

Krylov subspace methods for solving Lyapunov equations *revisited*

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Lyapunov equation is linear matrix equation

$$AX + XA^T = -C \quad (\text{LYAP})$$

with $n \times n$ coefficient matrices A and C .

Outline

- ▶ Basic properties
 - ▶ solvability, integral representation
 - ▶ Cauchy matrices
 - ▶ eigenvalue decay
- ▶ Krylov subspace methods
 - ▶ basic Arnoldi and Lanczos methods
 - ▶ convergence
 - ▶ preconditioning
 - ▶ finite-precision aspects
 - ▶ memory-efficient variants

Basic properties – Solvability

(LYAP) $AX + XA^T = -C$ can be written as $n^2 \times n^2$ linear system:

$$((I_n \otimes A) + (A \otimes I_n))\text{vec}(X) = -\text{vec}(C) \quad (\text{KRON})$$

with the Kronecker (tensor) product \otimes .

- (LYAP) has a unique solution
- \Leftrightarrow (KRON) has a unique solution
- \Leftrightarrow A has no eigenvalue pairs $(\lambda, -\lambda)$.

In the rest of this talk, we assume A stable and C s.p.sd.



$$X = \int_0^{\infty} e^{tA} C e^{tA^T} dt. \quad (\text{INT})$$

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\Downarrow

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Basic properties – Cauchy matrices

Let $A = T\Lambda T^{-1}$ (diagonalization) and $C = bb^T$ with vector b .
Transform (LYAP) to

$$\Lambda \tilde{X} + \tilde{X} \bar{\Lambda} = -(T^{-1}b)(T^{-1}b)^*.$$

Then

$$\tilde{X} = -D_b \left[\frac{1}{\lambda_i + \bar{\lambda}_j} \right]_{i,j=1}^n \bar{D}_b \quad (\text{CAUCHY})$$

with $D_b = \text{diag}(\tilde{b}_1, \tilde{b}_2, \dots, \tilde{b}_n)$.

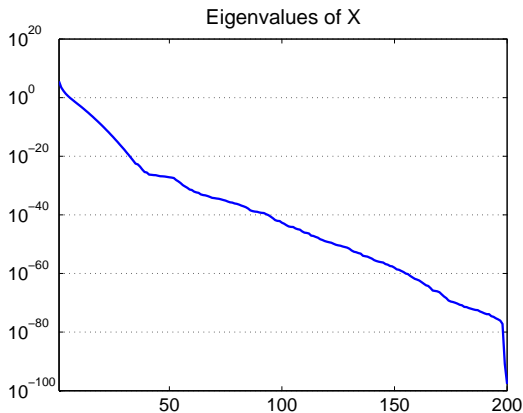
$\left[\frac{1}{\lambda_i + \bar{\lambda}_j} \right]_{i,j=1}^n$ is called a **Cauchy matrix**.

Eigenvalue decay – Example

Consider $AX + XA^T = -BB^T$, where $B \in \mathbb{R}^{n \times m}$ with $m \ll n$. Then the singular values of X often decay very rapidly.

Simple example:

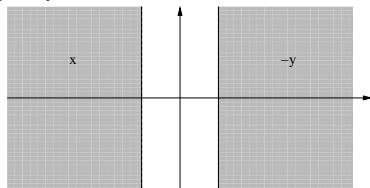
$A \in \mathbb{R}^{200 \times 200}$ second-difference operator and $B = [1, \dots, 1]^T$.



