

Tensor Calculations

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What is a Tensor?

Tensors are used to describe linear interactions between physical properties.

rank zero tensor scalar property, e.g. temperature

rank one tensor directional dependent property, e.g. wave velocity

rank two tensors relationship between two vector fields, e.g. stress, strain, conductivity

rank three tensor relationship between a one and a two rank tensor, e.g. piezoelectricity

rank four tensor relationship between two two rank tensor, e.g. elasticity,

A tensor T of rank $s + t$ maps a tensor A of rank s onto a tensor B of rank t by the formula

$$B_{k_1, \dots, k_t} = T_{k_1, k_2, \dots, k_t, j_1, \dots, j_s} A_{j_1, \dots, j_s}$$

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A Simple Example

```
M = [[1.45  0.00  0.19];...
      [0.00  2.11  0.00];...
      [0.19  0.00  1.79]];
```

```
sigma = stressTensor(M, 'unit', 'MPa');
```

```
sigma = stressTensor (show methods, plot)
```

```
unit: MPa
```

```
rank: 2 (3 x 3)
```

```
1.45    0  0.19
```

```
  0  2.11    0
```

```
0.19    0  1.79
```

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      [0.19  0.00  1.79]];
```

```
sigma = stressTensor(M, 'unit', 'MPa');
```

```
n = vector3d.X % normal direction
```

```
n = vector3d (show methods, plot)
size: 1 x 1
x y z
1 0 0
```

A Simple Example

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M = [[1.45  0.00  0.19];...
      [0.00  2.11  0.00];...
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the stress vector $T^{\vec{n}}$ of plane $\vec{n} = \{1, 0, 0\}$, is computed by $T_j^{\vec{n}} = \sigma_{ij}\vec{n}_i$.

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```

the stress vector $T^{\vec{n}}$ of plane $\vec{n} = \{1, 0, 0\}$, is computed by $T_j^{\vec{n}} = \sigma_{ij}\vec{n}_i$.

```
T = EinsteinSum(sigma, [-1 1], n, -1)
```

```
T = tensor (show methods, plot)
```

```
unit: MPa
```

```
rank: 1 (3)
```

```
1.45
```

```
0
```

```
0.19
```

Einstein Summation

The scalar magnitudes of the normal stress σ_N and the shear stress σ_S are given as

$$\sigma_N = T_i^{\vec{n}} \vec{n}_i = \sigma_{ij} \vec{n}_i \vec{n}_j \quad \text{and} \quad \sigma_S = \sqrt{T_i^{\vec{n}} T_i^{\vec{n}} - \sigma_N^2}.$$

```
sigmaN = double(EinsteinSum(T, -1, n, -1))
sigmaS = sqrt(double(EinsteinSum(T, -1, T, -1))...
              - sigmaN^2)
```

```
sigmaN =
    1.4500

sigmaS =
    0.1900
```

Einstein Summation

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```
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    1.4500

sigmaS =
    0.1900
```

Visualization

For a second order tensor σ_{ij} its directional magnitude $R(\vec{x})$ is defined as

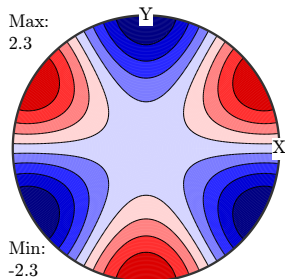
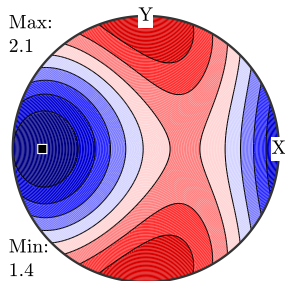
$$R(\vec{x}) = \sigma_{ij} \vec{x}_i \vec{x}_j.$$

```
R = EinsteinSum(sigma, [-1 -2], ...
  x, -1, x, -2)
```

```
R = directionalMagnitude(sigma)
```

```
[value, pos] = min(R)
```

```
plot(sigma . directionalMagnitude)
annotate(pos)
plot(sigma, 'minmax')
mteColorMap blue2red
```



Visualization

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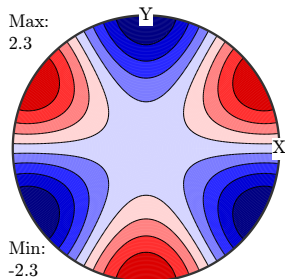
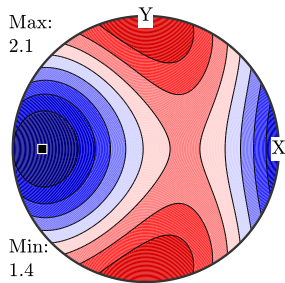
$$R(\vec{x}) = \sigma_{ij} \vec{x}_i \vec{x}_j.$$

```
R = EinsteinSum (sigma , [-1 -2] , ...
  x , -1 , x , -2)
```

```
R = directionalMagnitude (sigma)
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plot (sigma . directionalMagnitude)
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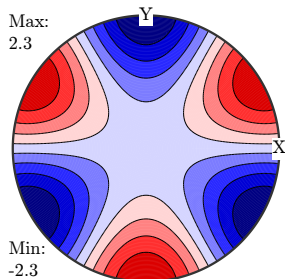
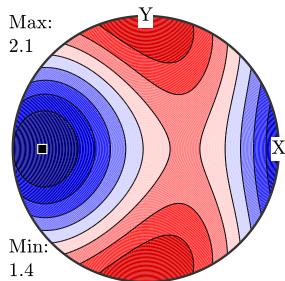
```
R = EinsteinSum (sigma , [ -1  -2 ] , ...
  x , -1 , x , -2)
```

```
R = directionalMagnitude (sigma , x)
```

```
R = directionalMagnitude (sigma )
```

```
[value , pos] = min(R)
```

```
plot (sigma . directionalMagnitude)
annotate (pos)
plot (sigma , 'minmax')
```



Visualization

For a second order tensor σ_{ij} its directional magnitude $R(\vec{x})$ is defined as

$$R(\vec{x}) = \sigma_{ij} \vec{x}_i \vec{x}_j.$$

```
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x, -1, x, -2)
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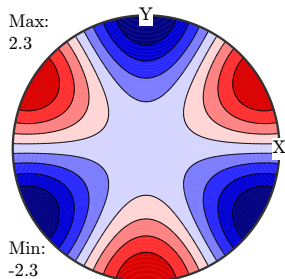
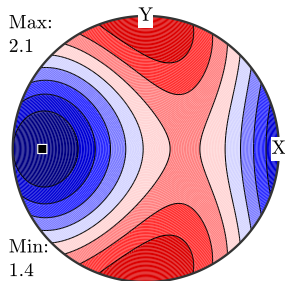
```
R = directionalMagnitude(sigma)
```

```
R = S2FunHarmonic (show methods, plot)
bandwidth: 2
antipodal: true
```

```
[value, pos] = min(R)
```

```
plot(sigma.directionalMagnitude)
annotate(pos)
```

```
plot(sigma, 'minmax')
```



