

# Robust multigrid methods for large-scale matrix equations

*Workshop Matrix Equations, Chemnitz*

Bart Vandereycken, Stefan Vandewalle

Department of Computer Science  
Katholieke Universiteit Leuven, Belgium

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## Model problem

Consider an elliptic second order PDE

$$\mathcal{L}u := - \sum_{i,j=1}^d \frac{\partial}{\partial x_j} \left( a_{ij}(\mathbf{x}) \frac{\partial u}{\partial x_i} \right) + \sum_{i=1}^d b_i(\mathbf{x}) \frac{\partial u}{\partial x_i} + c(\mathbf{x})u = f(\mathbf{x}), \quad \mathbf{x} \in \Omega$$

discretized by  $\mathbf{A}$ .

We want to solve the corresponding Lyapunov equation

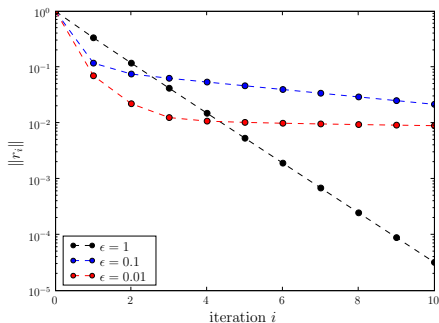
$$\mathbf{A}\mathbf{X} + \mathbf{X}\mathbf{A}^T + \mathbf{F} = 0, \quad \text{low rank } \mathbf{F}$$

Model problem for  $\mathcal{L}$ : **anisotropic** 2d diffusion

$$-\frac{\partial^2 u}{\partial x_1^2} - \epsilon \frac{\partial^2 u}{\partial x_2^2} = f(x_1, x_2), \quad \epsilon \rightarrow 0$$

## Observation

(LR-)MG with Jacobi does not work for  $-u_1 - \epsilon u_2$  if  $\epsilon \rightarrow 0$ .



Approx. rank of solution and  $\kappa$  stay the same  
 ADI, KPIK have no problem

## Solution

Well known problem for MG

- ▶ Fix grids

Choose grids so that anisotropy is eliminated and Jacobi works again

↪ Semi-coarsening, MG-S, AMG

- ▶ Fix smoothers

Keep grids but change smoothers

↪ line(block) smoothers, GS

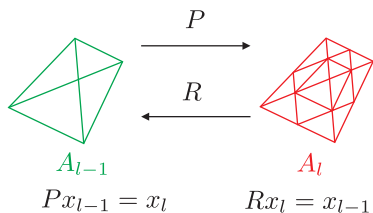
Better smoothers (RB-GS) also give you a faster MG.

# Multigrid

Solve  $\mathbf{A}\mathbf{x} = \mathbf{f}$

Cycling between  
fine and coarse grids

$\mathbf{A} : \mathbf{A}_l, \mathbf{A}_{l-1}, \mathbf{P}, \mathbf{R}$ , smoother



- ▶ Smoothing error  $\mathbf{e}_l$  on **fine** grid  
gives high frequency components  
cheap solve of  $\mathbf{A}_l \mathbf{x}_l = \mathbf{f}_l \rightsquigarrow$  Richardson, Jacobi, ...
- ▶ Error correction on **coarse** grid  
gives low frequency components  
cheap solve of  $\mathbf{A}_{l-1} \mathbf{e}_{l-1} = \mathbf{d}_{l-1} \rightsquigarrow \gamma$  recursive MG

# Tensor product MG

$$\mathbf{A}_J \mathbf{x} + \mathbf{f} = 0$$

1.  $\mathbf{x}_1 \leftarrow \text{smooth}^\nu(\mathbf{x}_0, \mathbf{f})$
2.  $\mathbf{d} \leftarrow \mathbf{A}_J \mathbf{x}_1 + \mathbf{f}$
3.  $\bar{\mathbf{f}} \leftarrow \mathbf{R}(\mathbf{d})$
4.  $\bar{\mathbf{x}} \leftarrow \mathbf{A}_{J-1}^{-1} \bar{\mathbf{f}}$
5.  $\mathbf{x}_2 \leftarrow \mathbf{x}_1 + \mathbf{P} \bar{\mathbf{x}}$

