Introduction to Practical FFT and NFFT

Michael Pippig and Daniel Potts

Department of Mathematics Chemnitz University of Technology

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③ Parallel Fast Summation







Task of 3d-DFT

Consider a three-dimensional dataset of $n_0 \times n_1 \times n_2$ complex numbers $\hat{g}_{k_0k_1k_2} \in \mathbb{C}$. Compute

$$g_{l_0 l_1 l_2} = \sum_{k_0=0}^{n_0-1} \sum_{k_1=0}^{n_1-1} \sum_{k_2=0}^{n_2-1} \hat{g}_{k_0 k_1 k_2} e^{-2\pi i \left(k_2 \frac{l_2}{n_2} + k_1 \frac{l_1}{n_1} + k_0 \frac{l_0}{n_0}\right)}$$

for all $l_t = 0, \ldots, n_t - 1$ (t = 0, 1, 2).

Realized by 3d-FFT $(n_0 = n_1 = n_2 = n)$ $\Rightarrow \mathcal{O}(n^3 \log n)$ instead of $\mathcal{O}(n^6)$

| Examples of FFT implementations | | | | | |
|--|--|---|--|--|--|
| • IBM ESSL | Intel MKL | • FFTW | | | |
| Features of FFTW [Frigo, Johnson] | | | | | |
| public available open source high performance many transforms | arbitrary size d-dim. FFT in place FFT | collect wisdomadjust planningeasy interface | | | |
| Available at http://www.fftw.org | | | | | |

Using FFTW



Basic Interface

- simple
- do a single transform

Advanced Interface

- do a transform on multiple datasets by one call
- supports strided input and output
- use a plan on different datasets

Guru Interface

- most powerful and most complicated
- combine transform and data permutation
- 64 bit compatible

Nonequispaced Discrete Fourier Transform

Task of 3d-DFT and 3d-NDFT

For $\hat{f}_{k_0k_1k_2} \in \mathbb{C}$ compute

$$f_{l_0 l_1 l_2} := \sum_{k_0=0}^{N-1} \sum_{k_1=0}^{N-1} \sum_{k_2=0}^{N-1} \hat{f}_{k_0 k_1 k_2} e^{-2\pi i \left(k_2 \frac{l_2}{N} + k_1 \frac{l_1}{N} + k_0 \frac{l_0}{N}\right)}$$
(DFT)

for all $0 \le l_t < N \ (\Rightarrow 0 \le \frac{l_t}{N} < 1)$, t = 0, 1, 2, and compute

$$f_j := \sum_{k_0=0}^{N-1} \sum_{k_1=0}^{N-1} \sum_{k_2=0}^{N-1} \hat{f}_{k_0 k_1 k_2} e^{-2\pi i (k_2 x_j^{(2)} + k_1 x_j^{(1)} + k_0 x_j^{(0)})}$$
(NDFT)

for
$$x_j^{(t)} \in [0,1)$$
 $(t = 0, 1, 2)$, $j = 1, \dots, M$.

Realized by 3d-NFFT [NFFT software library] $\Rightarrow \mathcal{O}(N^3 \log N + \log^3(\frac{1}{\varepsilon})M) \text{ instead of } \mathcal{O}(N^3M)$

Matrix-Vector-Notation

Compute $\boldsymbol{f} = (f_j)_j \in \mathbb{C}^M$ via

$$f = A\hat{f},$$

where
$$\boldsymbol{A} = (e^{-2\pi i \boldsymbol{k} \boldsymbol{x}_j})_{\boldsymbol{k},j} \in \mathbb{C}^{M \times N^3}$$
 and $\boldsymbol{\hat{f}} = (\hat{f}_{k_0 k_1 k_2})_{\boldsymbol{k}} \in \mathbb{C}^{N^3}$

Approximation [Dutt, Rohklin 93, Beylkin 95, Steidl 96, ...]