Visualization

For a second order tensor σ_{ij} its directional magnitude $R(\vec{x})$ is defined as

$$R(\vec{x}) = \sigma_{ij} \vec{x}_i \vec{x}_j.$$

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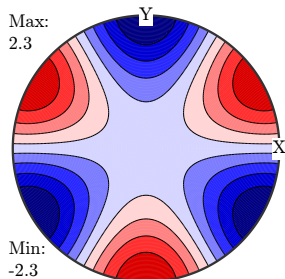
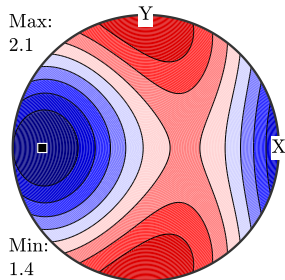
```
R = directionalMagnitude (sigma)
```

```
[value , pos] = min(R)
```

```
value =
  1.3652
```

```
pos = vector3d
  size: 1 x 1
```

	x	y	z
	-0.918733	0	0.394879



Visualization

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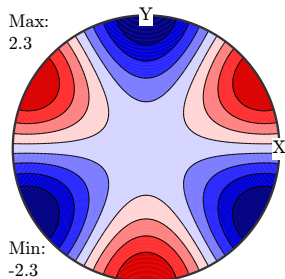
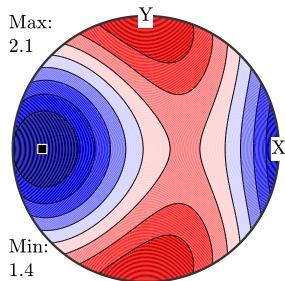
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R = directionalMagnitude (sigma)
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plot (sigma . directionalMagnitude)
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```



Field Tensors vs. Matter Tensors

field tensors:

- in specimen coordinates
- describe applied forces like: stress, electric field

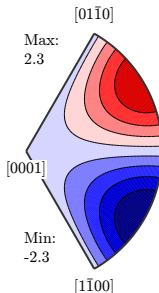
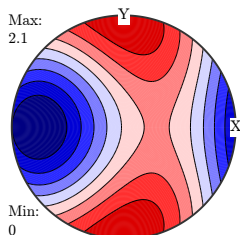
$\sigma = \text{stressTensor}(M)$;

matter tensors:

- in crystal coordinates
- describe physical properties like: electrical or thermal conductivity, magnetic permeability

$CS = \text{loadCif}('Quartz')$

$P = \text{piezoElectricityTensor}(M, CS)$



Field Tensors vs. Matter Tensors

field tensors:

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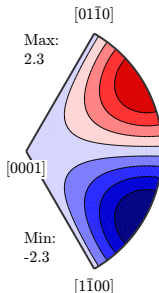
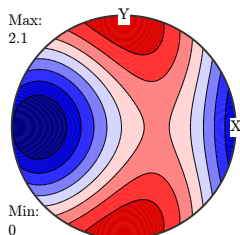
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matter tensors:

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$CS = \text{loadCif}('Quartz')$

$P = \text{piezoElectricityTensor}(M, CS)$



Rotating Tensors

Consider the piezoelectricity tensor

$P = \text{piezoElectricityTensor}(M, CS)$

```

P = piezoElectricityTensor (show methods, plot)
unit          : C/N
rank          : 3 (3 x 3 x 3)
mineral       : Quartz (321, X||a*, Y||b, Z||c)

tensor in compact matrix form:
  0      0      0 -0.67      0      4.6
  2.3   -2.3     0      0     0.67     0
  0      0      0      0      0      0

```

Remember orientations transforms crystal into specimen coordinates

```

ori = orientation( 'Euler', 10*degree, 20*degree, 0, CS)
ori * P

```

Contrary, an inverse orientation transforms specimen coordinates into crystal coordinates.

```

inv(ori) * sigma

```

Rotating Tensors

Consider the piezoelectricity tensor

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P=piezoElectricityTensor(M,CS)
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```
ans = piezoElectricityTensor (show methods, plot)
  unit          : C/N
  rank          : 3 (3 x 3 x 3)

  tensor in compact matrix form:
  -1.08  1.25 -0.17 -0.01  1.47  3.72
   1.92 -1.63 -0.29 -1.29  1.10  1.86
   0.76 -0.66 -0.09 -0.46  0.30  0.43
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inv(ori) * sigma
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```
ans = stressTensor (show methods, plot)
unit      : MPa
rank      : 2 (3 x 3)
mineral   : Quartz (321, X||a*, Y||b, Z||c)

1.47  0.17  0.14
0.17  2.03 -0.12
0.14 -0.12  1.85
```

Average Tensors

The average tensorial property of a specimen is the mean of matter tensors rotated according to each grain orientation o_m , $m = 1, \dots, M$.

The Voigt and the Reuss averages of a tensor T are defines as

$$\langle T \rangle^{\text{Voigt}} = \sum_{m=1}^M o_m \cdot T, \quad \langle T \rangle^{\text{Reuss}} = \left[\sum_{m=1}^M o_m \cdot T^{-1} \right]^{-1}.$$

For EBSD data this is computed by

```
[TVoigt, TReus, THill] = calcTensor(ebsd, T)
```

and for an ODF by

```
[TVoigt, TReus, THill] = calcTensor(odf, T)
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For EBSD data this is computed by

$$[\text{TVoigt}, \text{TReus}, \text{THill}] = \text{calcTensor}(\text{ebsd}, T)$$

and for an ODF by

$$[\text{TVoigt}, \text{TReus}, \text{THill}] = \text{calcTensor}(\text{odf}, T)$$

Elastic Deformation

Import some stiffness tensor

```
cs = loadCIF('Nickel')
C = stiffnessTensor.load(...
    'IN739LC.GPa', cs)
```

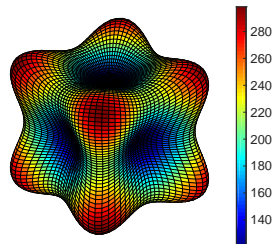
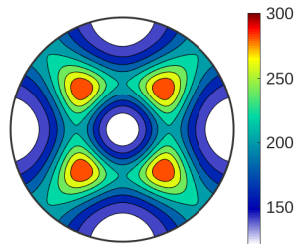
```
C = stiffnessTensor (show methods)
unit : GPa
rank : 4 (3 x 3 x 3 x 3)
mineral: Ni (432)

tensor in Voigt matrix representation:
235.16  147.67  147.67    0    0    0
147.67  235.16  147.67    0    0    0
147.67  147.67  235.16    0    0    0
    0    0    0  122.53    0    0
    0    0    0    0  122.53    0
    0    0    0    0    0  122.53
```

The inverse of the stiffness is the compliance

```
S = inv(C)
```

Consider uniaxial stress σ



Elastic Deformation

Import some stiffness tensor

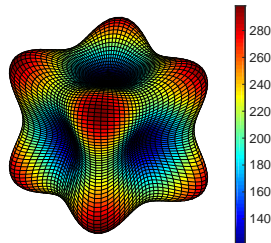
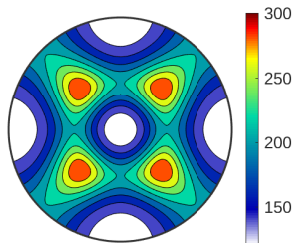
```
cs = loadCIF('Nickel')
C = stiffnessTensor.load(...
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```

The inverse of the stiffness is the compliance