Eigenvalue decay – Analytic Intuition

$1/(x + y)$ can be well approximated by separated functions

$$\frac{1}{x + y} \approx \sum_{l=1}^k f_l(x) \overline{f_l(y)}.$$



Apply to (CAUCHY):

$$\left[\frac{1}{\lambda_i + \overline{\lambda_j}} \right]_{i,j=1}^n \approx \left[\sum_{l=1}^k f_l(\lambda_i) \overline{f_l(\lambda_j)} \right]_{i,j=1}^n = LL^H$$

with

$$L = \begin{bmatrix} f_1(\lambda_1) & \cdots & f_l(\lambda_1) \\ f_1(\lambda_2) & \cdots & f_l(\lambda_2) \\ \vdots & & \vdots \\ f_1(\lambda_n) & \cdots & f_l(\lambda_n) \end{bmatrix}.$$

Basic properties – Eigenvalue decay

Approaches to prove eigenvalue decay

- ▶ [Penzl'00]: Apply ADI method to construct explicit low-rank approximations to $X \rightsquigarrow$

$$\frac{\lambda_{mk+1}(X)}{\lambda_1(X)} \leq \left(\prod_{j=0}^{k-1} \frac{\kappa^{(2j+1)/(2k)} - 1}{\kappa^{(2j+1)/(2k)} + 1} \right)^2 = \exp \left(-O \left(\frac{k}{\log \kappa} \right) \right)$$

holds for symmetric A with $\kappa = \kappa(A)$.

Basic properties – Eigenvalue decay

- ▶ [Antoulas/Sorensen/Zhou'02]: Apply results on Cholesky factor diagonal of Cauchy matrices [Gohberg/Koltracht'96] to (CAUCHY) \rightsquigarrow

$$\frac{\lambda_{mk}(X)}{\lambda_1(X)} \leq \frac{\kappa(T)\Re\lambda_1}{\Re\lambda_k} \prod_{j=1}^{k-1} \left| \frac{\lambda_k - \lambda_j}{\lambda_k + \lambda_j} \right|^2.$$

holds for nonsymmetric, diagonalizable A with eigenvalues $\lambda_1, \dots, \lambda_n$.

- ▶ [Grasedyck/Hackbusch/Khoromsky'02]: Apply numerical quadrature [Stenger'93] to (INT) \rightsquigarrow

$$\frac{\lambda_{mk}(X)}{\lambda_1(X)} \leq O(\exp(-\sqrt{k})).$$

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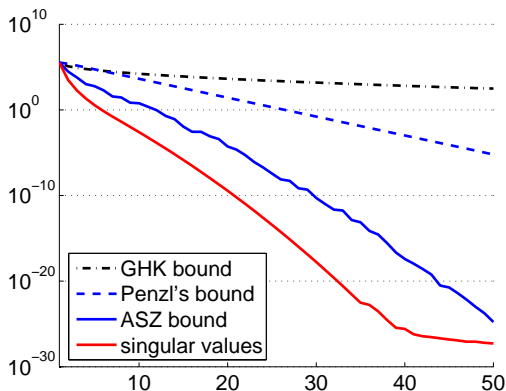
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Basic properties – Eigenvalue decay

Example:

$A \in \mathbb{R}^{200 \times 200}$ second-difference operator and $B = [1, \dots, 1]^T$.



Existing solution methods for Lyapunov equations

$n \leq O(10^4)$

Schur form + substitution [Bartels/Stewart'72]
[Hammarling'82], [Jonsson/Kågström'02],
[Sorensen/Zhou'03], [Quintana-Ortí/van de Geijn'03],
[Granat'05], [Kressner'06].

form/store A^{-1}

Sign function iteration [Roberts'71],
[Beavers/Denman'75], [Byers'87],
[Benner/Quintana-Ortí'99], [Grasedyck et al.'03],
[Baur/Benner'04].

