

An inf-sup stable local grid refinement

Numerical Improvements of the TERRA-code

Markus Müller

Outline

- 1 Motivation
- 2 Preliminary results
- 3 Generalization possibilities

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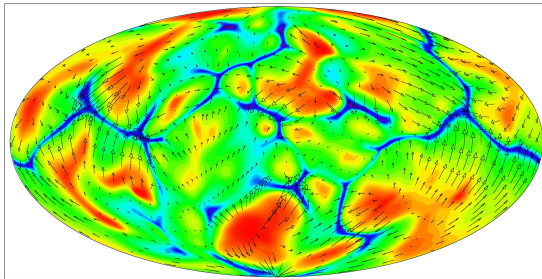
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Model



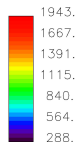
Run 808 Y419u Tcmb,st=3

Tcmb Var. B eta3 ys=1.15e

Depth = 1.348e+02 km

Time = 4.490e+09 a Age = -3.302e-01 Ma

Max vel = 1.837e+00 cm/a Av hor vel = 5.594e-01 cm/a

Temperature
(K)

Equations

conservation of

- energy
- mass
- momentum

because of the low velocities of the flow this boils down to the following procedure

- solve the temperature ode to get $T(t)$
- solve a **Stokes problem** for pressure and velocity in every time step

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Stokes as an abstract variational problem

The Stokes system in variational form: Given $l \in V'$ and $g \in Q'$, find a pair $(u, p) \in V \times Q$, such that

$$\begin{aligned} a(v, u) + b(v, p) &= \langle l, v \rangle & \forall v \in V \\ b(u, q) &= \langle g, q \rangle = 0 & \forall q \in Q. \end{aligned} \quad (1)$$

Continuous inf-sup condition

Theorem

Assume that the bilinear form $a(.,.)$ is V elliptic, i.e. there exists a constant $\alpha > 0$ such that

$$a(v, v) \geq \alpha \|v\|_V^2 \quad \forall v \in V$$

Then Problem 1 is well-posed **if and only if** the bilinear form $b(.,.)$ satisfies the following inf-sup condition.

There exists a constant $\beta > 0$ such that

$$\inf_{q \in Q} \sup_{v \in V} \frac{b(v, q)}{\|v\|_V \|q\|_Q} \geq \beta;$$

This condition is fulfilled for the (continuous) Stokes Problem but implicates a similar condition for the numerical algorithm.

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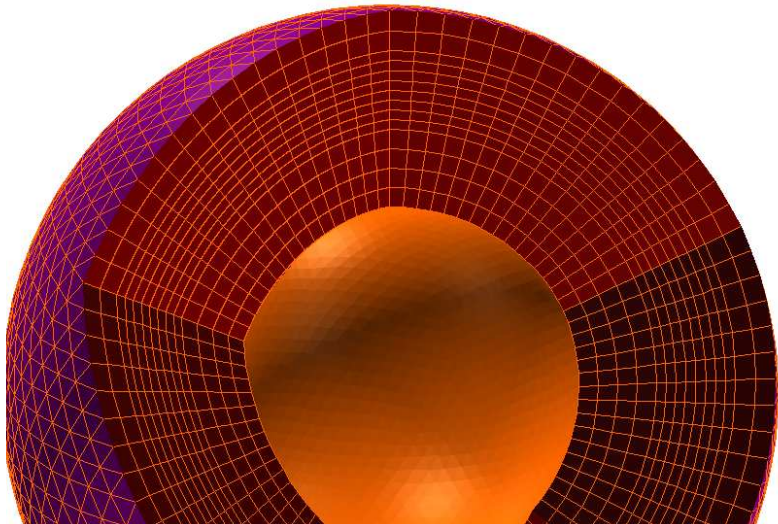
Discrete inf- sup condition

Theorem

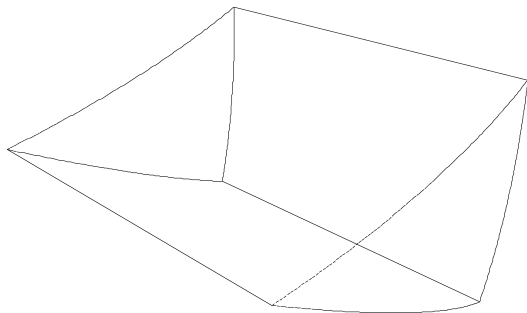
$$\inf_{q_h \in Q_h} \sup_{v_h \in V_h} \frac{b(v_h, q_h)}{\|v_h\|_{V_h} \|q_h\|_{Q_h}} \geq \beta_h;$$

- This condition ensures that we can **calculate** our solution.
- it depends on the approximation spaces for pressure and velocity - that is on the grid and the elements used for the approximation.

