \leq \sigma_i(A) \leq \frac{\overline{C}}{i^{3/2}} \quad (i = 1, 2, \dots).$$

The gap between lower and upper bounds for  $\sigma_i(A)$  is too large.

### Open question (Hausdorff mystery)

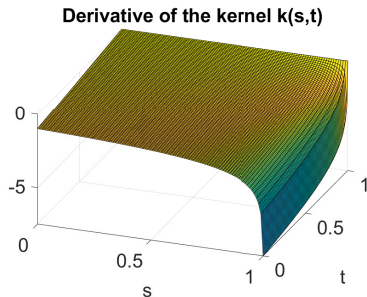
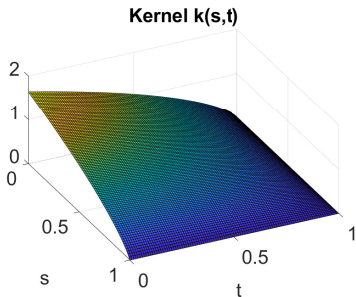
Is the linear operator equation  $(*)$  with forward operator  $A = B^{(H)} \circ J$  moderately or severely ill-posed?

▷ D. GERTH, B.H.: A note on open questions asked to analysis and numerics concerning the Hausdorff moment problem. *EJMCA* **10** (2022), pp. 40–50.

## Arguments pro moderate ill-posedness:

For the Hilbert-Schmidt operator  $A = B^{(H)} \circ J$  we have

$$[A^*Ax](s) = \int_0^1 k(s,t) x(t) dt \quad (0 \leq s \leq 1) \quad \text{with} \quad k(s,t) = \sum_{j=1}^{\infty} \frac{(1-s^j)(1-t^j)}{j^2}.$$



Kernel  $k$  is smooth, but partial derivative  $\frac{\partial k}{\partial s}$  has a pole at  $s = 1$ .

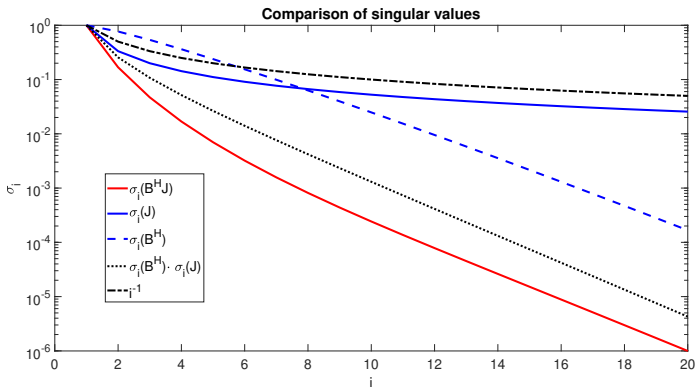
Limited kernel-smoothness seems to mismatch an exponential decay of  $\sigma_i(A)$  for  $A = B^{(H)} \circ J$ .

But the following open question should be answered:

### Open question (kernel smoothness and ill-posedness)

Under which conditions can an operator equation  $(*)$  with a Hilbert-Schmidt operator  $A$  mapping from  $L^2(0, 1)$  into an arbitrary Hilbert space  $Y$  with non-closed range  $\mathcal{R}(A)$  be severely (exponentially) ill-posed, provided that the kernel  $k \in C([0, 1] \times [0, 1])$  from  $A^*A : L^2(0, 1) \rightarrow L^2(0, 1)$  has limited smoothness, which means that  $k$  is not infinitely many continuously differentiable on the whole closed unit square?

## Arguments against moderate ill-posedness:



Semi-logarithmic plot of singular values of  $n \times n$ -matrices with  $n = 10^4$  supporting points representing **discretization matrices** of the operators  $A$ ,  $B^{(H)}$  and  $J$ . While numerically the singular values of  $J$  decay as suggested by the theory, the **singular values of  $A = B^{(H)} \circ J$  decay exponentially** in the numerical experiments.