$$A \approx BFD, \qquad A^{H} \approx DF^{H}B^{T}$$

where

- $oldsymbol{D} \in \mathbb{R}^{N^3 imes N^3}$ diagonal matrix
- $\boldsymbol{F} \in \mathbb{C}^{n^3 \times N^3}$ truncated Fourier matrix $(n \ge N)$
- $oldsymbol{B} \in \mathbb{R}^{M imes n^3}$ sparse matrix

NFFT Software Library [Keiner, Kunis, Potts]

Available at

http://www.tu-chemnitz.de/~potts/nfft





NFFT Precompute

PRE_FULL_PSI

- fully precomputed window function
- Storage: $(2m+2)^d M$, Computation: None

PRE_PSI

- tensor product based precomputation
- Storage: d(2m+2)M, Computation: $(2m+2)^dM$

PRE_LIN_PSI

- linear interpolation from lookup table
- Storage: dK, Computation: $2(2m+2)^dM$

PRE_FG_PSI

- fast Gaussian gridding
- Storage: 2dM, Computation: $(2m+2)^dM$







Task of 3d-DFT

Consider a three-dimensional dataset of $n_0 \times n_1 \times n_2$ complex numbers $\hat{g}_{k_0k_1k_2} \in \mathbb{C}$. Compute

$$g_{l_0 l_1 l_2} := \sum_{k_0=0}^{n_0-1} \sum_{k_1=0}^{n_1-1} \sum_{k_2=0}^{n_2-1} \hat{g}_{k_0 k_1 k_2} e^{-2\pi i \left(k_2 \frac{l_2}{n_2} + k_1 \frac{l_1}{n_1} + k_0 \frac{l_0}{n_0}\right)}$$
$$= \sum_{k_0=0}^{n_0-1} \left(\sum_{k_1=0}^{n_1-1} \sum_{k_2=0}^{n_2-1} \hat{g}_{k_0 k_1 k_2} e^{-2\pi i \left(k_2 \frac{l_2}{n_2} + k_1 \frac{l_1}{n_1}\right)} \right) e^{-2\pi i k_0 \frac{l_0}{n_0}}$$

for all $l_t = 0, \ldots, n_t - 1$ (t = 0, 1, 2).

Realized by 3d-FFT $(n_0 = n_1 = n_2 = n)$ $\Rightarrow \mathcal{O}(n^3 \log n)$ instead of $\mathcal{O}(n^6)$

One-Dimensional Data Distribution



p - number of processors

Features of FFTW [Frigo, Johnson]

- open source
- easy interface
- communicator
- arbitrary size
- *d*-dim. FFT
- in place FFT

- high performance
- many transforms
- adjust blocksize
- adjust planning
- collect wisdom

Maximum Number of Processors p_{\max}^{1D} ($n_0 = n_1 = n_2 = n$) $p_{\max}^{1D} = n$

FFTW combines portable performance and good usability, but is not scalable enough.

Two-Dimensional Data Distribution

[Ding, Eleftheriou et al. 03, Plimpton, Pekurovsky - P3DFFT]



1 1D

2D

2

 $p_0 imes p_1$ - size of processor grid

| | n | $p_{\text{max}} = n$ | $p_{\text{max}} = n^{-1}$ |
|----------------------------|------|----------------------|---------------------------|
| Maximum Number of | 64 | 64 | 4096 |
| Processors p_{\max}^{2D} | 128 | 128 | 16384 |
| $(n_0 = n_1 = n_2 = n)$ | 256 | 256 | 65536 |
| "2D "2 | 512 | 512 | 262144 |
| $p_{\max} = n$ | 1024 | 1024 | 1048576 |

Aim

Implement a new parallel FFT sofware library (PFFT) based on FFTW and the highly scalable two-dimensional data distribution.