```
S = inv(C)
```

```
S = complianceTensor
unit           : 1 / GPa
rank           : 4 (3 x 3 x 3 x 3)
doubleConvention: true
mineral        : Ni (432)

tensor in Voigt matrix represent.: *10^-4
82.48  -31.82  -31.82   0   0   0
-31.82  82.48  -31.82   0   0   0
-31.82  -31.82  82.48   0   0   0
  0   0   0  81.61   0   0
  0   0   0   0  81.61   0
  0   0   0   0   0  81.61
```



Consider uniaxial stress σ

Elastic Deformation

Import some stiffness tensor

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Consider uniaxial stress σ

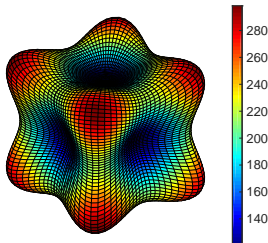
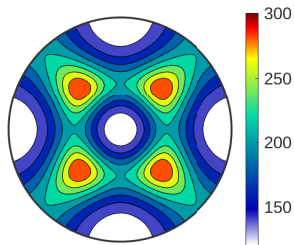
```
d = vector3d.Z;
sigma = stressTensor.uniaxial(d)
```

```
sigma = stressTensor(show methods, plot)
rank: 2 (3 x 3)
```

```
0 0 0
0 0 0
0 0 1
```

strain $\epsilon_{ij} = S_{klij}\sigma_{kl}$

```
eps = (ori * S) * sigma
```



Elastic Deformation

Import some stiffness tensor

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Consider uniaxial stress σ

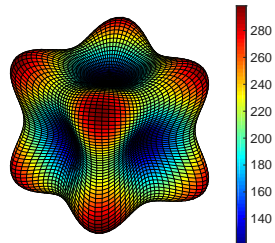
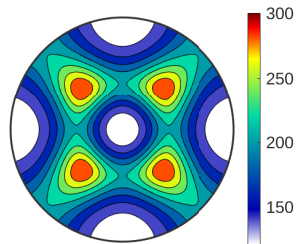
```
d = vector3d.Z;
sigma = stressTensor.uniaxial(d)
```

strain $\varepsilon_{ij} = S_{klij}\sigma_{kl}$

```
eps = (ori * S) * sigma
```

```
eps = strainTensor (show methods, plot)
rank: 2 (3 x 3)
```

```
147.67      0      0
   0 147.67      0
   0      0 235.16
```



Elasticity Tensors

derived elastic properties

beta = C. **volumeCompressibility**

beta = C. **linearCompressibility**

E = C. **YoungsModulus**

G = C. **shearModulus**(h, u)

nu = C. **PoissonRatio**(x, y)

T = C. **ChristoffelTensor**(n)

```
nu = C. PoissonRatio ([], xvector);
```

```
contourf(nu, 'minmax')
```

```
mtexColorMap blue2red
```

```
[value, pos] = max(nu)
```

```
annotate(pos, 'label', 'max')
```

Elasticity Tensors

derived elastic properties

$\beta = C.$ **volumeCompressibility**

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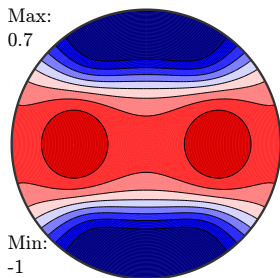
```
nu = C. PoissonRatio ([ ], xvector );
```

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derived elastic properties

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nu = C. PoissonRatio( [], xvector );
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```
contourf(nu, 'minmax')
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```
mtexColorMap blue2red
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```
[value, pos] = max(nu)
```

```
value =
```

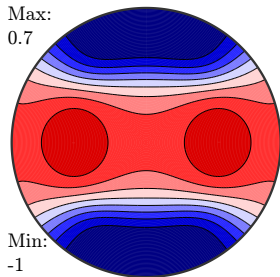
```
0.6956
```

```
pos = vector3d
```

```
size: 1 x 1
```

x	y	z
-0.918733	0	0.394879

Max:
0.7



Min:
-1

Elasticity Tensors

derived elastic properties

beta = C. **volumeCompressibility**

beta = C. **linearCompressibility**

E = C. **YoungsModulus**

G = C. **shearModulus**(h, u)

nu = C. **PoissonRatio**(x, y)

T = C. **ChristoffelTensor**(n)

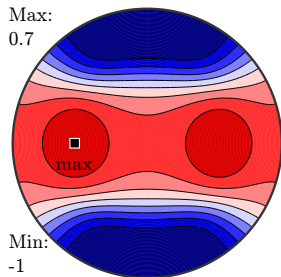
```
nu = C. PoissonRatio([], xvector);
```

```
contourf(nu, 'minmax')
```

```
mtexColorMap blue2red
```

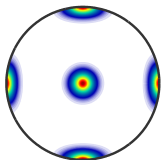
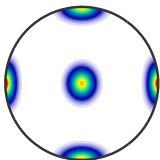
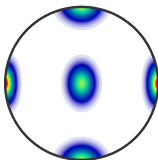
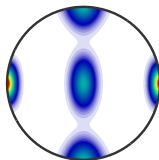
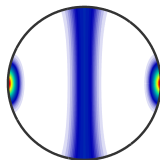
```
[value, pos] = max(nu)
```

```
annotate(pos, 'label', 'max')
```



Evolution of Elasticity

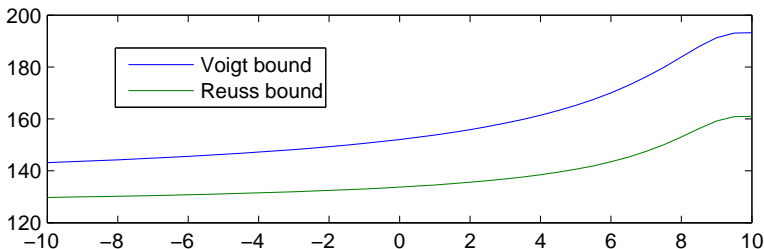
```
for k = 1:5  
    odf{k} = BinghamODF([-10, -10, 5*k - 15, 10], cs);  
end
```

 $\lambda_3 = -10$  $\lambda_3 = -5$  $\lambda_3 = 0$  $\lambda_3 = 5$  $\lambda_3 = 10$ 

Evolution of Elasticity

```
for k = 1:5  
    odf{k} = BinghamODF([-10, -10, 5*k - 15, 10], cs);  
end
```

```
for k = 1:length(odf)  
    [C_v, C_r] = calcTensor(odf{k}, C);  
    psr_v(k) = C_v.YoungsModulus(vector3d.Z);  
    psr_r(k) = C_r.YoungsModulus(vector3d.Z);  
end
```



Wave Velocities

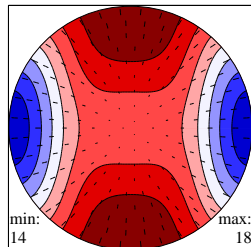
```
[vp , vs1 , vs2 , pp , ps1 , ps2 ] = velocity (C)
```

```
plot (vp , 'minmax')
```

```
hold on
```

```
plot (pp)
```

```
hold off
```



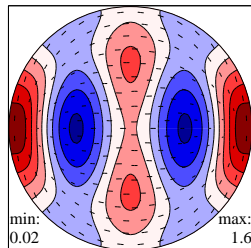
```
nextAxis % generate a new axis
```

```
plot (vs1-vs2 , 'minmax')
```

```
hold on
```

```
plot (ps1)
```

```
hold off
```



Wave Velocities

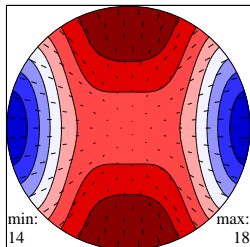
```
[vp , vs1 , vs2 , pp , ps1 , ps2 ] = velocity (C)
```

```
plot (vp , 'minmax')
```

```
hold on
```

```
plot (pp)
```

```
hold off
```