apply $(A - \sigma I)^{-1}$

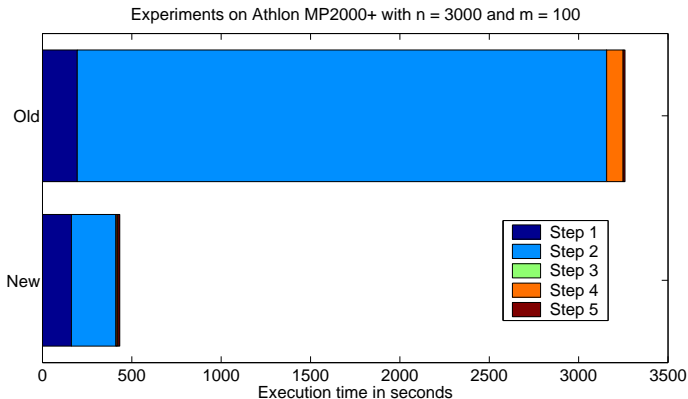
ADI [Wachspress'88], [Penzl'99], [Li/White'02], [Gugercin et al.'03], [Simoncini'06] a.m.o.; **API** [Hodel et al.'96].

Multigrid methods [Rosen/Wang'95], [Penzl'97],
[Grasedyck/Hackbusch'04].

apply A

Krylov subspace methods [Saad'90], [Hu/Reichel'92],
[Jaimoukha/Kasenny'94], [Hochbruck/Starke'95],
[Kressner/Marković'07].

Bartels/Stewart method



Step 1 $A \rightsquigarrow$ Hessenberg H (Old: LAPACK 3, New: [Quintana-Ortí/Van de Geijn'06])

Step 2 $H \rightsquigarrow$ Schur \tilde{A} (Old: LAPACK 3, New: [Braman/Byers/Mathias'02])

Step 4 Sol. of $\tilde{A}\tilde{A}X + \tilde{X}\tilde{A}^T = \tilde{B}\tilde{B}^T$ (Old: SLICOT, New: [Kressner'06])

Krylov subspace methods

Apply **Arnoldi method** to generate orthonormal basis U_k of

$$\text{span}\{b, Ab, A^2b, \dots, A^{k-1}b\}$$

$$u_1 = b/\|b\|_2$$

for $j = 1, \dots, k$ **do**

$$w = Au_j$$

$$h_{1:j,j} = [u_1, \dots, u_j]^T w$$

$$w = w - [u_1, \dots, u_j] h_{1:j,j}$$

$$h_{j+1,j} = \|w\|_2$$

$$u_{j+1} = w/h_{j+1,j}$$

end for

Setting

$$U_k = [u_1, \dots, u_k], \quad H_k = [h_{ij}]_{i,j=1}^k$$

yields **Arnoldi decomposition**

$$AU_k = U_k H_k + h_{k+1,k} u_{k+1} e_k^T.$$

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Arnoldi method applied to Lyapunov equation

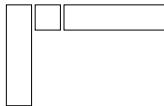
$$U_k^T \rightarrow AX + XA^T = -bb^T \leftarrow U_k$$

This is a *compressed* Lyapunov equation of size $k \times k$.

- ▶ Requires stability of H_k to have positive semi-definiteness of Y_k .
Sufficient condition: $\eta = -\lambda_{\max}(A + A^T)/2 > 0$.
- ▶ Hammarling's method requires $\mathcal{O}(k^3)$ flops and yields factorized solution $Y_k = L_k L_k^T$.

Set

$$X_k = U_k Y_k U_k^T =$$



Then (hopefully) $X_k \rightarrow X$ as $k \rightarrow \infty$.

Convergence can be cheaply monitored:

$$\|AX_k + X_k A^T + bb^T\|_2 = \|e_k^T Y_k\|_2 \|b\|_2^2.$$

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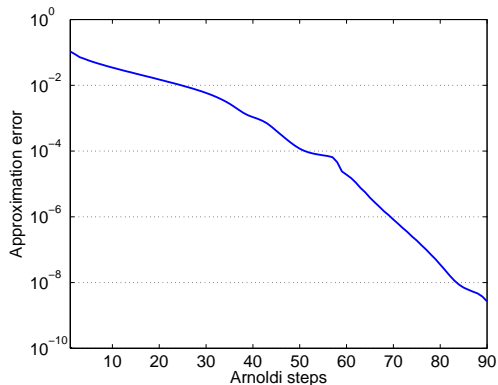
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Convergence of Arnoldi for Lyapunov

2D instationary heat equation on the unit square with homogeneous 1st kind boundary conditions; 30×30 finite difference discretization.