Original grid



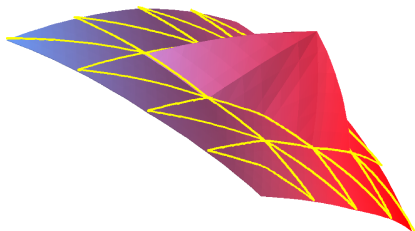
A grid cell



The basis functions for velocity and pressure are piecewise bilinear on such a grid-cell.

A continuous equal interpolation is used.

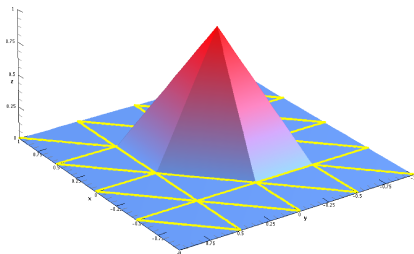
A lateral basis function



lateral basis defined on the sphere

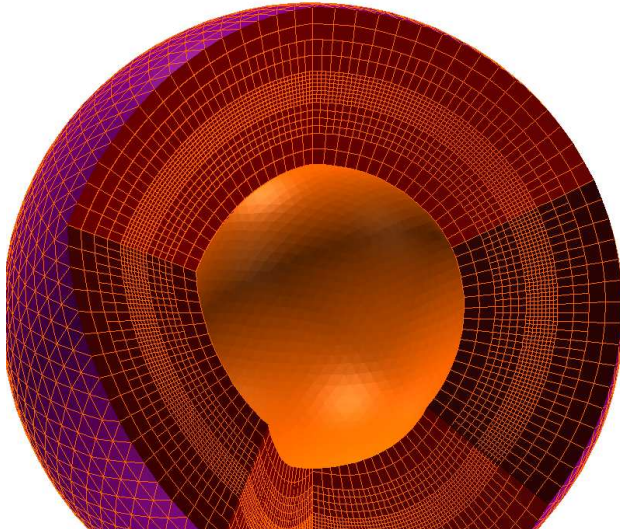
Note:

The spherical barycentric coordinates are recursively defined by the grid refinement process. There is no explicit formulation e.g. as function of ϕ and θ

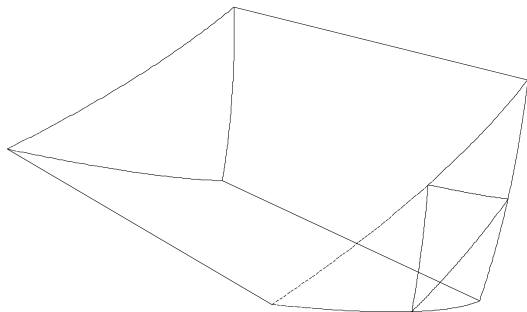


lateral basis function as function of the spherical barycentric coordinates

Proposed locally refined grid



A grid cell with hanging nodes



Note:

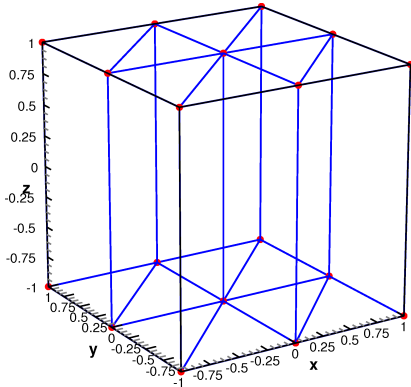
The continuity requirement enforces the values at hanging nodes to be interpolated, this way erasing degrees of freedom probably needed to ensure the inf-sup condition.

Preliminary conclusions

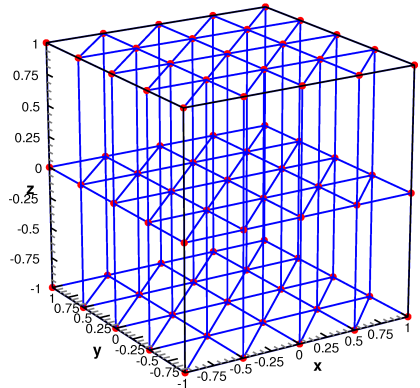
- The refined mesh is surely not inf-sup (not even the unrefined grid)
- The code is highly developed and sophisticated. A change to a totally different grid would not be possible in reasonable time and is therefore not desirable.
- The task is therefore to find a way to ensure the inf-sup condition with small changes to the code.

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Differently resolved grids for pressure and velocity



grid for pressure



grid for velocity

- Since the code implements a multi-grid, different grid levels already exist.