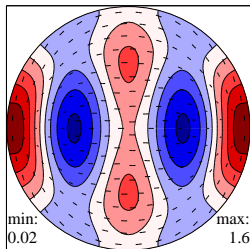
```
nextAxis % generate a new axis
```

```
plot (vs1-vs2 , 'minmax')
```

```
hold on
```

```
plot (ps1)
```

```
hold off
```



Slowness Surface

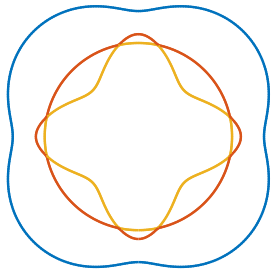
```
[vp , vs1 , vs2 , pp , ps1 , ps2 ] = velocity (C)
```

The wavefront in the plane perpendicular to z

```
pN = vector3d.Z  
plotSection (vp , pN)  
hold on  
plotSection (vs1 , pN)  
plotSection (vs2 , pN)  
hold off
```

The slowness surface perpendicular to z

```
plotSection (1./vp , pN)  
hold on  
plotSection (1./vs1 , pN)  
plotSection (1./vs2 , pN)  
hold off
```



Slowness Surface

$$[v_p, v_{s1}, v_{s2}, p_p, p_{s1}, p_{s2}] = \mathbf{velocity}(C)$$

The wavefront in the plane perpendicular to \mathbf{z}

```
pN = vector3d.Z
```

```
plotSection(v_p, pN)
```

```
hold on
```

```
plotSection(v_{s1}, pN)
```

```
plotSection(v_{s2}, pN)
```

```
hold off
```

The slowness surface perpendicular to \mathbf{z}

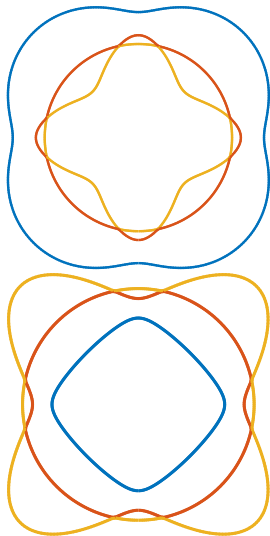
```
plotSection(1./v_p, pN)
```

```
hold on
```

```
plotSection(1./v_{s1}, pN)
```

```
plotSection(1./v_{s2}, pN)
```

```
hold off
```



Vertical and Horizontal Velocities

Vertical and horizontal velocities

```
id = angle(ps1 ,pN) <= 89.9*degree ;  
vsv = id .* vs1 + (1-id) .* vs2 ;  
vsh = id .* vs2 + (1-id) .* vs1 ;
```

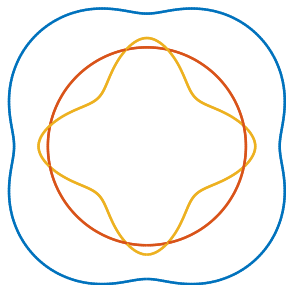
Vertical and Horizontal Velocities

Vertical and horizontal velocities

```
id = angle(ps1 , pN) <= 89.9 * degree ;  
vsv = id .* vs1 + (1-id) .* vs2 ;  
vsh = id .* vs2 + (1-id) .* vs1 ;
```

The wavefront in the plane perpendicular to **z**

```
plotSection(vp , pN)  
hold on  
plotSection(vsv , pN)  
plotSection(vsh , pN)
```



Vertical and Horizontal Velocities

Vertical and horizontal velocities

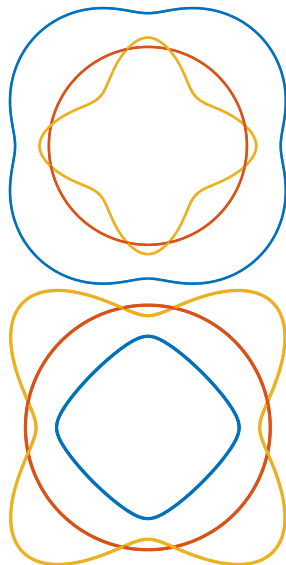
```
id = angle(ps1 , pN) <= 89.9*degree ;  
vsv = id .* vs1 + (1-id) .* vs2 ;  
vsh = id .* vs2 + (1-id) .* vs1 ;
```

The wavefront in the plane perpendicular to \mathbf{z}

```
plotSection(vp , pN)  
hold on  
plotSection(vsv , pN)  
plotSection(vsh , pN)
```

The slowness surface perpendicular to \mathbf{z}

```
plotSection(1./vp , pN)  
hold on  
plotSection(1./vsv , pN)  
plotSection(1./vsh , pN)
```



Energy Velocity Vector

Definition

$$E_i = \frac{v}{\rho} C_{ijkl} p_j p_l x_k$$

- C stiffness tensor
- x propagation direction
- v wave velocity in x
- p polarization in x
- ρ density

Energy Velocity Vector

Definition

$$E_i = \frac{v}{\rho} C_{ijkl} p_j p_l x_k$$

$E_{vp} = \mathbf{energyVector}(C, [], v_p, p_p)$

$E_{sv} = \mathbf{energyVector}(C, [], v_{sv}, p_{sv})$

$E_{sh} = \mathbf{energyVector}(C, [], v_{sh}, p_{sh})$

C stiffness tensor

x propagation direction

v wave velocity in x

p polarization in x

ρ density

Energy Velocity Vector

Definition

$$E_i = \frac{v}{\rho} C_{ijkl} p_j p_l x_k$$

```

Evp = energyVector(C, [], vp, pp)
Esv = energyVector(C, [], vsv, psv)
Esh = energyVector(C, [], vsh, psh)

```

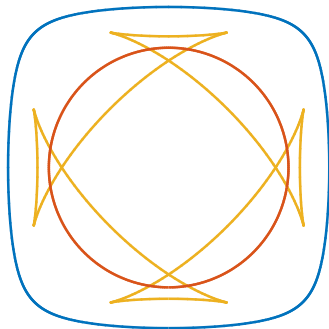
The energy vector perpendicular to \mathbf{z}

```

plotSection(Evp, pN)
hold on
plotSection(Esv, pN)
plotSection(Esh, pN)
hold off

```

- C stiffness tensor
- x propagation direction
- v wave velocity in x
- p polarization in x
- ρ density



Schmid Factor

Consider the slip system

```
d = Miller(0, -1, 1, cs, 'uvw'); % slip direction  
n = Miller(1, 1, 1, cs, 'hkl'); % slip plane normal
```

and the extension direction

```
r = vector3d(0, 0, 1) % extension direction
```

Then the Schmid factor in direction \mathbf{r} is given by

$$SF = \cos \theta \cos \rho$$

In **MTEX** this can be computed by

```
SF = dot(n, r) * dot(b, r)
```

Schmid Factor

Consider the slip system

```
d = Miller(0, -1, 1, cs, 'uvw'); % slip direction
n = Miller(1, 1, 1, cs, 'hkl'); % slip plane normal
```

and the extension direction

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Schmid Factor

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d = Miller(0, -1, 1, cs, 'uvw'); % slip direction  
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and the extension direction

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Schmid Factor

Consider the slip system

```
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Then the Schmid factor in direction \mathbf{r} is given by

$$SF = \cos \theta \cos \rho$$

In **MTEX** this can be computed by