Linear convergence observed.

Convergence analysis – basic ideas

Solution of original (LYAP) can be written as (INT):

$$X = \int_0^{\infty} e^{At} b b^T e^{A^T t} dt.$$

Similarly for the compressed equation:

$$\begin{aligned} X_k = U_k Y_k U_k^T &= \|b\|_2^2 U_k \left(\int_0^{\infty} e^{H_k t} e_1 e_1^T e^{H_k^T t} dt \right) U_k^T \\ &= \int_0^{\infty} e^{A_k t} b b^T e^{A_k^T t} dt, \end{aligned}$$

where $A_k = U_k H_k U_k^T = U_k U_k^T A U_k U_k^T$.

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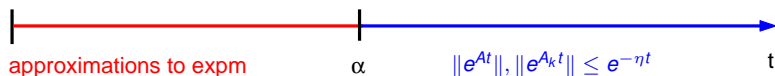
Enables the use of convergence results for expm:

$$\begin{aligned}\|X - X_k\| &\leq \int_0^\infty \left\| e^{At} b b^T e^{A^T t} - e^{A_k t} b b^T e^{A_k^T t} \right\| dt \\ &\leq 2 \int_0^\infty \left\| (e^{At} - e^{A_k t}) b b^T (e^{A^T t} + e^{A_k^T t}) \right\| dt\end{aligned}$$

Bounds for **red term**:

Error bounds for Krylov subspace

Trivial bound



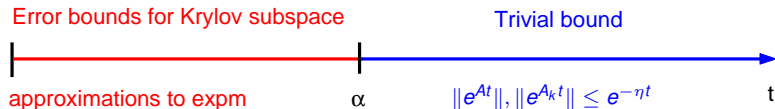
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Bounds for **red term**:



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Most general result

[Gallopoulos/Saad'92]: Bounds for expm from Taylor approx. of exp:

$$\| (e^{At} - e^{A_k t}) b \| \leq 2 \| b \| \frac{\| At \|^k}{k!}$$

Optimal cut point $\alpha = O(k) \rightsquigarrow$ **Loss of superlinear convergence!**

Resulting approximation result for Lyapunov equation:

$$\| X - X_k \| \leq \frac{2 \| b \|^2}{\eta} \gamma^k$$

with the convergence rate

$$\gamma = \exp W \left(-\frac{2\eta}{e \| A \|} \right) \approx \exp \left(-\frac{2\eta}{e \| A \|} \right);$$

W is **Lambert-W function** (= inverse function of $f(W) = We^W$)
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$\gamma \approx 0.998$ for numerical example!

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Symmetric case

[Hochbruck/Lubich'97] provides improved bounds on Krylov subspace approx. to expm; especially for **symmetric** A :

$$\|e^{At}b - e^{A_k t}b\| \leq \begin{cases} 10e^{-\eta t} e^{-\rho t} \frac{e^k \rho^{k-1} t^{k-1}}{k^k}, & t \in [0, k/(2\rho)], \\ 10e^{-\eta t} e^{-k^2/(5\rho t)}, & t \in [k/(2\rho), k^2/(4\rho)], \end{cases}$$

where $\rho = (\lambda_{\max}(A) - \lambda_{\min}(A))/4$.

Application to (LYAP) with nearly optimal cut point $\alpha = k/\sqrt{10\rho\eta}$ yields

$$\|X - X_k\| \leq \frac{80\|b\|^2}{\rho k} \left(\frac{\sqrt{e}}{2}\right)^k + \frac{\|b\|^2}{\eta} (20e^{-k\eta/\rho} + 1)\gamma^k$$

for all $k \geq 4\sqrt{\rho/(10\eta)}$, where $\gamma = e^{-\sqrt{2\eta/(5\rho)}}$.

