

# Numerical analysis of a quasilinear Neumann equation under minimal regularity of the data

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We consider the finite element approximation of the following quasilinear Neumann problem

$$\begin{cases} -\operatorname{div}[a(x, u(x))\nabla u(x)] + f(x, u(x)) = 0 & \text{in } \Omega, \\ a(x, u(x))\partial_\nu u(x) = g(x) & \text{on } \Gamma. \end{cases} \quad (1)$$

The consideration is restricted to polygonal domains of dimension two and polyhedral domains of dimension three. For numerical purposes we discretize  $\Omega$  by a regular triangulation and the mesh on  $\Gamma$  is induced by that on  $\Omega$ . We approximate the PDE (1) by linear and continuous finite elements.

In spite that  $f$  is considered monotone nondecreasing with respect to  $u$ , the above equation is not monotone because of the dependence of the coefficients of the operator with respect to the function  $u$ . This lack of monotonicity causes the main difficulty in the numerical analysis of the above equation: the uniqueness of a solution of the discretized version of (1) is an open question, even though (1) has a unique solution. This non-monotonicity also complicates the discussion of any linearization of (1) which is needed, in particular, to apply the well-known Aubin-Nitsche trick for optimal  $L^2$  error estimates for the approximation of (1).

In contrast to well-known results in the literature, the  $C^2$  regularity and the boundedness of the coefficient  $a$  are not necessary to derive error estimates. In most of the cases it suffices to require only a local Lipschitz property of  $a$ .

The boundary datum  $g$  is supposed to be in  $L^s(\Gamma)$  ( $s \geq 2$ ), therefore the regularity of the solution  $u$  of (1) cannot be  $H^2(\Omega)$  but only  $H^{3/2}(\Omega)$ . Because of this lower regularity of  $u$ , the analysis becomes more difficult than in the regular case.

The assumption on  $\Omega$  introduces a new difficulty: the regularity of elliptic equations in corner domains needs special care. For this reason, we distinguish two cases: whether  $\Omega$  is convex or not. These two different situations yield different order of convergence for the discretization of equation (1) in the  $L^2(\Omega)$  norm.

The main aims of this talk are twofold. First, error estimates in different function spaces are presented and second the issue of uniqueness of a solution to the approximate discrete equation is addressed.

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