```
SF = dot(n, r) * dot(b, r)
```

Slip Systems

```
sS = slipSystem(d, n)
```

```
sS = slipSystem  
symmetry: 432  
CRSS: 1  
size: 1 x 1  
  u   v   w | h   k   l  
  0  -1   1 | 1   1   1
```

```
sS = slipSystem.fcc(cs)
```

```
sS.symmetrise('antipodal')
```

```
sS.SchmidFactor(vector3d.Z)
```

```
plot(sS.SchmidFactor)
```

```
M = [1 0 1; 0 0 0; 1 0 1];  
sigma = stressTensor(M)  
sS.SchmidFactor(sigma)
```

Slip Systems

```
sS = slipSystem(d, n)
```

```
sS = slipSystem.fcc(cs)
```

```
sS = slipSystem
```

```
symmetry: 432
```

```
CRSS: 1
```

```
size: 1 x 1
```

```
u   v   w | h   k   l
```

```
0   1  -1 | 1   1   1
```

```
sS.symmetrise('antipodal')
```

```
sS.SchmidFactor(vector3d.Z)
```

```
plot(sS.SchmidFactor)
```

```
M = [1 0 1; 0 0 0; 1 0 1];
```

```
sigma = stressTensor(M)
```

```
sS.SchmidFactor(sigma)
```

Slip Systems

```
sS = slipSystem(d, n)
```

```
sS = slipSystem.fcc(cs)
```

```
sS.symmetrise('antipodal')
```

```
sS = slipSystem
symmetry: 432
CRSS: 1
size: 12 x 1
  u   v   w | h   k   l
  0  -1   1 | 1   1   1
  1   0  -1 | 1   1   1
 -1   1   0 | 1   1   1
 -1   1   0 | 1   1  -1
 -1   0  -1 | 1   1  -1
  0  -1  -1 | 1   1  -1
  0  -1   1 | -1  1   1
 -1   0  -1 | -1  1   1
 -1  -1   0 | -1  1   1
  1   0  -1 | 1  -1   1
 -1  -1   0 | 1  -1   1
  0  -1  -1 | 1  -1   1
```

Slip Systems

```
sS = slipSystem(d, n)
```

```
sS = slipSystem.fcc(cs)
```

```
sS.symmetrise('antipodal')
```

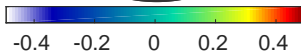
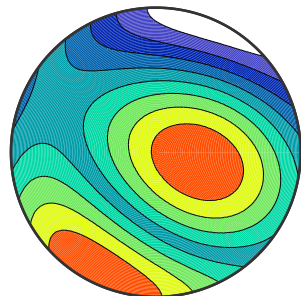
```
sS.SchmidFactor(vector3d.Z)
```

```
plot(sS.SchmidFactor)
```

```
M = [1 0 1; 0 0 0; 1 0 1];
```

```
sigma = stressTensor(M)
```

```
sS.SchmidFactor(sigma)
```



Slip Systems

```
sS = slipSystem(d, n)
```

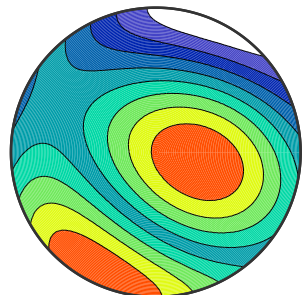
```
sS = slipSystem.fcc(cs)
```

```
sS.symmetrise('antipodal')
```

```
sS.SchmidFactor(vector3d.Z)
```

```
plot(sS.SchmidFactor)
```

```
M = [1 0 1; 0 0 0; 1 0 1];  
sigma = stressTensor(M)  
sS.SchmidFactor(sigma)
```



Slip Systems

```
sS = slipSystem(d, n)
```

```
sS = slipSystem.fcc(cs)
```

```
sS.symmetrise('antipodal')
```

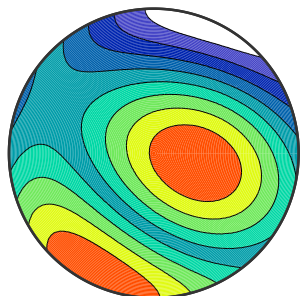
```
sS.SchmidFactor(vector3d.Z)
```

```
plot(sS.SchmidFactor)
```

```
M = [1 0 1; 0 0 0; 1 0 1];
```

```
sigma = stressTensor(M)
```

```
sS.SchmidFactor(sigma)
```



Maximum Schmid Factor

the Schmid factor for a list of tension directions

```
sS = sS.symmetrise('antipodal')  
r = plotS2Grid('upper')  
SF = sS.SchmidFactor(r)
```

SF is $\text{length}(r) \times \text{length}(sS)$ matrix
maximum Schmidfactor over the second
dimension

```
[maxSF, id] = max(abs(SF), [], 2)  
contourf(r, maxSF)
```

the active slip system

```
contourf(r, id, 'contours', 12)  
hold on  
quiver(r, sS(id).n, 'Color', 'r');  
quiver(r, sS(id).b, 'Color', 'g');  
hold off
```

Maximum Schmid Factor

the Schmid factor for a list of tension directions

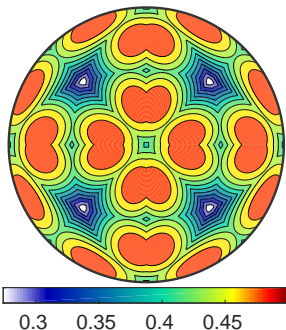
```
sS = sS.symmetrise('antipodal')  
r = plotS2Grid('upper')  
SF = sS.SchmidFactor(r)
```

SF is $\text{length}(r) \times \text{length}(sS)$ matrix
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hold on  
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quiver(r, sS(id).b, 'Color', 'g');  
hold off
```



Maximum Schmid Factor

the Schmid factor for a list of tension directions

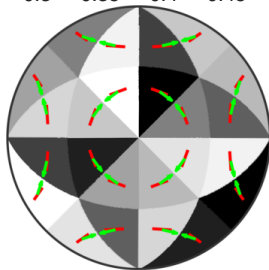
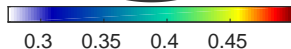
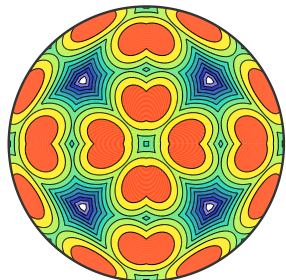
```
sS = sS.symmetrise('antipodal')  
r = plotS2Grid('upper')  
SF = sS.SchmidFactor(r)
```

SF is $\text{length}(r) \times \text{length}(sS)$ matrix
maximum Schmidfactor over the second
dimension

```
[maxSF, id] = max(abs(SF), [], 2)  
contourf(r, maxSF)
```

the active slip system

```
contourf(r, id, 'contours', 12)  
hold on  
quiver(r, sS(id).n, 'Color', 'r');  
quiver(r, sS(id).b, 'Color', 'g');  
hold off
```



Stress Based Analysis - Route 1

```
sS = symmetrise(slipSystem.fcc(ebsd.CS))
```

```
sS = slipSystem (show methods, plot)
```

```
mineral: iron (m-3m)
```

```
size: 24 x 1
```

