

# Forecasting Future Values From Time Series Data

**Perspective:** Seminar thesis, Bachelor, Master's thesis

**Writing hints:** <https://www.overleaf.com/read/hdpgkxgjkbgw>

## Preliminaries

Consider a random variable (random vector)  $X \in \mathbb{R}^d$  with density  $f_X$ ,

$$f_X(x) dx = P(X \in dx), \quad x \in \mathbb{R}^d.$$

The Rosenblatt–Parzen kernel density estimator for the density function  $f_X$  is

$$\hat{f}_n(x) := \frac{1}{n} \sum_{i=1}^n k_h(x - X_i), \quad x \in \mathbb{R}^d,$$

where  $X_i, i = 1, \dots, n$ , are independent observations of  $X$ . The kernel  $k: \mathbb{R}^d \rightarrow \mathbb{R}$  is non-negative ( $k(x) \geq 0$  for all  $x \in \mathbb{R}^d$ ) and satisfies  $\int_{\mathbb{R}^d} k(x_1, \dots, x_d) dx_1 \dots dx_d = 1$ .<sup>1</sup> For a strictly positive definite bandwidth matrix  $H$ , the kernel with bandwidth is

$$k_H(x) := \frac{1}{|\det H|} k(H^{-1}x).$$

Most often,  $H = \begin{pmatrix} h_1 & 0 & \ddots \\ 0 & \ddots & 0 \\ \ddots & 0 & h_d \end{pmatrix}$  with the scalar  $h := h_1 = \dots = h_d$  termed the *bandwidth*. A value of the bandwidth  $h$  too close to zero leads to *overfitting*, larger values for  $\lambda$  lead to *oversmoothing* (underfitting).

The conditional density is

$$f(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}, \quad x \in \mathbb{R}^d, y \in \mathbb{R}^\ell, \quad (1)$$

where  $f_{X,Y}(x,y) dx dy = P(X \in dx, Y \in dy)$  is the joint density of the random vector  $(X, Y) \in \mathbb{R}^d \times \mathbb{R}^\ell$  (which we assume to exist here for convenience).

<sup>1</sup>Popular kernels include the sigmoid kernel  $k(x) := \frac{2}{\pi} \frac{1}{e^{\|x\|} + e^{-\|x\|}}$ , which nowhere vanishes and thus is often better suited than the Epanechnikov kernel in the present context.

Employing two kernels  $k: \mathbb{R}^d \rightarrow \mathbb{R}$  and  $k: \mathbb{R}^\ell \rightarrow \mathbb{R}$ , the estimator for the conditional density (1) is

$$\hat{f}_n(x|y) := \sum_{i=1}^n k_h(x - X_i) \cdot \underbrace{\frac{k_h(y - Y_i)}{\sum_{j=1}^n k_h(y - Y_j)}}_{=: w_i(y)}, \quad (2)$$

where  $(X_i, Y_i), i = 1, \dots, n$ , are independent observations of the pair  $(X, Y)$ ; the weights  $w_i(y)$  are non-negative and  $\sum_{i=1}^n w_i(y) = 1$ .

## Samples from the conditional distribution

To obtain random samples from the conditional distribution  $f(\cdot|y)$  in (2) for known  $y$  recall that  $\sum_{i=1}^n w_i(y) = 1$ . We employ the *composition method*: for a uniform  $U \in [0, 1]$ , find the index  $i^* \in \{1, \dots, n\}$  such that

$$w_1(y) + \dots + w_{i^*-1}(y) < U \leq w_1(y) + \dots + w_{i^*}(y),$$

and note that the random index  $i^*$  satisfies  $P(i^* = i) = w_i(y), i = 1, \dots, n$ . Then

$$X_{i^*} + h \cdot \varepsilon \sim \hat{f}_n(\cdot|y), \quad (3)$$

that is,  $X_{i^*} + h \cdot \varepsilon$  is random with density  $\hat{f}_n(\cdot|y)$ , provided that  $\varepsilon$  is chosen randomly from the distribution with density  $k$ , the random index  $i^*$  is as above, and  $h > 0$  is the scalar bandwidth.

## Application to Non-Linear Time Series

Suppose a stationary time series  $(X_t), X_t \in \mathbb{R}$ , with lag  $\ell$  has conditional density

$$f(x_{\ell+1}|x_1, \dots, x_\ell). \quad (4)$$

Based on observing the trajectory

$$X_{2-\ell}, \dots, X_{n+1} \quad (5)$$

of the time series, the estimator for the conditional density (4) is

$$\hat{f}_n(x_{\ell+1}|x_1, \dots, x_\ell) = \sum_{i=1}^n k_h(x_{\ell+1} - X_{i+1}) \cdot \underbrace{\frac{k_h(x_1 - X_{i+1-\ell}) \cdot \dots \cdot k_h(x_\ell - X_i)}{\sum_{j=1}^n k_h(x_1 - X_{j+1-\ell}) \cdot \dots \cdot k_h(x_\ell - X_j)}}_{w_i(x_1, \dots, x_\ell)}. \quad (6)$$

## Task: Forecasting with Delayed Embedding of Dimension $\ell$

Suppose observations  $X_1, \dots, X_\ell$  are given. We may sample  $X_{\ell+1}$ , the next observation of the time series, by employing (3).

1. Discuss and implement the relations (1)–(6) for a suitable, oscillating time series with  $(X_t)$  (for example the *nottem* time series data, which is included in the statistical programming language *R*).
2. **Recursive multistep forecasting and sliding window:** For some chosen, initial starting values  $(\hat{X}_1, \dots, \hat{X}_\ell)$ , extend this time series by getting new samples from (6) with (3) and *plot* the realization  $\hat{X}_1, \hat{X}_2, \dots, \hat{X}_\ell, \dots, \hat{X}_n, \dots, \hat{X}_N$  with some  $N \gg \ell$ .
3. Adjust the kernel and the scalar bandwidth  $h$  so that the time series  $\hat{X}$  *visually* matches the initial observations (5) of  $X$ .

Bonne chance!