1d-FFT Combined with Local Transposition

$$\begin{array}{cccc} \hat{n}_0 \times \hat{n}_1 \times \hat{n}_2 & \stackrel{\mathsf{FFT2}}{\rightarrow} & \hat{n}_0 \times \hat{n}_1 \times n_2 \\ \hat{n}_0 \times \hat{n}_1 \times \hat{n}_2 & \stackrel{\mathsf{FFT2}}{\rightarrow} & \hat{n}_1 \times \hat{n}_0 \times n_2 \\ \hat{n}_0 \times \hat{n}_1 \times \hat{n}_2 & \stackrel{\mathsf{FFT2}}{\rightarrow} & \hat{n}_1 \times \hat{n}_0 \times n_2 \\ \hat{n}_0 \times \hat{n}_1 \times \hat{n}_2 & \stackrel{\mathsf{FFT2}}{\rightarrow} & \hat{n}_0 \times n_2 \times \hat{n}_1 \\ (\hat{n}_0 \times \hat{n}_1) \times \hat{n}_2 & \stackrel{\mathsf{FFT2}}{\rightarrow} & n_2 \times (\hat{n}_0 \times \hat{n}_1) \end{array}$$

Transposition of One-Dimensional Distributed Data

$$N_0 \times \frac{N_1}{P} \xrightarrow{\mathsf{T}} \frac{N_0}{P} \times N_1$$

Group two of the three dimensions to use FFTWs matrix transposition on two-dimensional decomposed data, e.g. $N_0 = n_2, N_1 = n_0 \times \frac{n_1}{p_1}, P = p_0.$

Transposition of Two-Dimensional Distributed Data

$$n_2 \times \left(\frac{n_0}{p_0} \times \frac{n_1}{p_1}\right) \xrightarrow{\mathsf{T}} \frac{n_2}{p_0} \times \left(n_0 \times \frac{n_1}{p_1}\right)$$



PFFT Backward Transform

$$\begin{array}{cccc} \frac{n_1}{p_0} \times \frac{n_2}{p_1} \times n_0 & \stackrel{\mathsf{FFT2}}{\to} & \frac{n_1}{p_0} \times \frac{n_2}{p_1} \times \hat{n}_0 & \stackrel{\mathsf{T}}{\to} \\ n_1 \times \frac{n_2}{p_1} \times \frac{\hat{n}_0}{p_0} & \stackrel{\mathsf{FFT0}}{\to} & \frac{n_2}{p_1} \times \frac{\hat{n}_0}{p_0} \times \hat{n}_1 & \stackrel{\mathsf{T}}{\to} \\ n_2 \times \frac{\hat{n}_0}{p_0} \times \frac{\hat{n}_1}{p_1} & \stackrel{\mathsf{FFT0}}{\to} & \frac{\hat{n}_0}{p_0} \times \frac{\hat{n}_1}{p_1} \times \hat{n}_2 \end{array}$$

Scaling FFT of Size 512^3 on BlueGene/P



Scaling FFT of Size 512^3 on BlueGene/P



Scaling FFT of Size 1024^3 on BlueGene/P



Scaling FFT of Size 1024^3 on BlueGene/P



Comparison of PFFT and P3DFFT

Common Features

- open source
- high scalability
- portability
- multiple precisions
- Fortran interface
- C interface
- r2c FFT
- ghost cell support

PFFT Unique Features

- c2c FFT
- completely in place FFT
- FFTW like interface (basic, advanced and guru)
- adjustable blocksize
- separate communicator
- accumulated wisdom
- change of planning effort without recompilation
- *d*-dimensional parallel FFT
- over- and downsampling

Ghost Cell Support



 p_0

Oversampled & Downsampled FFT

Without Library Support







PFFT Library Support







 \hat{n}_0









PFFT Software Library [Pippig]

