

# An approximation theorem of Runge type for kernels of certain non-elliptic partial differential operators

Thomas Kalmes  
TU Chemnitz

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## Introduction

## Runge's Approximation Theorem

For  $X_1 \subseteq X_2 \subseteq \mathbb{C}$  open the following are equivalent.

- i) For every  $g \in \mathcal{H}(X_1)$ , for every compact  $K \subseteq X_1$ , and for every  $\varepsilon > 0$  there is  $f \in \mathcal{H}(X_2)$  such that

$$\varepsilon > \sup_{z \in K} |f(z) - g(z)| =: \|f - g\|_{0,K},$$

i.e.  $r : \mathcal{H}(X_2) \rightarrow \mathcal{H}(X_1), f \mapsto f|_{X_1}$  has dense range when  $\mathcal{H}(X_1)$  is equipped with the compact-open topology.

- ii)  $X_2$  does not contain a compact connected component of  $\mathbb{C} \setminus X_1$ .

For  $X \subseteq \mathbb{C} = \mathbb{R}^2$  we have  $\mathcal{H}(X) = \{f \in C^\infty(X); \frac{1}{2}(\partial_1 + i\partial_2)f = 0\}$ .

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$X \subseteq \mathbb{R}^d$  open,  $\mathcal{E}(X) := C^\infty(X)$  equipped with its natural locally convex topology which is generated by the seminorms

$$\forall K \subseteq X \text{ compact}, l \in \mathbb{N}_0 : \|f\|_{l,K} := \sup_{|\alpha| \leq l} \sup_{x \in K} |\partial^\alpha f(x)| \quad (f \in C^\infty(X))$$

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$$\mathcal{E}_P(X) := \{f \in C^\infty(X); P(\partial)f = 0 \text{ in } X\}.$$

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$P$  hypoelliptic  $:\Leftrightarrow \forall X$  open  $\forall u \in \mathcal{D}'(X) : (P(\partial)u = 0 \Rightarrow u \in C^\infty(X))$

Then  $\mathcal{E}_P(X) = \mathcal{D}'_P(X)$  as locally convex spaces and therefore: topology of  $\mathcal{E}_P(X)$  is generated by the seminorms  $\{\|\cdot\|_{0,K}; K \subseteq X \text{ compact}\}$ .

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$P(\xi) = \sum_{|\alpha| \leq m} a_\alpha \xi^\alpha$  elliptic  $:\Leftrightarrow \forall \xi \in \mathbb{R}^d \setminus \{0\} : 0 \neq P_m(\xi) := \sum_{|\alpha|=m} a_\alpha \xi^\alpha$

$P$  elliptic  $\Rightarrow P$  hypoelliptic

## Lax-Malgrange Theorem ([4], [5])

For  $X_1 \subseteq X_2 \subseteq \mathbb{R}^d$  open and  $P$  elliptic the following are equivalent.

- i) The restriction map  $r_{\mathcal{E}} : \mathcal{E}_P(X_2) \rightarrow \mathcal{E}_P(X_1), f \mapsto f|_{X_1}$  has dense range.
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Objective: Given  $P$  non-constant, find conditions ensuring that the restriction map

$$r_{\mathcal{E}} : \mathcal{E}_P(X_2) \rightarrow \mathcal{E}_P(X_1), f \mapsto f|_{X_1}$$

resp.

$$r_{\mathcal{D}'} : \mathcal{D}'_P(X_2) \rightarrow \mathcal{D}'_P(X_1), u \mapsto u|_{X_1}$$

has dense range.

## A general approximation theorem for kernels of differential operators

Given  $P \neq 0$ ,  $X \subseteq \mathbb{R}^d$  open. Recall that the following are equivalent

- i)  $P(\partial) : \mathcal{E}(X) \rightarrow \mathcal{E}(X)$  is surjective.
- ii)  $X$  is  $P$ -convex for supports, i.e.

$$\forall u \in \mathcal{E}'(X) : \text{dist}(\text{supp } \check{P}(\partial)u, \mathbb{R}^d \setminus X) = \text{dist}(\text{supp } u, \mathbb{R}^d \setminus X)$$

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If  $P$  is elliptic, every open  $X \subseteq \mathbb{R}^d$  is  $P$ -convex for supports.

$f : X \rightarrow \mathbb{R}$  satisfies the minimum principle in a closed subset  $H$  of  $\mathbb{R}^d$  if for every compact set  $K \subseteq H \cap X$  we have

$$\inf_{x \in K} f(x) = \inf_{\partial_H K} f(x),$$

where  $\partial_H K$  denotes the boundary of  $K$  in  $H$ .

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We set  $d_X : X \rightarrow \mathbb{R}, x \mapsto \text{dist}(x, X^c)$ , the *boundary distance* of  $X$ .

If  $X$  is  $P$ -convex for supports then  $d_X$  satisfies minimum principle in every characteristic hyperplane  $H$  for  $P$ , i.e.

$$H = \{\xi \in \mathbb{R}^d; \langle N, \xi \rangle = \beta\}, \beta \in \mathbb{R}, N \in \mathbb{R}^d, |N| = 1, P_m(N) = 0,$$

where  $P(\xi) = \sum_{|\alpha| \leq m} a_\alpha \xi^\alpha$ .

## Theorem ([2, Theorem 4])

Given  $P$  non-constant,  $X_1 \subseteq X_2 \subseteq \mathbb{R}^d$  open,  $X_2$   $P$ -convex for supports. Tfae.