# Tensor product MG

$$\mathbf{A}_l \mathbf{x} + \mathbf{f} = 0$$

1.  $\mathbf{x}_1 \leftarrow \text{smooth}^\nu(\mathbf{x}_0, \mathbf{f})$
2.  $\mathbf{d} \leftarrow \mathbf{A}_l \mathbf{x}_1 + \mathbf{f}$
3.  $\bar{\mathbf{f}} \leftarrow \mathcal{R}(\mathbf{d})$
4.  $\bar{\mathbf{x}} \leftarrow \mathbf{A}_{l-1}^{-1} \bar{\mathbf{f}}$
5.  $\mathbf{x}_2 \leftarrow \mathbf{x}_1 + \mathbf{P} \bar{\mathbf{x}}$

$$\mathbf{A}_l \mathbf{X} + \mathbf{X} \mathbf{A}_l^T + \mathbf{F} = 0$$

1.  $\mathbf{X}_1 \leftarrow \text{smooth}^\nu(\mathbf{X}_0, \mathbf{F})$
2.  $\mathbf{D} \leftarrow \mathbf{A}_l \mathbf{X}_1 + \mathbf{X}_1 \mathbf{A}_l^T + \mathbf{F}$
3.  $\bar{\mathbf{F}} \leftarrow \mathcal{R}(\mathbf{D})$
4.  $\bar{\mathbf{X}} \leftarrow (\mathbf{A}_{l-1} \bullet + \bullet \mathbf{A}_{l-1}^T + \bar{\mathbf{F}})$
5.  $\mathbf{X}_2 \leftarrow \mathbf{X}_1 + \mathcal{P} \bar{\mathbf{X}}$

# Framework Hackbusch

Smoothing property

$$\lim_{\nu \rightarrow \infty} \sup_I \frac{\|\mathbf{A}_I \mathbf{S}_I^\nu\|}{\|\mathbf{A}_I\|} = 0$$

Approximation property

$$\sup_I \|\mathbf{A}_I^{-1} - \mathbf{P} \mathbf{A}_{I-1}^{-1} \mathbf{R}\| \|\mathbf{A}_I\| = C_A$$

↪ TG and W-cycle mesh-independent convergence

Anisotropy:  $C_A \sim 1/\epsilon$

point-smoothers:  $\sup_I \frac{\|\mathbf{A}_I \mathbf{S}_I^\nu\|}{\|\mathbf{A}_I\|} \approx \epsilon$

block-smoothers:  $\sup_I \frac{\|\mathbf{A}_I \mathbf{S}_I^\nu\|}{\|\mathbf{A}_I\|} \sim \epsilon$

## Local Fourier Analysis

$\mathbf{A}_h$  is an operator on an infinite grid

$$\mathbf{G}_h = \{\mathbf{x} = (x_1, \dots, x_d) = \boldsymbol{\kappa} \mathbf{h} = (\kappa_1 h_1, \dots, \kappa_d h_d), \boldsymbol{\kappa} \in \mathbb{Z}^d\}.$$

with constant coefficients.

The formal eigenfunctions or Fourier modes

$$\varphi(\boldsymbol{\theta}, \mathbf{x}) = e^{i\boldsymbol{\theta} \mathbf{x} / \mathbf{h}} = e^{i\theta_1 x_1 / h_1} \dots e^{i\theta_d x_d / h_d} \quad \text{for } \mathbf{x} \in \mathbf{G}_h$$

with formal eigenvalue or symbol

$$\mathbf{A}_h \varphi(\boldsymbol{\theta}) = \tilde{\mathbf{A}}_h(\boldsymbol{\theta}) \varphi(\boldsymbol{\theta})$$

Heuristic but very good predictions of MG convergence.

## Tensor LFA

Tensor structure of  $\mathbf{A} \oplus \mathbf{A}$  also in LFA

- ▶ Frequency components

$$\varphi(\theta, \mathbf{x}) \rightarrow \varphi((\theta_x, \theta_y), (\mathbf{x}, \mathbf{y})), \quad \mathbf{x} \in \mathbf{G}_h \rightarrow (\mathbf{x}, \mathbf{y}) \in \mathbf{G}_h \otimes \mathbf{G}_h$$

- ▶  $2h$ -harmonics:  $\theta^{(0,0)}\theta^{(1,0)}$
- ▶ Symbols

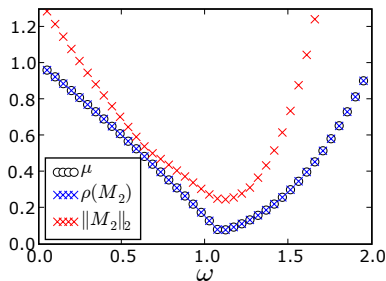
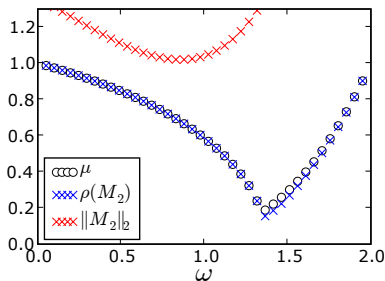
$$\tilde{R}_h(\theta^\alpha) \rightarrow \tilde{R}_h(\theta_x^{\alpha_x})\tilde{R}_h(\theta_y^{\alpha_y})$$