$\gamma \approx 0.938$ (instead of $\gamma \approx 0.998$) for numerical example.

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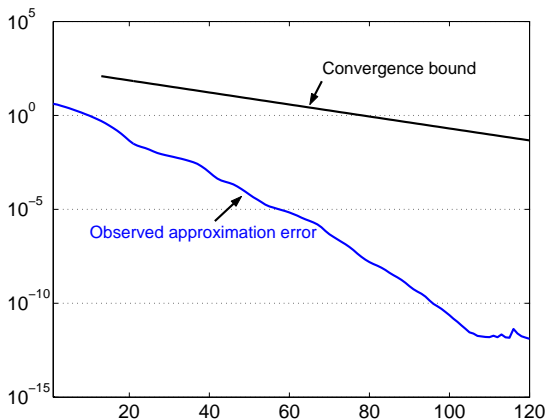
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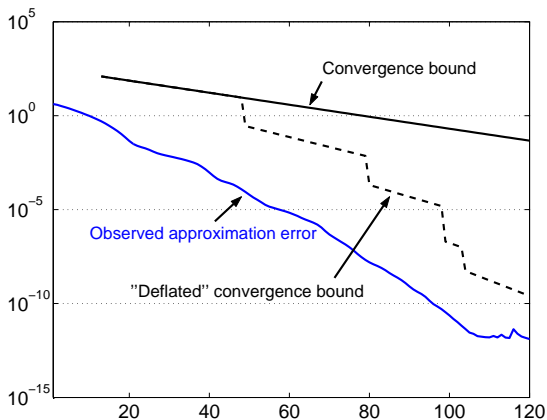
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Numerical example, ctd.



The bound can be considerably improved by neglecting converged eigenvalues of A during the Arnoldi process.

Numerical example, ctd.



Open: Genuine a priori bounds matching the convergence behavior better.

Outlook: Direct bounds

Symmetric case: Krylov subspace approximation to X can be related to

$$\begin{aligned} & \min_{X_k \in \mathbb{R}^{k \times k}} \|AU_k X_k U_k + U_k X_k U_k A + bb^T\|_2 \\ &= \min_{\rho_1, \dots, \rho_k \in \mathcal{P}_{k-1}} \max_{\lambda, \mu \in \Lambda(A)} \left| (\lambda + \mu) \sum_{l=1}^k \rho_l(\lambda) \rho_l(\mu) + 1 \right| |b_\lambda b_\mu|, \end{aligned}$$

where \mathcal{P}_{k-1} space of all polynomials of degree at most $k - 1$.

Replacing $\Lambda(A)$ by $[\lambda_{\min}(A), \lambda_{\max}(A)]$ leads to approx. problem:

$$\min_{\rho_1, \dots, \rho_k \in \mathcal{P}_{k-1}} \max_{x, y \in [\lambda_{\min}(A), \lambda_{\max}(A)]} \left| \frac{1}{x + y} + \sum_{l=1}^k \rho_l(x) \rho_l(y) \right|.$$

Outlook: Direct bounds

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Outlook: Preconditioning

$$AX + XA^T = -BB^T \quad \rightsquigarrow \quad XA^{-T} + A^{-1}X = -(A^{-1}B)(A^{-1}B)^T$$

Weighted sum of both equations:

$$(A + \alpha A^{-1})X + X(A + \alpha A^{-1})^T = -[B, A^{-1}B][B, A^{-1}B]^T$$

A symmetric and optimal choice of α :

$$\kappa(A + \alpha A^{-1}) \leq \sqrt{\kappa(A)}.$$

- ▶ Krylov subspace method based on A and A^{-1} [Simoncini'06] converges much faster.
- ▶ Effect of inexactness $P \approx A^{-1}$ not clear yet.