Available at http://www.tu-chemnitz.de/~mpip/software

Matrix-Vector-Notation

Compute $\boldsymbol{f} = (f_j)_j \in \mathbb{C}^M$ via

$$f = A\hat{f},$$

where
$$\boldsymbol{A} = (e^{-2\pi i \boldsymbol{k} \boldsymbol{x}_j})_{\boldsymbol{k},j} \in \mathbb{C}^{M \times N^3}$$
 and $\boldsymbol{\hat{f}} = (\hat{f}_{k_0 k_1 k_2})_{\boldsymbol{k}} \in \mathbb{C}^{N^3}$

Approximation [Dutt, Rohklin 93, Beylkin 95, Steidl 96, ...]

$$\boldsymbol{A} pprox \boldsymbol{B} \boldsymbol{F} \boldsymbol{D}, \qquad \boldsymbol{A}^{\mathsf{H}} pprox \boldsymbol{D} \boldsymbol{F}^{\mathsf{H}} \boldsymbol{B}^{T}$$

where

- $oldsymbol{D} \in \mathbb{R}^{N^3 imes N^3}$ diagonal matrix
- $\boldsymbol{F} \in \mathbb{C}^{n^3 imes N^3}$ truncated Fourier matrix $(n \ge N)$
- $\pmb{B} \in \mathbb{R}^{M imes n^3}$ sparse matrix

PNFFT in Pictures



PNFFT Software Library [Pippig]

Available at

http://www.tu-chemnitz.de/~mpip/software



2 Parallel FFT Algorithms



Parallel Fast Summation

Task

Fast computation of

$$h_j = \sum_{l=1}^{L} a_l K(\| \boldsymbol{y}_j - \boldsymbol{x}_l \|_2), \quad j = 1, \dots, M, \quad \boldsymbol{y}_j, \boldsymbol{x}_l \in \mathbb{R}^3$$

Example of Radial Kernel Function

$$K(\|\bm{x}\|_2) = \frac{1}{\|\bm{x}\|_2}, \dots$$

Realized with 3d-NFFT [NFFT Software Library]

 $\Rightarrow \mathcal{O}(\log^3(\frac{1}{\epsilon})(M+L))$ instead of $\mathcal{O}(ML)$

Matrix-Vector-Notation

Compute $\boldsymbol{h} = (h_j)_{j=1}^M$ via

h = Ka,

where $\boldsymbol{K} = (K(\|\boldsymbol{y}_j - \boldsymbol{x}_l\|))_{j,l=1}^{M,M}$ and $\boldsymbol{a} = (a_l)_{l=1}^M \in \mathbb{C}^M$.

Standard Algorithm for Equispaced Nodes

$$\pmb{K} = \pmb{F} \pmb{D} \pmb{F}^{arepsilon}$$

where

- $\boldsymbol{F} \in \mathbb{C}^{M imes M}$ equispaced Fourier matrix
- $\boldsymbol{D} \in \mathbb{C}^{M imes M}$ diagonal matrix

Parallel Fast Summation

Matrix-Vector-Notation

Compute $\boldsymbol{h} = (h_j)_{j=1}^M$ via

$$h = Ka$$
,

where
$$K = (K(||y_j - x_l||))_{j,l=1}^{M,L}$$
 and $a = (a_l)_{l=1}^{L} \in \mathbb{C}^{L}$.

Approximation [Potts, Steidl, Nieslony 2004]

$$\boldsymbol{K} pprox \boldsymbol{A}_2 \boldsymbol{D} \boldsymbol{A}_1^{ op} + \boldsymbol{K}_{NF}$$

where

• $A_2 = (e^{-2\pi i k y_j})_{j,k} \in \mathbb{C}^{M \times N^3}$ nonequispaced Fourier matrix • $D \in \mathbb{C}^{N^3 \times N^3}$ diagonal matrix • $A_1 = (e^{-2\pi i k x_l})_{l,k} \in \mathbb{C}^{L \times N^3}$ nonequispaced Fourier matrix • $K_{NF} \in \mathbb{C}^{M \times L}$ sparse near field correction