Checking the inf-sup condition

According to *Brezzi Fortin* this can be done constructing a family of uniformly continuous operators Π_h from V_h into V_h satisfying

$$\begin{cases} b(\Pi_h v - v, q_h) = 0, \forall q_h \in Q_h, \\ \|\Pi_h v\|_V \leq c \|v\|_V \end{cases} \quad (2)$$

as long as the continuous inf-sup condition holds which was proved for the stokes problem long ago.

Checking the inf-sup condition

The operator Π_h is constructed in two steps.

Theorem

Let $\Pi_1 \in \mathcal{L}(V, V_h)$ and $\Pi_2 \in \mathcal{L}(V, V_h)$ be such that

$$\begin{cases} \|\Pi_1 v\|_V \leq c_1 \|v\|_V, \\ b(\Pi_2 v - v, q_h) = 0 \quad \forall q_h \in Q_h, \\ \|\Pi_2(I - \Pi_1)v\|_V \leq c_2 \|v\|_V, \end{cases} \quad (3)$$

then Eq.(2) holds, and the inf-sup condition follows.

An approximation operator Π_1 can be constructed for many types of finite elements, the interesting part is to find Π_2 . This is done by a macro-element technique.

macro elements

By a macro-element we mean the union of a fixed number of adjacent elements along a well defined pattern.

Given a partition into macro-elements we can define the following spaces

$$V_{0,M} = \{v_h | v_h \in V_h, v_h = 0 \text{ in } \Omega \setminus M\}$$

The macro element technique

Theorem

(Brezzi Fortin) Suppose V_h is defined on a mesh of macro-elements and can be written as

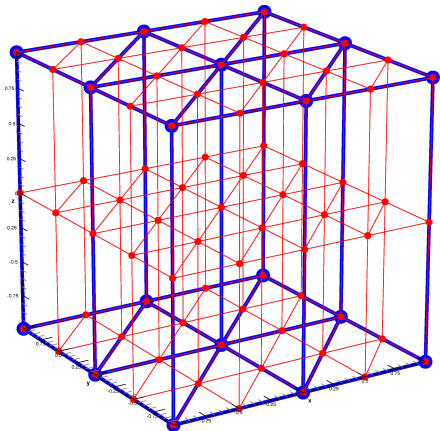
$$V_h = \tilde{V}_h \oplus (\oplus_M V_{0,M})$$

and the matrix associated with

$$\int_M v_h \phi_h dx, \quad \forall v_h \in V_{0,M}, \quad \forall \phi_h \in \Phi_M \supset \text{grad} Q_H|_M$$

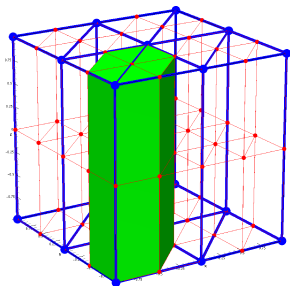
has full rank. Then a suitable Π_2 can be constructed.

My macro



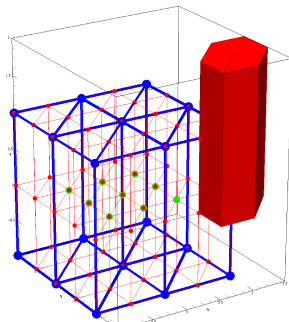
- 3x3x2 d.o.f. for pressure
- 5x5x3x3 d.o.f for velocity

$V_{0,M}$



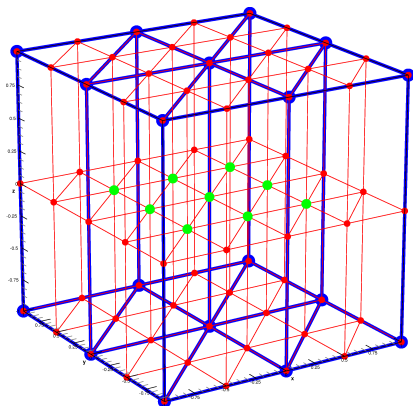
Allowed

$V_{0,M}$ contains only functions
with support inside M



Forbidden

The support (red) of this basis
function is not contained in the
macro



Only the basis functions with maximum on the nine green points belong to $V_{0,M}$

The matrix

$$\begin{pmatrix} \int_M \nabla P_1 \vec{v}_{1x} dx & \int_M \nabla P_1 \vec{v}_{1y} dx & \dots & \int_M \nabla P_1 \vec{v}_{9z} dx \\ \int_M \nabla P_2 \vec{v}_{1x} dx & & & \vdots \\ \vdots & & & \\ \int_M \nabla P_{18} \vec{v}_{1x} dx & & \dots & \int_M \nabla P_{18} \vec{v}_{9z} dx \end{pmatrix}$$

- Since \vec{v} is a 3D vector the nine grid points imply 27 basis functions for V_0 hence 27 columns
- As span for the gradient space of P I used the gradients of the 18 basis functions, which is not a basis because $\dim(\text{grad}P_h|_M) = \dim(P_h|_M) - 1 = 17$. In fact we could drop an arbitrary ∇P_i because it can be constructed as a linear combination of the remaining 17.
- Therefore - if everything is well - we expect the matrix to have rank 17.

interim result

- Up to now available:
inf-sup condition proofed only for a reference element
- Wanted:
proof for the mapped elements of our convection code.