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$$AX + XA^T = -BB^T \quad \rightsquigarrow \quad XA^{-T} + A^{-1}X = -(A^{-1}B)(A^{-1}B)^T$$

Weighted sum of both equations:

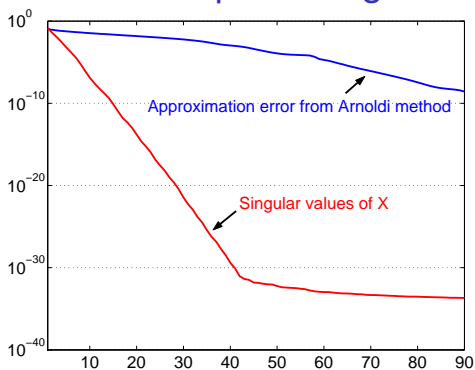
$$(A + \alpha A^{-1})X + X(A + \alpha A^{-1})^T = -[B, A^{-1}B][B, A^{-1}B]^T$$

A symmetric and optimal choice of α :

$$\kappa(A + \alpha A^{-1}) \leq \sqrt{\kappa(A)}.$$

- ▶ Krylov subspace method based on A and A^{-1} [Simoncini'06] converges much faster.
- ▶ Effect of inexactness $P \approx A^{-1}$ not clear yet.

Convergence does not capture singular value decay



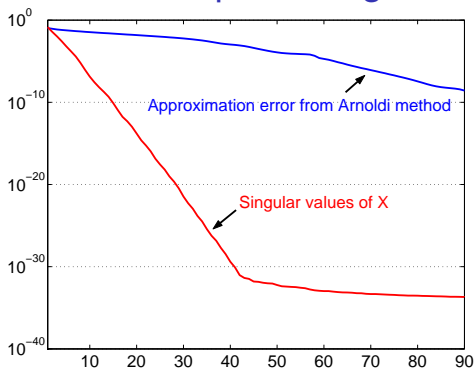
Example:

- ▶ $\text{svd}(X)$ tells there is a rank **12** approximation with error 10^{-8} ;
- ▶ Arnoldi yields only a rank **84** approximation with error 10^{-8} .

Achieve less storage requirements (allow more mv-products):

- ▶ perform restarts (open problem);
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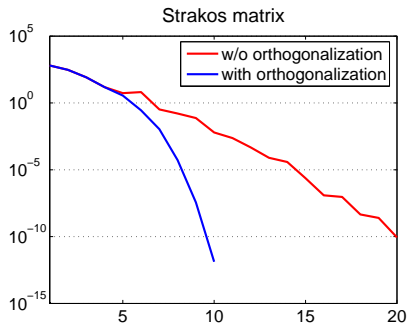
Lanczos method for symmetric matrix

If A is symmetric, then

Arnoldi process can be implemented using $O(n)$ memory.

But:

- ▶ no reorthogonalization possible;
- ▶ we need U_k to construct X_k .



Paige's classical results can be extended to show:

- ▶ loss of orthogonality only has mild effect on convergence *bounds*;
- ▶ residual norm can still be estimated using $\|e_k^T Y_k\|_2$.

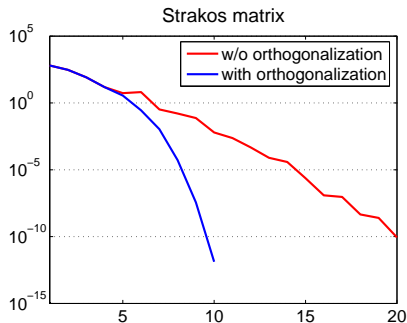
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Two-pass Lanczos method

Assume A is symmetric.

1st p. Apply Lanczos method **without** reorthogonalization!

Solve projected Lyapunov equation $H_k Y_k + Y_k H_k = -\beta^2 e_1 e_1^T$
and compute low rank approximation $Y_k \approx L_k L_k^T$ with $L_k \in \mathbb{R}^{k \times l}$.

Often, $l \ll k$!

2nd p. Repeat identical copy of Lanczos method to compute $V = U_k L_k$.
Yields approximate solution $X \approx VV^T$.