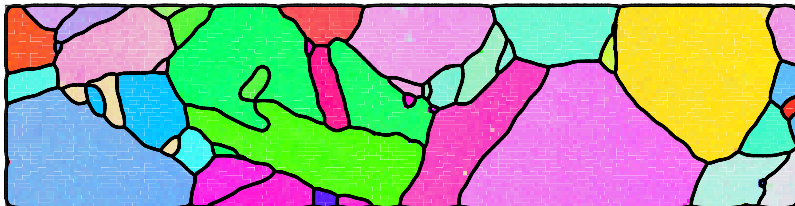
u	v	w		h	k	l
0	1	-1		1	1	1
-1	0	1		1	1	1
1	-1	0		1	1	1
0	-1	1		1	1	1
1	0	-1		1	1	1
-1	1	0		1	1	1
1	-1	0		1	1	-1
1	0	1		1	1	-1
0	1	1		1	1	-1
-1	0	-1		1	1	-1
0	-1	-1		1	1	-1
-1	1	0		1	1	-1
0	1	-1	-1	1	1	1
1	0	1	-1	1	1	1
1	1	0	-1	1	1	1
-1	0	-1	-1	1	1	1
-1	-1	0	-1	1	1	1
0	-1	1	-1	1	1	1

Stress Based Analysis - Route 1

```
sS = symmetrise(slipSystem.fcc(ebsd.CS))
```

```
sSGrain = grains.meanOrientation * sS
```

```
sSGrain = slipSystem (show methods, plot)  
size: 71 x 24
```

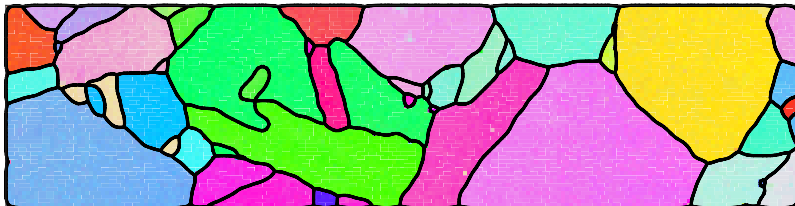


Stress Based Analysis - Route 1

```
sS = symmetrise(slipSystem.fcc(ebsd.CS))
```

```
sSGrain = grains.meanOrientation * sS
```

```
SF = sSGrain.SchmidFactor(sigma);
```



Stress Based Analysis - Route 1

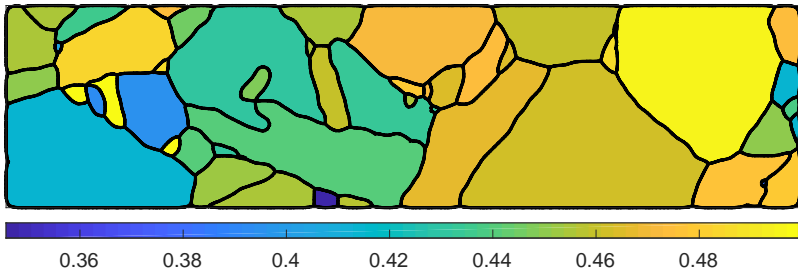
```
sS = symmetrise(slipSystem.fcc(ebsd.CS))
```

```
sSGrain = grains.meanOrientation * sS
```

```
SF = sSGrain.SchmidFactor(sigma);
```

```
[maxSF, active] = max(SF, [], 2);
```

```
plot(grains, maxSF)
```



Stress Based Analysis - Route 1

```
sS = symmetrise(slipSystem.fcc(ebsd.CS))
```

```
sSGrain = grains.meanOrientation * sS
```

```
SF = sSGrain.SchmidFactor(sigma);
```

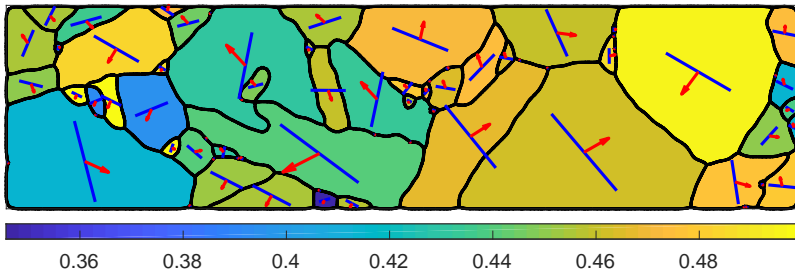
```
[maxSF, active] = max(SF, [], 2);
```

```
plot(grains, maxSF)
```

```
sSActive = grains.meanOrientation .* sS(active);
```

```
quiver(grains, sSActive.trace, 'color', 'b')
```

```
quiver(grains, sSActive.b, 'color', 'r')
```



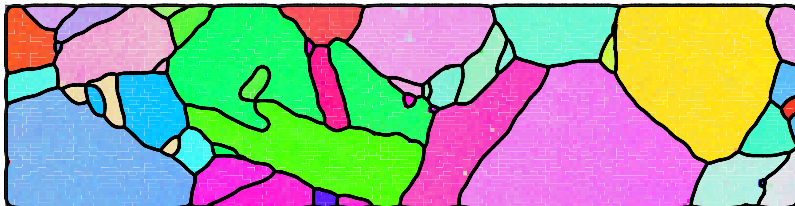
Stress Based Analysis - Route 2

```
sigma = stressTensor.uniaxial(vector3d.X)
```

```
sigma = stressTensor (show methods, plot)
```

```
rank: 2 (3 x 3)
```

```
1 0 0  
0 0 0  
0 0 0
```

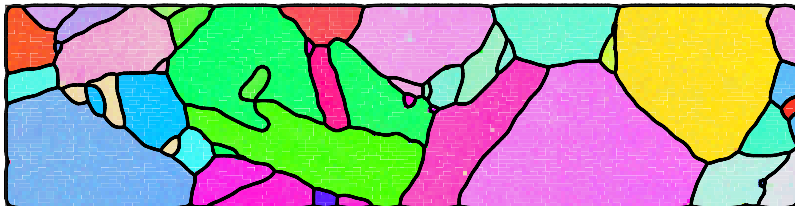


Stress Based Analysis - Route 2

```
sigma = stressTensor.uniaxial(vector3d.X)
```

```
sigmaCrystal = inv(grains.meanOrientation) * sigma
```

```
sigmaCrystal = stressTensor (show methods, plot)  
size      : 71 x 1  
rank      : 2 (3 x 3)  
mineral:  iron (m-3m)
```

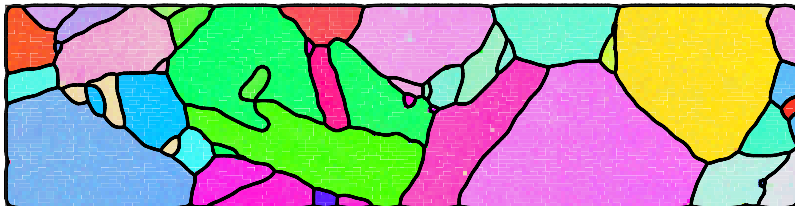


Stress Based Analysis - Route 2

```
sigma = stressTensor.uniaxial(vector3d.X)
```

```
sigmaCrystal = inv(grains.meanOrientation) * sigma
```

```
SF = sS.SchmidFactor(sigmaCrystal);
```