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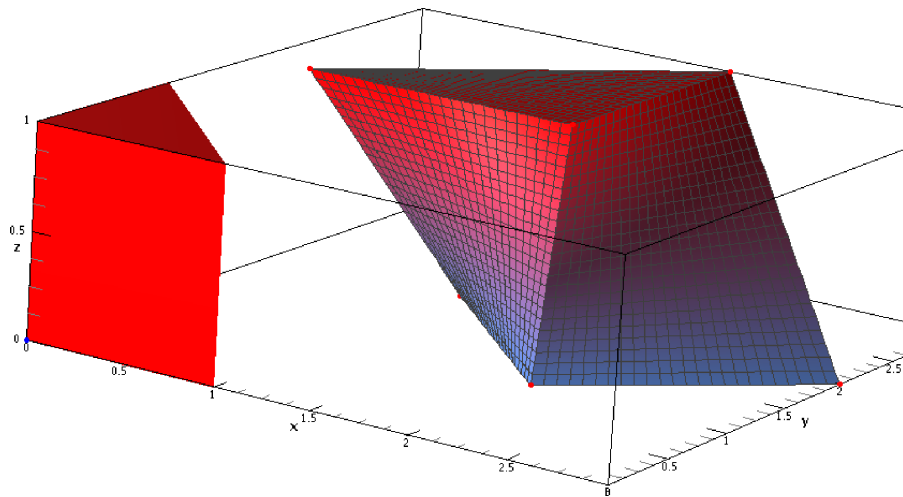
Question 1 (general approach)

- **Which properties** of a mapping ensure conservation of the linear independence of the matrix rows?
TERRA can offer e.g.
 - a bijective mapping
 - bounded aspect ratios

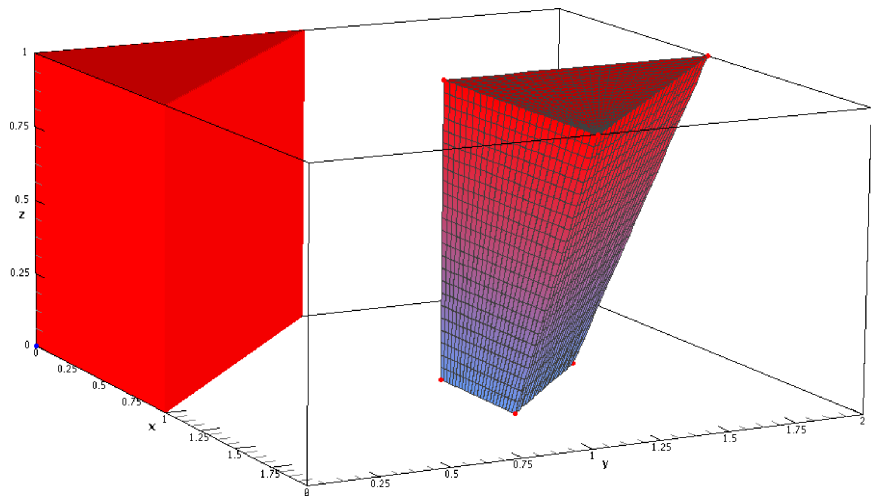
Question 2 (approximation approach)

- Possibility to check the rank of the matrix also for mapped elements for **explicitly** given mappings.
- Approximation properties of iso-parametric elements suggest a bilinear mapping for bilinear form functions.

Bilinear mapping



Bilinear mapping with plane surfaces



The Difficulty of piecewise defined mappings

let F be the mapping that maps the reference element to a real element.

$PRV(v)$ the set of all prisms that are inside the support of v
 then

$$\begin{aligned} \int_M \nabla p_i \vec{v}_j dx &= \int_M \nabla p_{0_i} \vec{v}_{0_j} \det(F) dx \\ &= \sum_{k=1}^{\text{card}(PRV)} \int_{v_{pr_k}} \nabla p_{0_i} |_{v_{pr_k}} \vec{v}_{0_j} |_{v_{pr_k}} \det(F) |_{v_{pr_k}} dx \end{aligned}$$

Note:

Even a mapping piecewisely affine on the prisms inside the macro does not multiply hole lines of the matrix with the same number.