- i)  $X_1$  is  $P$ -convex for supports and  $r_{\mathcal{D}'} : \mathcal{D}'_P(X_2) \rightarrow \mathcal{D}'_P(X_1), u \mapsto u|_{X_1}$  has dense range.
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- iii) For every  $u \in \mathcal{E}'(X_2)$  with  $\text{supp } \check{P}(\partial)u \subseteq X_1$  it holds  $\text{supp } u \subseteq X_1$ .
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For elliptic  $P$  the above yields Lax-Malgrange:

- $\exists C$  compact connected component of  $\mathbb{R}^d \setminus X_1, C \subseteq X_2$   
 $\Rightarrow \exists \psi \in \mathcal{D}(X_1 \cup C); \psi = 1$  in neighborhood of  $C$  so for  $\zeta \in \mathbb{C}^d, \check{P}(\zeta) = 0$   
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- Assume, no compact connected component of  $\mathbb{R}^d \setminus X_1$  is contained in  $X_2$ .  
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By hypothesis, every connected component of  $\mathbb{R}^d \setminus X_1$  intersects  $\partial_\infty X_2$   
(boundary of  $X_2$  in the one-point compactification of  $\mathbb{R}^d$ ) and  $\varphi = 0$  in a neighborhood of  $\partial_\infty X_2$



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Hence, a representation of  $\mathcal{E}_P(X_j)'$ , resp.  $\mathcal{D}'_P(X_j)'$ , will be useful for the proof.

Representation of  $\mathcal{E}_P(X)'$  for  $X$  being  $P$ -convex for supports due to Grothendieck (see [1]):  $E$  be a fixed fundamental solution for  $\check{P}(\partial)$ ,  $K \subseteq \mathbb{R}^d$  compact

- $u \in \mathcal{D}'_P(\mathbb{R}^d \setminus K)$  *regular at infinity w.r.t.  $E$*  iff for one (then every)  $\psi \in \mathcal{E}(\mathbb{R}^d)$  with  $\text{supp } \psi \cap K = \emptyset$  and  $\text{supp } (1 - \psi)$  compact:

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Then

$$\Phi_X : R_{\check{P}}(X^c)_{/\sim} \rightarrow \mathcal{E}_P(X)', \langle \Phi_X([u]_{\sim}), f \rangle := \langle \check{P}(\partial)(\psi u), f \rangle$$

is a well-defined (topological) isomorphism where additionally  $\text{supp } (1 - \psi) \subseteq X$



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$$\exists L \subseteq X_2 \text{ compact} : \psi u \in \mathcal{E}'(L), \check{P}(\partial)(\psi u) \in \mathcal{E}'(X_1) \xrightarrow{\text{iii)}} \psi u \in \mathcal{E}'(X_1) \quad \odot$$

## A Runge type approximation theorem for certain non-elliptic differential operators

We consider the class of differential operators  $P(\partial)$  for which

$\{\xi \in \mathbb{R}^d; P_m(\xi) = 0\}$  is a one-dimensional subspace of  $\mathbb{R}^d$

which contains e.g.

- $P(\partial) = i \frac{\partial}{\partial t} + \Delta_x$  with  $(x, t) = (x_1, \dots, x_{d-1}, t) \in \mathbb{R}^d$  (time-dependent free Schrödinger operator),
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### Theorem ([3, Corollary 5])

Let  $P$  be such that  $\{\xi \in \mathbb{R}^d; P_m(\xi) = 0\}$  is a one-dimensional subspace, let  $X \subseteq \mathbb{R}^d$  be open. Tfae

- $X$  is  $P$ -convex for supports.
- $d_X$  satisfies the minimum principle in every characteristic hyperplane.

## Runge type approximation theorem ([2, Theorem 1])

Let  $P$  be such that  $\{\xi \in \mathbb{R}^d; P_m(\xi) = 0\}$  is a one-dimensional subspace, let  $X_1 \subseteq X_2 \subseteq \mathbb{R}^d$  be open and  $P$ -convex for supports.

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$$\check{P}(\partial)\varphi_1, \check{P}(\partial)\varphi \in \mathcal{D}(X_1) \Rightarrow \check{P}(\partial)\varphi_2 = \check{P}(\partial)(\varphi - \varphi_1) \in \mathcal{D}(X_2 \setminus X_1) \cap \mathcal{D}(X_1) = \{0\}$$

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$$\exists \varepsilon > 0 : \varphi|_{B(\alpha(T), \varepsilon)} = 0, \check{P}(\partial)\varphi|_{\alpha([0, T]) + B(0, \varepsilon)} = 0.$$

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$\alpha 4)$  and a result due to Hörmander now imply  $0 = \varphi|_{B(\alpha(0), \varepsilon)} = \varphi|_{B(x_0, \varepsilon)}$ .



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Let  $P$  be such that  $\{\xi \in \mathbb{R}^d; P_m(\xi) = 0\}$  is a one-dimensional subspace, let  $X_1 \subseteq X_2 \subseteq \mathbb{R}^d$  be open and  $P$ -convex for supports.

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## Corollary ([2, Corollary 3])






Let  $Q \in \mathbb{C}[X_1, \dots, X_{d-1}]$  be elliptic of degree  $\geq 2$ ,  $P(\partial) = \frac{\partial}{\partial x_d} - Q(\partial)$ .

Moreover, let  $Y_1 \subseteq Y_2 \subseteq \mathbb{R}^{d-1}$ ,  $I \subseteq \mathbb{R}$  be open.

Then  $Y_1 \times I$  and  $Y_2 \times I$  are  $P$ -convex for supports.

Additionally, if  $Y_2$  does not contain any compact connected component of  $\mathbb{R}^{d-1} \setminus Y_1$  then  $r_{\mathcal{E}} : \mathcal{E}_P(Y_2 \times I) \rightarrow \mathcal{E}_P(Y_1 \times I)$  has dense range.

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