Reduces memory requirements from $n \times k$ to $n \times l$.

Doubles #mv-products.

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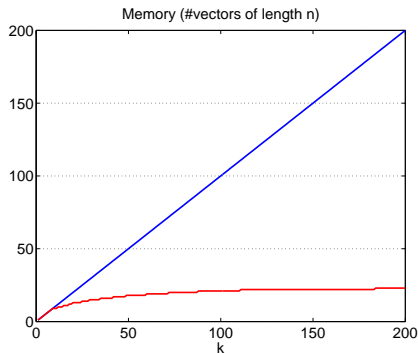
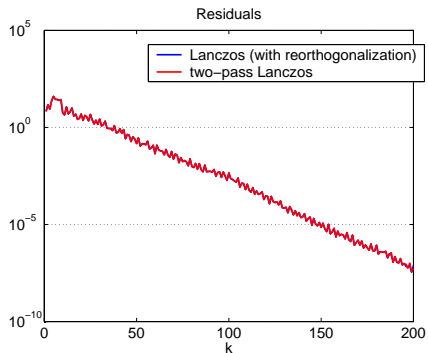
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Spiral Inductor PEEC Model [Li/Kamon'05]

A is 1434×1434 symmetric negative definite matrix and $m = 1$.



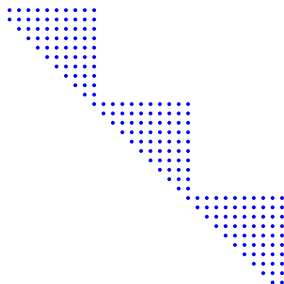
Two-pass “restarted” Arnoldi

[Eiermann/Ernst'06]: “Restarted” Arnoldi for computing $e^{At}b$ (and other matrix functions).

Rough idea: Restart Arnoldi method every k iterations with last column of Krylov subspace basis \rightsquigarrow Krylov decomposition

$$A[U_k^{(1)}, \dots, U_k^{(p)}] = [U_k^{(1)}, \dots, U_k^{(p)}]H_{pk} + u_{k+1}^{(p)}h_{pk+1,pk}e_{pk}^T,$$

where H_{pk} has structure



Two-pass restarted Arnoldi

Advantages:

- ▶ solution of projected Lyapunov equation requires $\mathcal{O}(pk^3)$ instead of $\mathcal{O}(p^3k^3)$ flops;
- ▶ only k basis vectors need to be stored when using a two-pass approach.

Disadvantages:

- ▶ more likely to break down if $\lambda_{\max}(A + A^T) \geq 0$;
- ▶ at least doubles #mv-products (significantly more are needed for small k).

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LYAPACK benchmark example [Penzl'99]

A is finite difference discretization ($n = 10000$)

$$\Delta u(x, y) - 10x \frac{\partial u(x, y)}{\partial x} - 20y \frac{\partial u(x, y)}{\partial y} \quad \text{on } \Omega = [0, 1] \times [0, 1].$$

Number of Arnoldi iterations to attain a residual of norm $\leq 10^{-5}$.

k	kp
∞	300
100	400
50	450
20	540
10	> 1000

Two-pass approach reduces memory requirements from $300n$ to $\approx 50n$ (however, #mv-products is tripled).

Conclusions

Novel results on Krylov subspace methods for Lyapunov equations:

- ▶ convergence bounds;
- ▶ efficient solution of compressed equation (Gohberg-Koltracht);
- ▶ analysis of loss of orthogonality in symmetric Lanczos.

(Joint work with Darija Marković and Ninoslav Truhar, both U Osijek, Croatia.)

Still to do:

- ▶ analysis of preconditioning:

$$(A + \alpha P)X + X(A + \alpha P)^T = BB^T + \alpha PBB^T P^T,$$

where $P \approx A^{-1}$;

- ▶ analysis of nonsymmetric restarted Arnoldi;
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Thanks for your attention!

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