- ▶ Block-diagonal

$$\dots \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} - \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} [\times] \dots \rightarrow \dots \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} \otimes \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} - \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} \otimes \begin{bmatrix} \times & & & \\ & \times & & \\ & & \times & \\ & & & \times \end{bmatrix} [\times] \oplus [\times] \dots$$

## LFA results

Anisotropic Poisson  $-u_{x_1x_1} - \epsilon u_{y_1y_1} - u_{x_2x_2} - \epsilon u_{y_2y_2}$ ,  $\epsilon = 0.3$



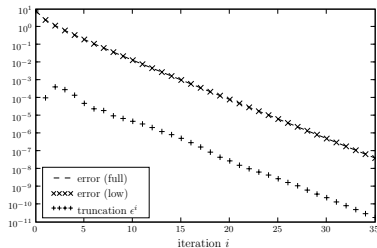
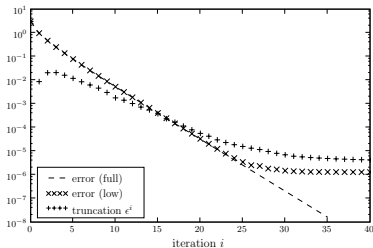
RB G-S, FW, Linear interp., 1 pre, 1 post

# Perturbed MG

1.  $\widetilde{\mathbf{X}}_1 \leftarrow \mathcal{T}_k(\text{smooth}^{\nu_1}(\widetilde{\mathbf{X}}_0, \mathbf{F})) \quad \rightsquigarrow \epsilon_s$
2.  $\widetilde{\mathbf{D}} \leftarrow \mathcal{T}_k(\mathbf{A}_l \widetilde{\mathbf{X}}_1 + \widetilde{\mathbf{X}}_1 \mathbf{A}_l^T + \mathbf{F}) \quad \rightsquigarrow \epsilon_d$
3.  $\widetilde{\mathbf{F}} \leftarrow \mathcal{R} \widetilde{\mathbf{D}}$
4.  $\widetilde{\widetilde{\mathbf{X}}} \leftarrow \mathcal{T}_k(\text{cgc}(\mathbf{A}_{l-1}, \widetilde{\mathbf{F}})) \quad \rightsquigarrow \epsilon_c$
5.  $\widetilde{\mathbf{X}}_2 \leftarrow \mathcal{T}_k(\mathbf{X}_1 + \mathcal{P} \widetilde{\widetilde{\mathbf{X}}}) \quad \rightsquigarrow \epsilon_e$

$$\begin{aligned}
 \|\mathbf{e}_2\| &\leq \|\mathbf{TG}\| \|\mathbf{e}_0\| \\
 &\quad + \|\mathbf{I} - \mathcal{P} \widetilde{\mathbf{S}}^{-1} \mathcal{R} \mathcal{S}\| \epsilon_s + \|\mathcal{P} \widetilde{\mathbf{S}}^{-1} \mathcal{R}\| \epsilon_d + \|\mathcal{P}\| \epsilon_c + \epsilon_e \\
 &\leq \|\mathbf{TG}\| \|\mathbf{e}_0\| + \epsilon_{\mathbf{TG}}
 \end{aligned}$$

## Truncation error due to low rank iterations for isotropic Poisson (1,1) Jacobi smoother.



# Conclusion

You can

- ▶ predict and proof **mesh-independent** convergence of MG (mature literature).  
     $\rightsquigarrow$  complexity of  $\mathcal{O}(n^2)$
- ▶ **control** the errors in LR-MG and keep convergence of MG.  
     $\rightsquigarrow$  complexity of  $\mathcal{O}(n \log^c n)$

## Implementation of LR-MG

How can we use **MG components** for the tensor problem and apply them in a *low rank* setting?

- ▶ **Intergrid transfers  $\mathbf{P}, \mathbf{R}$ :**

we can do  $\mathbf{P} \otimes \mathbf{P}$  to a LR matrix  $\mathbf{Y}\mathbf{Z}^T$  as

$$(\mathbf{P} \otimes \mathbf{P})\mathbf{Y}\mathbf{Z}^T = (\mathbf{P}\mathbf{Y})(\mathbf{P}\mathbf{Z})^T.$$

- ▶ **Coarse grid operator  $\mathbf{A}_{i-1}$ :**

tensorised application of the FDM of  $\mathbf{A}_{i-1}$  gives

$$\mathbf{A}_{i-1} \otimes \mathbf{I} + \mathbf{I} \otimes \mathbf{A}_{i-1}.$$

- ▶ **Smoothing:**

more *complicated*.