Stress Based Analysis - Route 2

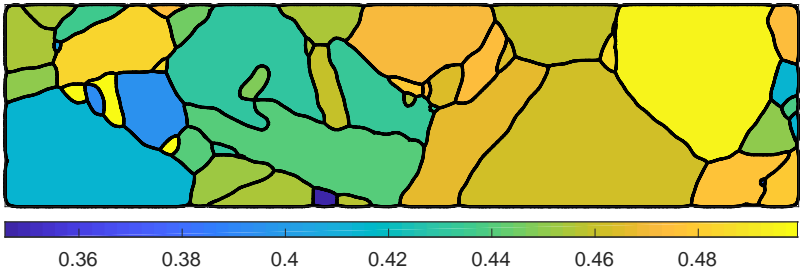
```
sigma = stressTensor.uniaxial(vector3d.X)
```

```
sigmaCrystal = inv(grains.meanOrientation) * sigma
```

```
SF = sS.SchmidFactor(sigmaCrystal);
```

```
[maxSF, active] = max(abs(SF), [], 2);
```

```
plot(grains, maxSF)
```



Stress Based Analysis - Route 2

```
sigma = stressTensor.uniaxial(vector3d.X)
```

```
sigmaCrystal = inv(grains.meanOrientation) * sigma
```

```
SF = sS.SchmidFactor(sigmaCrystal);
```

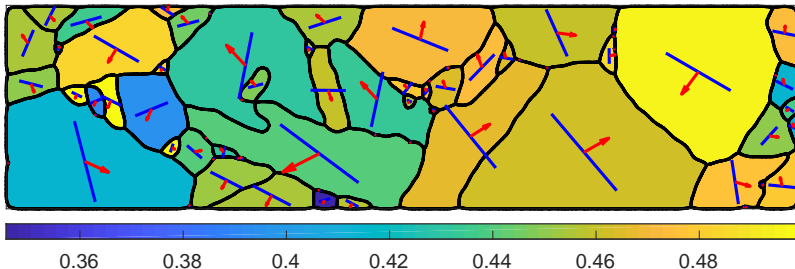
```
[maxSF, active] = max(abs(SF), [], 2);
```

```
plot(grains, maxSF)
```

```
sSActive = grains.meanOrientation .* sS(active);
```

```
quiver(grains, sSActive.trace, 'color', 'b')
```

```
quiver(grains, sSActive.b, 'color', 'r')
```



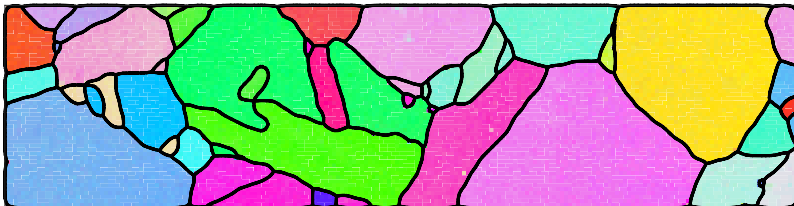
Strain Based Analysis

```
eps = strainTensor(diag([1,0,-1]))
```

```
sigma = strainTensor (show methods, plot)
```

```
rank: 2 (3 x 3)
```

```
1  0  0  
0  0  0  
0  0 -1
```

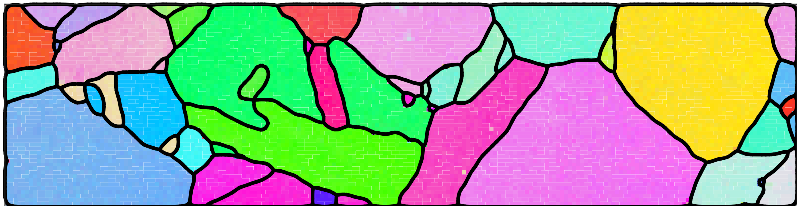


Strain Based Analysis

```
eps = strainTensor(diag([1,0,-1]))
```

```
epsCrystal = inv(grains.meanOrientation) * eps
```

```
sigmaCrystal = strainTensor (show methods, plot)  
size      : 71 x 1  
rank      : 2 (3 x 3)  
mineral:  iron (m-3m)
```

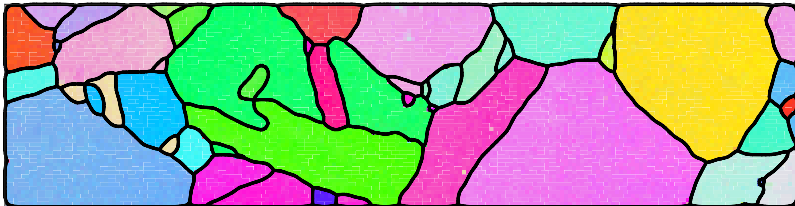


Strain Based Analysis

```
eps = strainTensor(diag([1,0,-1]))
```

```
epsCrystal = inv(grains.meanOrientation) * eps
```

```
[TF, b, mori] = calcTaylor(epsCrystal, sS);
```



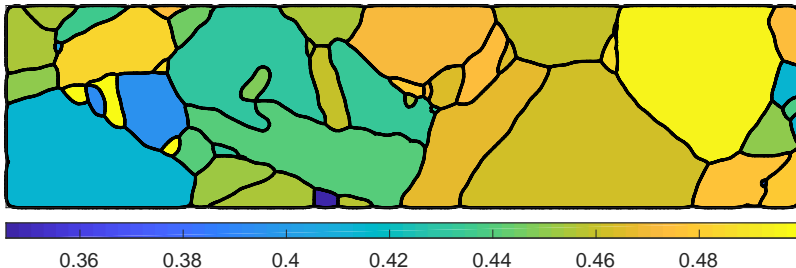
Strain Based Analysis

```
eps = strainTensor(diag([1,0,-1]))
```

```
epsCrystal = inv(grains.meanOrientation) * eps
```

```
[TF, b, mori] = calcTaylor(epsCrystal, sS);
```

```
plot(grains, TF)
```



Strain Based Analysis

```
eps = strainTensor(diag([1,0,-1]))
```

```
epsCrystal = inv(grains.meanOrientation) * eps
```

```
[TF, b, mori] = calcTaylor(epsCrystal, sS);
```

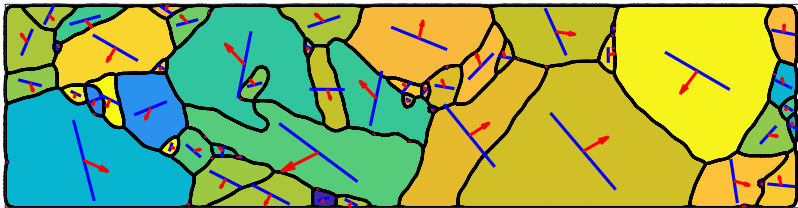
```
plot(grains, TF)
```

```
[bMax, bMaxId] = max(b, [], 2);
```

```
sSActive = grains.meanOrientation .* sS(bMaxId);
```

```
quiver(grains, sSActive.b, 'color', 'red')
```

```
quiver(grains, sSActive.trace, 'color', 'blue')
```



0.36

0.38

0.4

0.42

0.44

0.46

0.48

Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

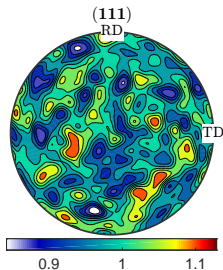
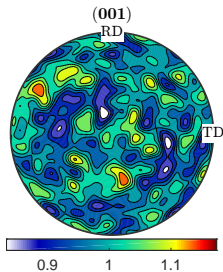
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)
h = Miller({0,0,1},{1,1,1}),CS)
plotPDF(ori,'contourf')
```

the slip systems

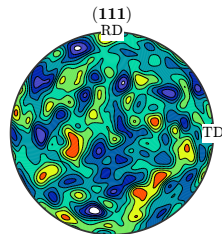
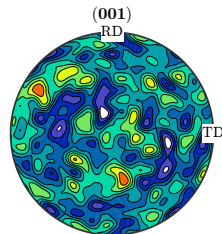
```
sS=symmetrise(slipSystem.fcc(CS))
```