Numerics indicates **severe ill-posedness** of  $A = B^{(H)} \circ J$ , but

▷ D. GERTH: A note on numerical singular values of compositions with non-compact operators. *ETNA* 57 (2022).

yields some arguments for the conjecture that  
**an exponential decay of matrix singular values is possible even if the singular values of the infinite dimensional operator  $A : L^2(0, 1) \rightarrow \ell^2$  decay slowly.**

We consider the  $n \times n$ -matrices  $\mathbb{J}_n, \mathbb{B}_n^{(H)}$  and  $\mathbb{A}_n$  as discretized versions of the operators  $J, B^{(H)}$  and  $A = B^{(H)} \circ J$ , calculated with  $n$  supporting points over the interval  $[0, 1]$  and with  $n$  moments of the truncated Hausdorff moment operator.

$\mathbb{H}_n = \left( \frac{1}{i+j-1} \right)_{i,j=1}^n$  :  $n$ -dimensional segment of Hilbert matrix  $\mathbb{H}$ .

$$1 \leq \sigma_1(\mathbb{H}_n) \leq \pi = \lim_{n \rightarrow \infty} \sigma_1(\mathbb{H}_n), \quad \sigma_n(\mathbb{H}_n) \approx \hat{C} \exp(-3.526n).$$

$\mathbb{B}_n^{(H)}$  constructed such that  $\sigma_i(\mathbb{B}_n^{(H)}) = (\sigma_i(\mathbb{H}_n))^{1/2} \quad (i=1,2,\dots,n)$ .

Owing to [Beckermann19, formula (4.8)] we have that

$$\sigma_i(\mathbb{B}_n^{(H)}) \leq 2 [\varphi(n)]^{i-1} (\sigma_1(\mathbb{H}_n))^{1/2} \quad (i=1,2,\dots,n-1), \quad (+)$$

$$\text{with factor } 0 < \varphi(n) = \exp\left(-\frac{\pi^2}{2 \ln(8n-4)}\right) < 1$$

growing very slowly to 1 as  $n \rightarrow \infty$  :  $1 - \varphi(n) \sim 1/\ln(n)$ .

$n$	$i = 2$	$i = 4$	$i = 10$	$i = 51$
$10^2$	0.4777	0.1091	0.0013	$9.1932 \cdot 10^{-17}$
$10^3$	0.5774	0.1926	0.0071	$1.1920 \cdot 10^{-12}$
$10^4$	0.6459	0.2695	0.0196	$3.2240 \cdot 10^{-10}$
$10^6$	0.7331	0.3940	0.0612	$1.8129 \cdot 10^{-7}$
$10^9$	0.8054	0.5224	0.1426	$1.9982 \cdot 10^{-5}$

Values of occurring multiplier  $\varphi(n)^{i-1}$  in (+)

We conjecture that (+) is approximately an equation if  $n \gg i$ .

For  $n$  fixed: Exponential decay  $\sigma_i(\mathbb{B}_n^{(H)}) \sim \exp(-K i)$  with  $K = K(n) > 0$ .

▷ B. BECKERMANN AND A. TOWNSEND: Bounds on the singular values of matrices with displacement structure. *SIAM Review* **61** (2019), pp. 319–344

We have  $\sigma_{2i}(\mathbb{A}_n) \leq \sigma_i(\mathbb{B}_n^{(H)}) \sigma_i(\mathbb{J}_n)$ .

If  $n$  is small or medium in size:

$\sigma_i(\mathbb{A}_n)$  dominated by  $\sigma_i(\mathbb{B}_n^{(H)}) \sim \exp(-K(n) i)$

If  $n$  is very large and  $\varphi(n) \approx 1$ :

$\sigma_i(\mathbb{A}_n)$  more dominated by  $\sigma_i(\mathbb{J}_n) \sim 1/i$ .

This yields some rough explanation for the contradiction.

**Is numerics reaching its limits here to evaluate the degree of ill-posedness for the infinite dimensional problem?**

However, by now there is no final unveiling of this mystery!