# LR smoother

Richardson iteration

$$\mathbf{x}_{i+1} = \mathbf{x}_i - \theta(\mathbf{A}\mathbf{x}_i + \mathbf{f})$$

$$\mathbf{X}_{i+1} = \mathcal{T}_k \left( \mathbf{X}_i - \theta(\mathbf{A}\mathbf{X}_i + \mathbf{X}_i\mathbf{A}^T + \mathbf{F}) \right)$$

how to do Gauss-Seidel, block-smoothers, ...

Typical MG smoothers for  $\mathbf{A}$  are based on a splitting:

$$\mathbf{A} = \mathbf{W} - \mathbf{R}$$

gives the iteration

$$\mathbf{W}\mathbf{u}_{i+1} = \mathbf{R}\mathbf{u}_i + \mathbf{f} \quad \mathbf{S} = \mathbf{W}^{-1}\mathbf{R}$$

We propose a similar splitting for  $\mathbf{A}\mathbf{X} + \mathbf{X}\mathbf{A}^T$

$$\mathbf{A} \otimes \mathbf{I} + \mathbf{I} \otimes \mathbf{A} = (\mathbf{W} \otimes \mathbf{I} + \mathbf{I} \otimes \mathbf{W}) - (\mathbf{R} \otimes \mathbf{I} + \mathbf{I} \otimes \mathbf{R})$$

gives

$$\mathbf{W}\mathbf{U}_{i+1} + \mathbf{U}_{i+1}\mathbf{W}^T = \mathbf{R}\mathbf{U}_i + \mathbf{U}_i\mathbf{R}^T + \mathbf{F}$$

The Lyapunov equation of the smoother

$$\mathbf{W}\mathbf{U}_{i+1} + \mathbf{U}_{i+1}\mathbf{W}^T = \mathbf{D}$$

is *supposed* to be easy with a well chosen splitting!

- ▶ solve  $\mathbf{U}_{i+1}$  as a low rank matrix

The Lyapunov equation of the smoother

$$\mathbf{W}\mathbf{U}_{i+1} + \mathbf{U}_{i+1}\mathbf{W}^T = \mathbf{D}$$

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- ▶ solve  $\mathbf{U}_{i+1}$  as a low rank matrix

↪ use existing LR Lyapunov solvers to *solve the smoother*,  
e.g. CF-ADI

- ▶ a lot better than solving  $\mathbf{A}\mathbf{X} + \mathbf{X}\mathbf{A}^T$  directly
- ▶ only *one, two* ADI iterations

## Smoother solved by ADI

Solve

$$\mathbf{W}\mathbf{U}_{i+1} + \mathbf{U}_{i+1}\mathbf{W}^T = \mathbf{D}$$

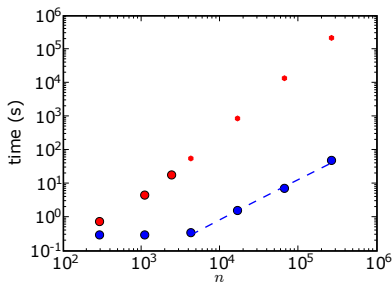
by CF-ADI:

smoother	$\mathbf{W}$	spectrum	shift-inv.	nb. ADI
Jacobi	$\mathbf{D}$	+	+	+
Lex.GS	$\mathbf{L}$	+ (non-normal)	+	?
RB Jac/GS	2 $\mathbf{D}/\mathbf{L}$	+	+	+/?
ILU	2 $\mathbf{L}$	?	-	+
Line-Jac	tri-diag.	symmetric: +	+	+/-

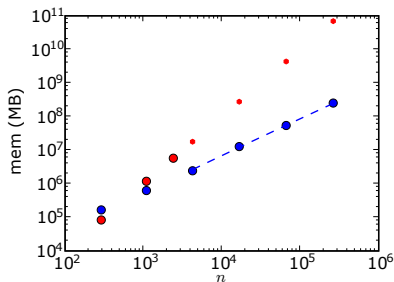
In the end: one or two very cheap ADI iterations

## Nested iteration

FMG on  $2d \times 2d$  Poisson: up to *discretisation* error



mesh of  $513 \times 513$  in 50s  
 $\mathcal{O}(n \log^4(n))$



mesh of  $513 \times 513$  in 250MB  
 $\mathcal{O}(n \log^2(n))$

RB G-S, FW, Linear interp., 1 pre, 1 post  
 3 sweeps / nested iteration

## LR-MG vs. K-PIK

Anisotropic diffusion

- ▶ LR-MG with line Jac.: nb of its constant with  $n$
- ▶ K-PIK: nb of its grows with  $n$