```
sS = slipSystem (show methods, plot)
```

size: 12 x 1

mineral: Austenite (fcc) (432)

u	v	w	h	k	l
0	1	-1	1	1	1
-1	0	1	1	1	1
1	-1	0	1	1	1
1	-1	0	1	1	-1
1	0	1	1	1	-1
0	1	1	1	1	-1
0	1	-1	-1	1	1
1	0	1	-1	1	1
1	1	0	-1	1	1
-1	0	1	1	-1	1
1	1	0	1	-1	1



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

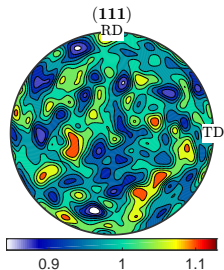
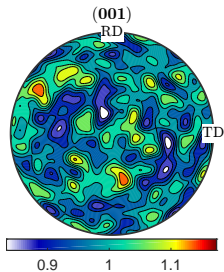
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

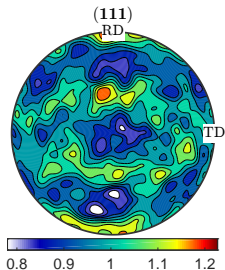
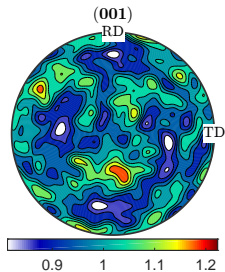
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

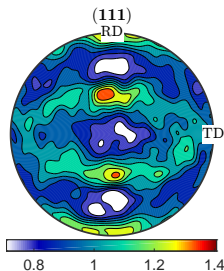
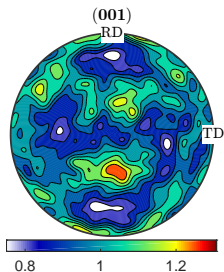
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS  
plotPDF(ori,'contourf')
```

the slip systems

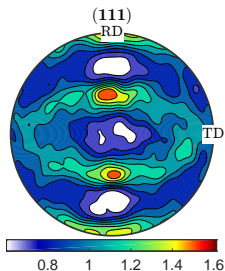
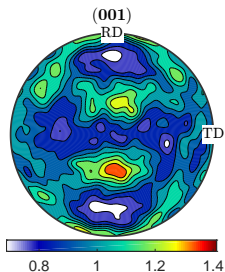
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

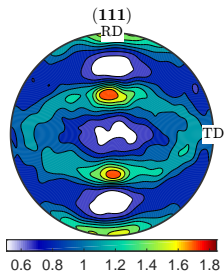
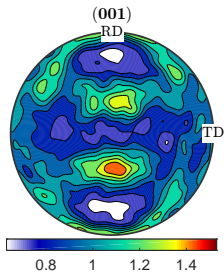
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS  
plotPDF(ori,'contourf')
```

the slip systems

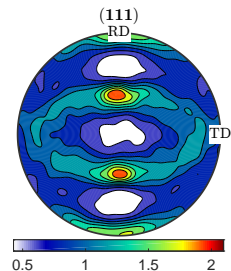
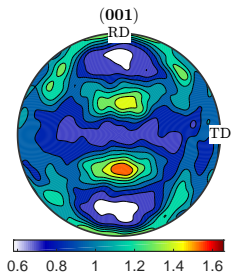
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

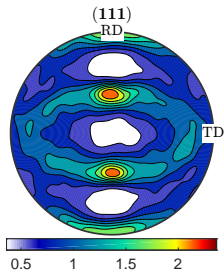
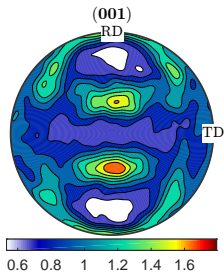
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

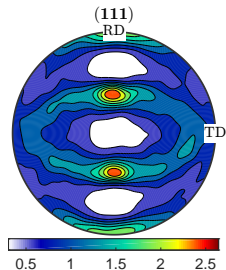
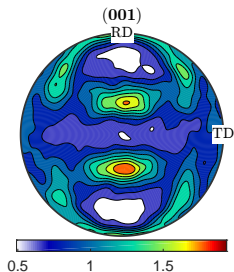
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

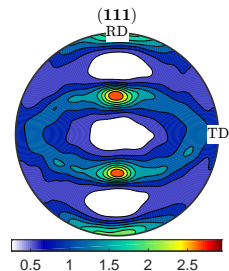
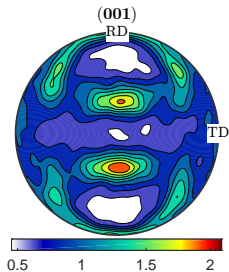
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

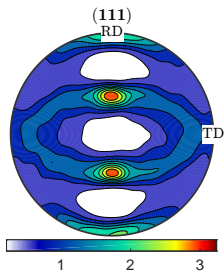
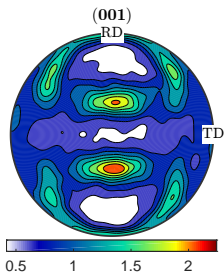
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Rolling texture evolution

```
ori = orientation.rand(10000,CS)  
h = Miller({0,0,1},{1,1,1}),CS)  
plotPDF(ori,'contourf')
```

the slip systems

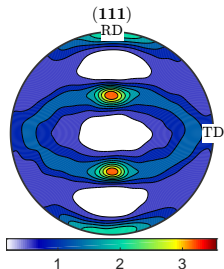
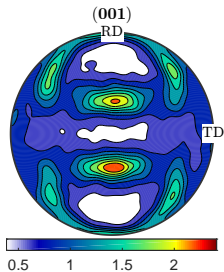
```
sS=symmetrise(slipSystem.fcc(CS))
```

30 percent strain

```
eps = strainTensor(diag([0.3 0 -0.3]))
```

iterate deformation:

```
for i = 1:10  
    [TF,b,mori] = calcTaylor(...  
        inv(ori) * eps ./ 10, sS);  
    ori = ori .* mori;  
    plotPDF(ori,h,'contourf')  
end
```



Misc

epsGrain

```
epsGrain = strainTensor (show methods, plot)
  size    : 37 x 1
  rank    : 2 (3 x 3)
  mineral : fcc (432)
```

```
epsGrain(1)
```

```
epsGrain{1,1}
```


Misc

epsGrain

epsGrain(1)

```
ans = strainTensor (show methods, plot)
```

```
rank      : 2 (3 x 3)
```

```
mineral: fcc (432)
```

```
*10-2
```

```
57.35  -24.9  -70.07
```

```
-24.9  -20.11  7.41
```

```
-70.07  7.41  -37.24
```

epsGrain{1,1}

Misc

`epsGrain``epsGrain(1)``epsGrain{1,1}`

```
ans =  
    0.5735  
    0.7898  
   -0.2335  
    0.5767  
    0.1689  
    0.1850  
    0.7818  
   -0.1903  
   -0.2332  
    0.6518  
    0.1988  
    0.2005  
    0.1999  
   -0.2329  
    0.6348
```